

Nonlinear ultrasonic inspection of the effect of contaminants on material properties of epoxy-adhesive

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3 epoxy-adhesive

4

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8

9 **Key words:** epoxies, adhesive joints, contaminants, second harmonic generation, nonlinearity
10 parameter

11

12 **Abstract**

13 Adhesive joints have been an effective alternative to conventional mechanical fasteners for
14 joining materials in the aerospace and automotive industries. Although adhesive joints have
15 various advantages, including uniform stress distribution, lower weight, improved corrosion
16 tolerance, and design flexibility, there can be various defects in adhesive joints, which have
17 limited wider application. This paper investigates the effect of a contaminant on the chemical
18 and mechanical properties of the epoxy-adhesive and seeks to determine if a SHG method can
19 reliably detect and characterize the degree of contamination in the epoxy-adhesive. A contract
20 based ultrasonic through-transmission method was used to measure nonlinearity and then the
21 nonlinearity parameter was calculated using the measured fundamental and second harmonic
22 frequency components in the signals. It was found that there is higher sensitivity to contaminant
23 concentration, up to 1.5%, of the nonlinearity parameter than that for the sound velocity. These
24 data were also found to correlate with changes in the mechanical hardness, which was measured
25 by the Rockwell hardness testing, with different four levels of contamination. Differential
26 scanning calorimetry (DSC) and the thermogravimetric analysis (TGA) were also conducted
27 to assess the effect of the contaminant on thermal properties of the epoxy-adhesive. The DSC
28 and TGA techniques were used to evaluate the curing reaction and the thermal stability of the
29 epoxy-adhesive respectively.

30

31 **Key words:** epoxies, adhesive joints, contaminants, second harmonic generation, nonlinearity
32 parameter

33

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35 **1. Introduction**

36 Adhesive joints are an effective and potentially attractive alternative to conventional
37 mechanical fasteners used to join similar or dissimilar materials in the aerospace industry.
38 Adhesive joints have various advantages over fasteners, including uniform stress distribution,
39 lower structure weight, improved corrosion tolerance, and design flexibility. In addition, the
40 reduction in numbers of fasteners enables some forms of smart structures, such as embedded
41 sensor systems [1]. The potential for reduced weight in aircraft, through the use of adhesive
42 joints, also gives potential for higher fuel efficiency with reduced [2]. However, defects in
43 adhesive joints can reduce strength, and the inability to reliably quantify strength has prevented
44 such joints from use in a wider range of applications that would enable use of fewer fasteners.

45 Adhesive joints can exhibit various defects, including at the interfaces between adhesive and
46 substrates and in bulk adhesive, that are due to poor fabrication processes and presence of
47 foreign material introduced in manufacturing, and in-service damage [3]. To enable increased
48 use of adhesive joints, it is necessary to detect these defects, reliably quantify strength and
49 ensure uniform joint quality.

50 In looking in detail at the local structure found in adhesive joints there can be micro-scale
51 defects at the micrometer (μm) scale, and these are in the form of voids and cracks, which are
52 also stress concentrators and these are early-stage defects, with potential for growth in these
53 joints. The detection and evaluation of such micro-scale defects, before they develop into
54 macro-scale defects, can enable corrective actions to be taken that potentially enable an
55 increase in structural lifetime and, and in the process, give a reduction in inspection cost. For
56 example, since macro-scale defects in a system in fatigue can develop with about 20% of
57 structural life remaining before fracture. The reliable detection of such micro-scale defects can
58 reduce the potential for catastrophic failure in structures [4].

59 Although there have been advances in ultrasonic evaluation techniques used to detect micro-
60 scale defects in adhesive joints, these have in general focused on detecting interfacial defects
61 and delamination induced in-service [5-8], which are also known as dry contact kissing bonds
62 [9]. Various studies have investigated such defects, and it appears that this is in part because
63 such damage is relatively simpler to simulate in experimental samples [10,11]. Kissing bonds
64 remain as one form of critical joint defects defined as surfaces are in intimate mechanical
65 contact between adhesive and substrates, but there is little or no bond strength [12].

66 Micro-scale defects can come in several forms, in addition to kissing bonds, through the
67 introduction of various contaminations during the manufacturing process. Contaminants can,
68 in general, cause two types of micro-scale defects in the adhesive joints as shown in Fig. 1.
69 Firstly, these can be in the form of interfacial defects, also known as contaminant or liquid layer
70 kissing bonds [9], where the contaminants remain at the interface between the substrates and
71 adhesive [9,13,14]. Secondly, if contaminants are mixed into bulk epoxy-adhesive, they will
72 generally change properties and cause poor cohesion, which is seen as a degradation of the
73 strength of the adhesive materials itself [15,16]. Prior studies have focused on detection and
74 characterization of the kissing bonds based on several contaminants, including silicone-based
75 release agents [17], oils [18], sand [14], and polytetrafluoroethylene (PTFE) [19] and ethylene
76 tetrafluoroethylene (ETFE) films [20]. In seeking to detect these contaminants and quantify

77 performance of such defective bonds various NDE techniques have been investigated. These
78 techniques include infrared thermography [19], digital image correlation (DIC) [20], micro-
79 wave imaging [21], vibro-acoustic modulation [22], and ultrasonic resonance spectroscopy
80 [14]. In reviewing the various approaches, each gave images and showed some possibility for
81 the detection and mapping of kissing bonds, but they all still have their own limitations in the
82 measurements and alternate approaches remain of interest.

83 Nonlinear ultrasonic techniques are one family of methods that have been demonstrated to have
84 some potential for effective detection and characterization of some micro-scale defects [23].
85 Such nonlinear ultrasonic techniques are based on wave modulation generated when incident
86 ultrasonic waves interact with the micro-structurally changed materials, such as micro-scale
87 defects, which induce various nonlinear interaction phenomena [24-29]. Second harmonic
88 generation (SHG) is one of the typical nonlinear phenomena that occurs when a finite
89 amplitude ultrasonic wave is propagating through materials, and there is energy transfer from
90 the fundamental into the higher harmonic components, as a result of the wave distortion due to
91 energy interacting with the micro-structural changes encountered in the materials [30-32].

92 In quantifying such interactions the nonlinearity parameter (β) is used, which is a ratio of the
93 amplitude of the fundamental and second harmonic components, and this has been shown to
94 be directly related to micro-structural changes in materials [33,34]. The SHG method has been
95 used as a metric to evaluate various micro-scale defects and damage in materials. Cantrell and
96 Yost [35] used the nonlinearity parameter to characterize fatigue damage in aluminum alloy
97 2024-T4 and they showed that an increase in the nonlinearity parameter is related to the growth
98 of dislocation dipoles during fatigue cycles. Ruiz et al. [36] applied nonlinear Rayleigh wave
99 to evaluate early thermal damage in 2205 duplex stainless steel. In this case the nonlinearity
100 parameter is shown to be related to the precipitation of a sigma phase during thermal aging. In
101 addition, Balasubramaniam et al. [37] used both second and third harmonic components to
102 measure creep damage in copper. They employed low amplitude longitudinal ultrasonic waves
103 and demonstrated that the nonlinear response is sensitive to creep-generated dislocations. For
104 interfacial micro-scale defects, Barnard et al. [38] produces samples that simulated a partially
105 closed interface in a copper-copper diffusion bond. It was shown that differences in interfacial
106 strength can effectively be related to interface condition and evaluated using second harmonic
107 generation.

108 The specific problem of kissing bonds at interfaces was considered by Brotherhood et al. [39]
109 who investigated simulated dry contact kissing bonds in adhesively bonded joints. A linear
110 ultrasonic and a high-power based nonlinear ultrasonic method, measuring the second
111 harmonic component, were both used as a function of the contact pressure applied to the joint.
112 The results showed that each method has their own sensitivity to certain states of the interface.
113 The linear method is sensitive to defects when a higher contact pressure is applied. On the other
114 hand, the nonlinear method is shown to be effective in detecting defects when a low contact
115 pressure is applied to the kissing bonds. The use of a combination of linear and nonlinear
116 methods appears to have potential to enhance the effectiveness of defect detection.

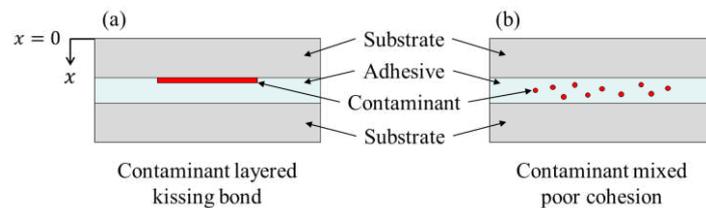
117 The various SHG measurements, which have demonstrated potential in various applications,
118 have not yet been applied for the detection of poor cohesion induced by contaminants in the
119 epoxy-adhesive, even though contaminant-based poor cohesion is one of the potential critical

120 defects identified in adhesive joints during manufacturing [16]. When contaminants are mixed
121 into the epoxy-adhesive during the manufacturing processes, they will alter the chemical
122 aspects of the epoxy structure, typically reducing the curing reaction, which deteriorates the
123 mechanical properties of the epoxy, which will then cause a reduction in bond quality and
124 strength and increase the risk of cohesive failure in adhesive joints.

125 This paper investigates the effect of a contaminant on the chemical and mechanical properties
126 of the epoxy-adhesive and seeks to determine if a SHG method can reliably detect and
127 characterize the degree of contamination in the epoxy-adhesive, expanding on preliminary data
128 presented previously [40]. In manufacturing, release agents which are required to produce
129 many adhesively jointed structures, are one possible source of critical contaminants in
130 adhesively jointed structures. This material was used at low concentration in thick epoxy-
131 adhesive samples. A contact based ultrasonic through-transmission method was used to
132 measure nonlinearity and then the nonlinearity parameter was calculated using the measured
133 fundamental and second harmonic frequency components in the signals.

134 In seeking to quantify the effectiveness of the SHG method, the variation in nonlinearity
135 parameter was compared with corresponding changes in the sound velocity as a linear
136 ultrasonic parameter used to detect the contaminant-based poor cohesion with varying
137 contamination levels. It was found that there is higher sensitivity to contaminant concentration
138 of the nonlinearity parameter than that for the sound velocity. These data were also found to
139 correlate with changes in the mechanical hardness, which was measured by the Rockwell
140 hardness testing, with different four levels of contamination. Differential scanning calorimetry
141 (DSC) and the thermogravimetric analysis (TGA) were also conducted to assess the effect of
142 the contaminant on thermal properties of the epoxy-adhesive. The DSC and TGA techniques
143 were used to evaluate the curing reaction and the thermal stability of the epoxy-adhesive
144 respectively [41,42]. A correlation between the nonlinearity parameter and the thermal, and
145 mechanical properties of the epoxy-adhesive was found.

146



147

148 **Fig. 1** Two types of contaminant-based micro-scale defects in general adhesive joints: (a)
149 contaminant layered kissing bond and (b) contaminant mixed poor cohesion

150

151 2. Second harmonic generation

152 When a monochromatic ultrasonic wave with a finite amplitude is incident on micro-
153 structurally changed materials, due to defects or damage, higher harmonic components are
154 generated from the wave-material interaction that gives wave distortion [23]. It has been found
155 that the second-order harmonic component has a larger amplitude than other higher harmonic

156 components and such interactions are dependent on the level change of material nonlinearity
 157 due to the micro-scale defects. As such this offers the potential that the SHG method is effective
 158 for certain classes of micro-scale defects [40].

159 The micro-scale defects that induce the nonlinear behavior in the ultrasound-material
 160 interactions can be described with the stress and strain relationship as given as equation 1. This
 161 relationship is limited to the second-order term as only the second harmonic component is
 162 employed in this analysis.

$$\sigma = E\varepsilon(1 + \beta\varepsilon) \quad (1)$$

163

164 where σ is the stress, E is the Young's modulus, ε is the strain, and β the nonlinearity
 165 parameter.

166 A one-dimensional monochromatic longitudinal wave propagating in the x-direction of
 167 materials (as defined in Fig. 1) can be described with equation 2. When this ultrasonic wave is
 168 incident on the nonlinear material, the resulting nonlinear wave equation can be obtained by
 169 combining equations 1 and 2 to give equation 3.

$$\rho \frac{\partial^2 u(x, t)}{\partial t^2} = \frac{\partial \sigma(x, t)}{\partial x} \quad (2)$$

$$\rho \frac{\partial^2 u(x, t)}{\partial t^2} = E \frac{\partial^2 u(x, t)}{\partial x^2} + 2E\beta \frac{\partial u(x, t)}{\partial x} \frac{\partial^2 u(x, t)}{\partial x^2} \quad (3)$$

170

171 where $u(x, t)$ is the displacement and ρ is the density.

172 To solve the nonlinear wave equation first-order perturbation theory is used and this gives the
 173 nonlinearity parameter (β) shown as equation 4 [43].

$$\beta = \frac{8}{k^2 x} \frac{A_2}{A_1^2} \quad (4)$$

174

175 where k is the wave number, A_1 is the displacement amplitude of the fundamental
 176 component, and A_2 is the displacement amplitude of the second harmonic component. The
 177 nonlinearity parameter is directly proportional to the amplitude of the second harmonic
 178 component, which is generated from the interaction with micro-scale defects in materials.

179 In an experiment if the measured samples have the same thickness and a fixed excitation
 180 frequency and pulse is used, the nonlinearity parameter can be simplified to the relationship
 181 given as equation 5 (a). In the experiments the amplitudes of the received electrical signals can
 182 be measured and used directly to give a relative nonlinearity parameter (β'), shown in equation
 183 5 (b). In this case there is no requirement for additional calculation or corrections which are
 184 required a calibration process [44,45] to obtain the absolute displacement amplitude of each
 185 harmonic component in equation 5 (a).

186 The metric (β') can be used for the relative comparison of the level of the micro-structural
187 change in materials at different contamination levels, as used in this study. Additionally, the
188 use of the metric (β') can minimize the effects of the excitation amplitude and the coupling
189 condition on the second harmonic measurements, when compared with those encountered in
190 determining the absolute nonlinearity parameter (β) that is shown in equation 5 (a) [46].

$$\beta = \frac{A_2}{A_1^2} \quad (5 \text{ (a)})$$

$$\beta' = \frac{A_2'}{A_1'^2} \quad (5 \text{ (b)})$$

191

192 where A_1' and A_2' are the measured electrical signal amplitudes of the received fundamental
193 and second harmonic components respectively.

194

195 **3. Samples**

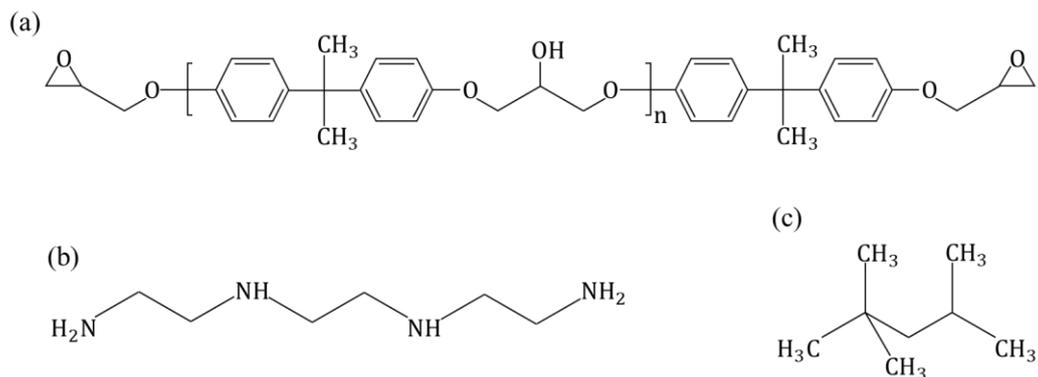
196 A series of epoxy samples were fabricated in the form of short cylinders, approximately 25.4
197 mm in diameter and 8 mm thick. In curing of epoxy mixtures, it is the general process of the
198 curing reaction, which determines the quality of the cured epoxy samples, and this is described
199 below. The sets of samples were prepared for each ultrasonic measurements, and mechanical
200 and thermal testing with varying levels of contamination.

201

202 **3.1 Materials**

203 The epoxy-adhesive used in this study was composed of the epoxy resin (EPO-FIX
204 EMBEDDING RESIN, USA), and the hardener (EPO-FIX HARDENER, USA). The epoxy
205 resin is based on bisphenol A diglycidyl ether (commonly abbreviated BADGE or DGEBA),
206 which is the combination of bisphenol A and epichlorohydrin, and the hardener is based on
207 triethylenetetramine (TETA) which is a primary aliphatic amine. The contaminant used was
208 the release agent (BUEHLER RELEASE AGENT, USA) which is based on isooctane. Their
209 chemical structures are shown in Fig. 2. The critical curing reaction for the synthesis of the
210 epoxy resin and the hardener involves opening the epoxide ring of the resin by the active
211 hydrogen in the amines of the hardener, which induces the polymerization in the mixture.
212 Repeated reactions between the epoxy resin and hardener eventually form a three-dimensional
213 epoxy structure which is the cross-linked network. Fig. 3 shows the general mechanism of the
214 ring-opening polymerization for the epoxy network formation during the curing reaction
215 between the epoxy resin and hardener [47].

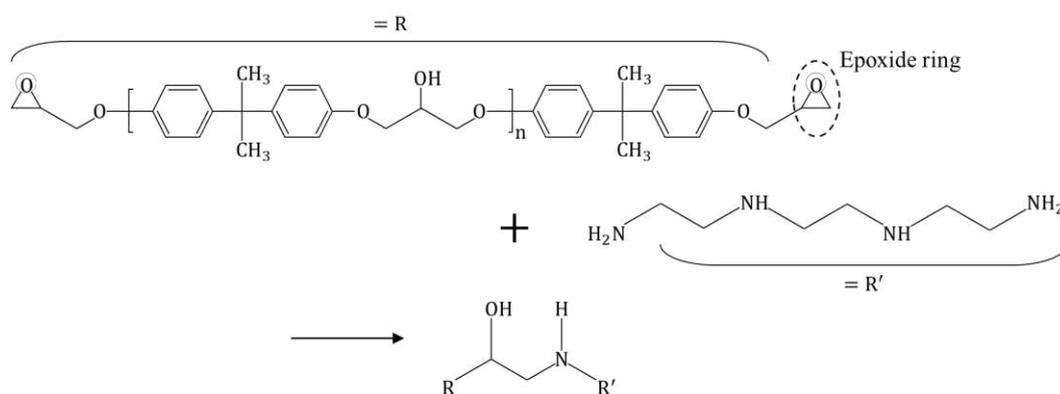
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217

218 **Fig. 2** Chemical structure of (a) the epoxy resin, (b) hardener, and (c) release agent

219



220

221 **Fig. 3** General curing mechanism between the epoxy resin and primary hardener

222

223 3.2 Sample preparation

224 The epoxy resin and hardener were consistently mixed in the ratio of 28:3 parts by weight
 225 following the product preparation instructions. After this mixing, the release agent, used as the
 226 contaminant, was added into the mixture at the level of 0.5, 1.0, and 1.5% of the total weight
 227 of the mixture and the compounds were then completely mixed again for each of four samples,
 228 including the pure (uncontaminated) sample. The mixtures were degassed in a vacuum chamber
 229 to remove air bubbles entrained into the mixtures and poured into molds coated with a release
 230 agent in advance, and into alumina crucibles, to be used in subsequent testing after curing. The
 231 mixture in the molds is for ultrasonic measurements and hardness testing, and the mixture in
 232 the alumina crucibles is for thermal analyses. After pouring, the mixtures were again degassed
 233 and cured under vacuum at room temperature. For ultrasonic and hardness measurements, the
 234 thickness of the cured samples was set to 8 mm (± 0.05 mm) with parallel surfaces and the
 235 surfaces of the samples were polished using a series of sandpapers (120, 320, 600, 1000, 2000,
 236 3000, and 5000 grits) to smooth initial surface roughness.

237

238

239 4. Experiments

240 In experiments, using ultrasound, the sound velocity (c) and the relative nonlinearity parameter
241 (β') obtained using the SHG method were measured, and data used to determine sensitivity to
242 the levels of contamination. Also, to check the effects of contamination on change of the
243 material properties of the epoxy samples, such as mechanical and thermal properties,
244 mechanical hardness, and curing reaction and thermal stability were evaluated through the
245 Rockwell hardness testing, and differential scanning calorimetry (DSC) and thermogravimetric
246 analysis (TGA). The experimental details are set out below.

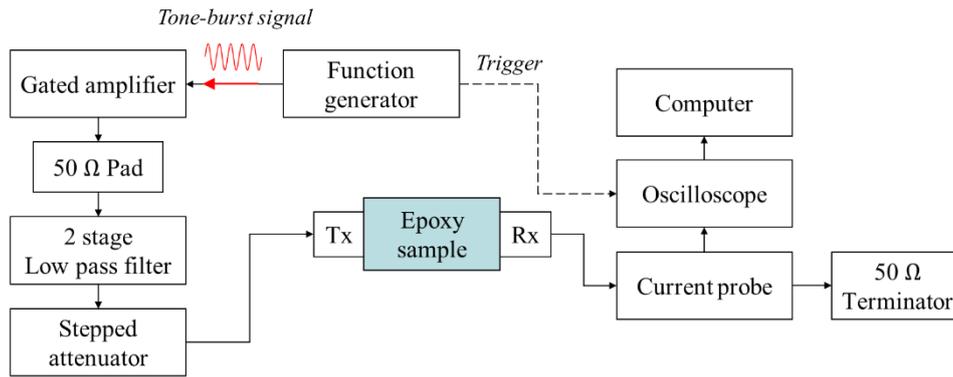
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248 4.1 Second harmonics generation

249 A through-transmission ultrasonic experimental [40, 45] setup shown in Fig. 4 was used to
250 measure the fundamental and second harmonic components for samples containing four
251 different levels of contamination. A 17 cycles tone-burst signal, 800 mV peak-to-peak, was
252 generated from the function generator (Agilent, USA) and then amplified through the high-
253 power amplifier (RITEC GA-2500, USA). Before reaching the transmitting transducer, the
254 signal passed through a 50 Ω terminator and the two stage low pass filters to give more
255 consistent and reliable signals by removing the transient signal and the nonlinear effects due to
256 the electronics in the experimental system. The stepped attenuator was also used to obtain
257 several sets of data by varying the current output signals by changing the power. Based on this
258 through-transmission method, a 5MHz commercial transducer (Olympus V110, USA) with
259 6.35 mm (0.25 inch) diameter, was used to transmit ultrasonic longitudinal waves, and a broad-
260 band 10 MHz commercial transducer (Olympus V112, USA), with the same dimension was
261 used as the receiver to increase sensitivity to the second harmonic frequency to detect both the
262 fundamental and the second harmonic frequency components. The spectra for the transducers
263 were measured. The center frequency of the transmitter is 5.68 MHz, with the -3 dB bandwidth
264 being from 4.35 to 6.98 MHz, and the receiver has the center frequency of 6.81 MHz with the
265 -3 dB bandwidth being from 4.29 to 9.91 MHz.

266 The fundamental frequency excited is set as 4.5 MHz, because this frequency can optimize the
267 measurement by providing stable waveforms for the tone-burst signals and provide large
268 amplitudes in the measured signals in the transmitter-receiver combination used in this study.
269 The received time domain signals for the ultrasonic waves that propagated through the samples
270 were recorded with a digital oscilloscope (LeCroy, USA) set at 1 GHz sampling rate and with
271 1000 averages to improve signal-to-noise ratio for the signal post-processing.

272



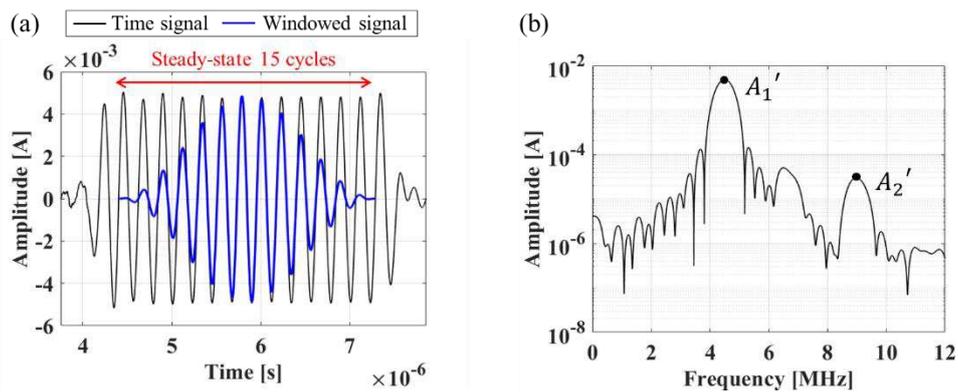
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274 **Fig. 4** Through-transmission experimental setup used for nonlinear measurements

275

276 An example of the received time domain signal is shown as Fig. 5 (a). A Hanning window
 277 function was applied to the steady-state 15 cycles of the received time domain signal to prevent
 278 spectral leakage, which reduces side-lobe effects [48]. When window functions are applied to
 279 signals, there can be power loss, so a scaling factor was used to compensate for the amplitude
 280 reduction due to the use of the Hanning window. The amplitudes of the fundamental and second
 281 harmonics were then obtained using a Fast Furrier Transform (FFT). An example of the
 282 measured amplitudes of the fundamental and second harmonic frequencies for the case of the
 283 pure sample in the frequency spectrum are given in Fig. 5 (b). By changing the power output
 284 using the stepped attenuator, this measurement process to obtain the fundamental and second
 285 harmonic components was repeated at several signal power outputs to determine the
 286 relationship between the amplitudes of the fundamental and second harmonic frequencies,
 287 which enables the nonlinearity parameter (β') to be obtained.

288



289

290 **Fig. 5** Example of (a) The received time domain signal with Hanning window function, and
 291 (b) frequency spectrum showing the fundamental and second harmonic components

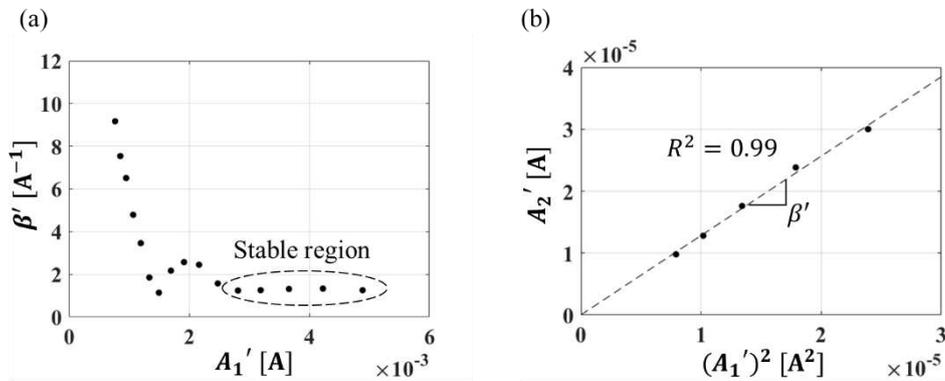
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293 Fig. 6 (a) shows the nonlinearity parameter (β') as a function of the fundamental amplitude
 294 (A_1'), obtained by changing the power output using the stepped attenuator. For the data shown

295 in Fig. 6 (a), at small amplitudes the β' value varies, because the second harmonic
 296 components are at or below the noise levels. The most reliable descriptor of properties is for
 297 the range of the fundamental amplitude which gives the stable region [45] and a consistent
 298 nonlinearity parameter. Using the stable region of the fundamental amplitude, a reproducible
 299 linear relationship between the square of the fundamental amplitude and second-harmonic
 300 amplitude was obtained as shown in Fig. 6 (b). The slope of this relationship gives a value for
 301 the nonlinearity parameter that is consistent with the relationship given as equation 5 (b).

302 This measurement process was repeated three times at each three points on each sample; giving
 303 a total of nine measurements for each sample. These data minimize the effect of any micro-
 304 bubbles randomly distributed in the samples and the effect of the surface contact conditions
 305 between the transducers and samples, and provide more accurate and reliable results.

306



307

308 **Fig 6** Nonlinearity metrics: (a) the relative nonlinearity parameter as a function of the
 309 fundamental amplitude, and (b) the relationship between the square of the fundamental
 310 amplitude and the second harmonic amplitude

311

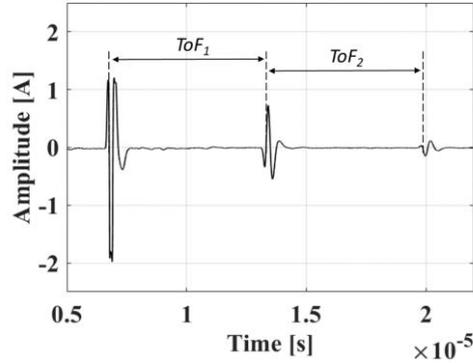
312 4.2 Sound velocity

313 Sound velocity in the samples was measured using a common pulse-echo method. To generate
 314 ultrasonic waves, the pulser/receiver (Olympus 5800, USA) was used, in combination with the
 315 5 MHz and 10 MHz commercial transducers that were employed in the SHG method
 316 measurements. For each transducer, the received time domain signal reflected from the
 317 opposite side (back-wall) of samples was recorded and an example of a typical signal is shown
 318 in Fig. 7. The transit times for the first and second time-of-flight (ToF) signals were measured
 319 based on the differences between the first zero-crossing points. The difference between the first
 320 and second ToF transit times were then averaged. The measurement was repeated three times
 321 at each of three points on each sample. In addition, the data obtained from each 5 MHz and 10
 322 MHz ultrasonic signal was also averaged to get a best estimate of the ToF transit time. The ToF
 323 transit time (t) and sample-thickness (d) data were then used to give the sound velocity (c)
 324 using equation 6.

325

$$c = \frac{2 \times d}{t} \text{ (m/s)} \quad (6)$$

326



327

328 **Fig. 7** Example of the pulse-echo signal for 5 MHz transducer: received time domain back-
 329 wall echo's showing 1st, 2nd, and 3rd reflections.

330

331 4.3 Mechanical hardness

332 To measure the mechanical hardness of softer non-metallic materials, such as epoxies,
 333 Rockwell hardness testing based on M type (HRM) is commonly used [49]. In this study, a
 334 Rockwell hardness tester (LECO LR-series, USA) which uses the setup for the M type ball
 335 type indenter, with a 100 kg load and a 6.35 mm (1/4 inch) ball, was employed. For each sample,
 336 the measurement was repeated 10 times on the surface of the sample and averaged.

337

338 4.4 Curing reaction and thermal stability

339 Thermal characteristics of the epoxy samples were analyzed using differential scanning
 340 calorimetry (DSC) and thermogravimetric analysis (TGA) performed with a Netzsch STA449
 341 F1 instrument (Netzsch, USA). In DSC, the curing reaction, which is one of critical curing
 342 kinetics phenomena, was measured for the epoxy samples cured in alumina crucibles. The
 343 measurements gave the glass transition temperature (T_g) in the heating temperature range from
 344 room temperature to 400 °C. The temperature, T_g , can give the glass transition point which is
 345 used to determine the curing kinetics of epoxies. This temperature was measured at the peak
 346 point of the first derivative of DSC results, which has a similar value to the midpoint of the
 347 glass transition. In addition, in TGA, the thermal stability was analyzed by measuring two
 348 parameters, the initial decomposition temperature (IDT) and the temperature of the maximum
 349 rate of degradation (T_{max}), based on the amount of the weight loss in the cured epoxy as a
 350 function of a temperature. In the measurements, the IDT was measured at the onset of weight
 351 decomposition and the T_{max} was measured at the 50% point for weight loss. The TGA
 352 measurements were performed in the heating temperature range from the room temperature to
 353 600 °C. For both DSC and TGA, the heating rate is 10 °C/min under a nitrogen atmosphere of
 354 20 mL/min.

355 5. Results and discussion

356 The linear ultrasonic data (sound velocity), and the second harmonic generation data (relative
357 nonlinearity parameter, β') were compared the corresponding results for different samples,
358 specifically the material characterizations that gave mechanical hardness and various thermo-
359 physical properties. In more details, mechanical hardness, and curing reaction and thermal
360 stability were evaluated through the mechanical (hardness) and thermal (glass transition
361 temperature, the initial decomposition temperature, and the temperature of the maximum rate
362 of degradation) parameters for the various samples. Potential correlations between the
363 nonlinearity parameter and material properties of epoxy samples with varying levels of
364 contamination were investigated.

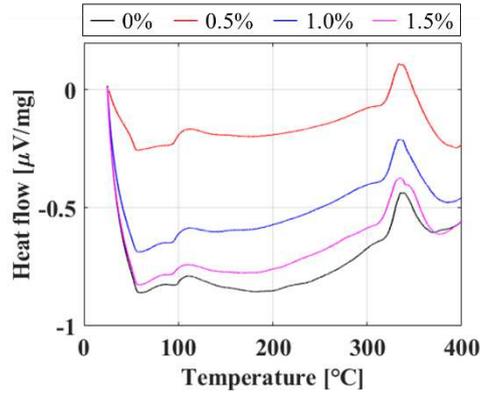
365

366 5.1 Effects of contaminant on thermal properties of epoxy-adhesive

367 The DSC analysis was conducted to investigate the curing behavior of the epoxy-adhesive with
368 varying levels of contamination. Fig. 8 shows the DSC result of four contaminant cases. From
369 these results, the T_g for each contaminant case was calculated and these data are summarized
370 in Table 1. The T_g values of the contaminated materials are lower than that for the pure
371 material, and the T_g value is gradually decreased with the increase in the level of the
372 contaminant. This trend means that the contaminant would appear to slow the curing reaction
373 of the epoxy mixture, because the partial weight of the contaminant can be miscible with the
374 epoxy during the curing process. If the curing reaction decreases due to the contaminant and
375 there is unreacted epoxy in the mixture in the cured state, the cross-linking density would also
376 be decreased, which reduces the chemical rigidity of the epoxy network. It appears that it can
377 be assumed that the contaminant can retard the rate of the curing reaction and deteriorate the
378 physical/chemical properties of the epoxy system.

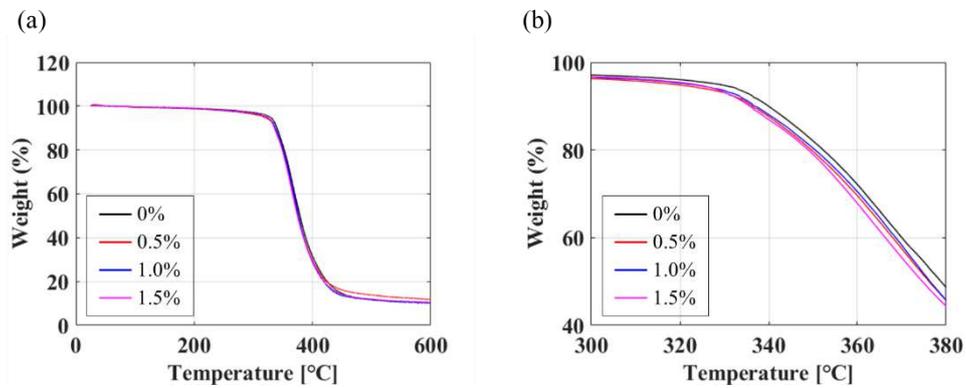
379 The TGA analysis was conducted to investigate the effect of the contaminant on the thermal
380 stability of the epoxy-adhesive. The TGA results, the weight loss as a function of the
381 temperature, are shown in Fig. 9. To determine the thermal stability of the material, also known
382 as the thermal degradation behavior, the IDT and the T_{max} were used as indicators. The
383 values of these two temperatures with varying levels of contamination are summarized in Table
384 1. From the data it is seen that the IDT of the contaminated materials are definitely lower than
385 that of the pure material. The contaminated cases have a similar value of IDT , which is not
386 unreasonable given that the differences between the contamination levels is small, and this
387 results in only very small changes in the initial decomposition range. These results do show
388 that the pure epoxy has a better epoxy network. Also, the T_{max} is gradually decreased with
389 the increased in the level of the contaminant. After the initial decomposition range, the higher
390 the level of contamination the higher the thermal decomposed. Based on the decrease in the
391 IDT and T_{max} with the increased in the level of contamination, the TGA results can also
392 confirm that it is highly likely that the contaminant can induce the incomplete curing reaction
393 of the epoxy mixture, and therefore decrease the cross-linking density. Both DSC and TGA
394 results show that the contaminant can deteriorate the thermal properties of the epoxy-adhesive.

395



396

397 **Fig. 8** DSC results of four contamination levels



398

399 **Fig. 9** TGA results (a) four contamination levels, and (b) data shown on expanded scales
400 between 300°C and 380°C

401

402 **Table 1** Curing reaction and thermal stabilities of samples as a function of the
403 contamination level

Contamination level	DSC	TGA	
	T_g (°C)	IDT (°C)	T_{max} (°C)
0%	99.86	339.6	378.1
0.5%	97.04	335.4	376.4
1.0%	96.17	336.7	376.2
1.5%	95.60	336.1	375.1
ΔT Error	$\pm 1^\circ\text{C}$		

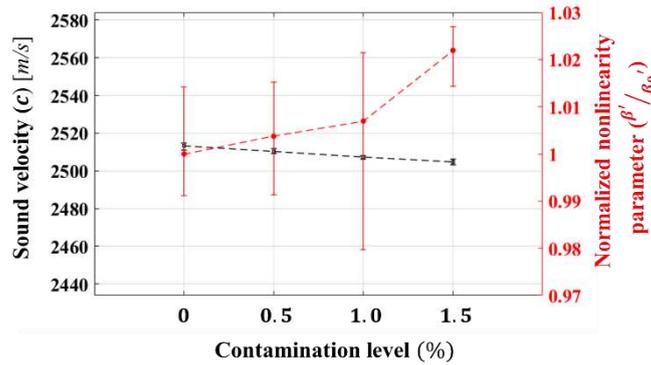
404

405 **5.2 Effects of the contaminant on ultrasonic parameters**

406 The sound velocity (c) and the relative nonlinearity parameter (β') were measured and data
407 compared for the epoxy-adhesive samples with varying level of contamination. The effects of
408 the contaminant on ultrasonic characteristics are shown in Fig. 10. In the comparison, the sound

409 velocity is seen to decrease, and the normalized nonlinearity parameter (β' / β_0') increases with
 410 the increase in the level of contamination. With the decreased trend of the sound velocity, if the
 411 mechanical hardness is decreased with the increased level of the contamination, it can be
 412 assumed that the contaminant can induce material softening in the epoxy-adhesive. Modulus
 413 of elasticity (E) is proportional to the sound velocity, and the modulus and the mechanical
 414 hardness (H) are related to each other.

415



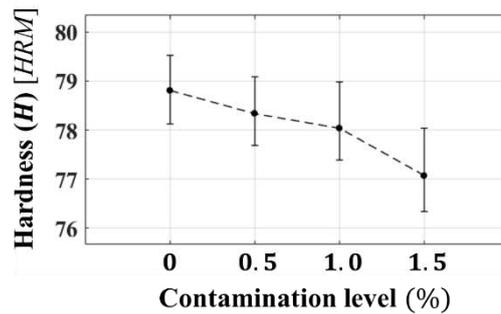
416

417 **Fig. 10** Comparison between changes in the sound velocity (c) and the
 418 nonlinearity parameter (β' / β_0') with varying the levels of contamination

419

420 To confirm this relationship, the effect of the contaminant on mechanical hardness of the epoxy-
 421 adhesive was investigated. With the increased level of the contaminant, the hardness of the
 422 epoxy-adhesive is decreased as shown in Fig. 11. This result confirms that the contaminant can
 423 induce material softening of the epoxy-adhesive, which in turn decreases the sound velocity.

424



425

426 **Fig. 11** Mechanical hardness (H) with varying level of contamination

427

428 In reviewing the data, the nonlinearity parameter, shown in Fig. 10, is seen to increase with
 429 increased contamination. This change correlates with the expected micro-structural change in

430 the epoxy-adhesive due to the contaminant. When the contaminant causes the slower curing
431 reaction in the epoxy-adhesive, there will be incomplete curing and impurities generated in the
432 cured epoxy-adhesive. These impurities can be related to the micro-structural change in the
433 epoxy-adhesive, which means the increased impurities due to the contaminant will cause the
434 increase of the nonlinearity parameter.

435 In addition, the sensitivity to changes in the contamination level was compared for the sound
436 velocity and the normalized nonlinearity parameter. While the rate of change in the sound
437 velocity is only 0.33% from the pure case to the 1.5% contamination level, the normalized
438 nonlinearity parameter is changed by 2.15% as shown in Fig. 10.

439 It can be seen that the nonlinearity parameter has the potential, in at least this case, to detect
440 the level of contamination. The effect on β' is seen to be 6.5 times larger than the
441 corresponding change seen in the sound velocity. The sensitivity comparison of ultrasonic
442 parameters was also extended to consider –the mechanical hardness. The rate of change of the
443 hardness from the pure case to the 1.5% contamination level is about 2.16% as shown in Fig.
444 11. This trend is in good agreement with that seen for the nonlinearity parameter, which shows
445 a good correlation between the changes in the nonlinearity parameter and the hardness.

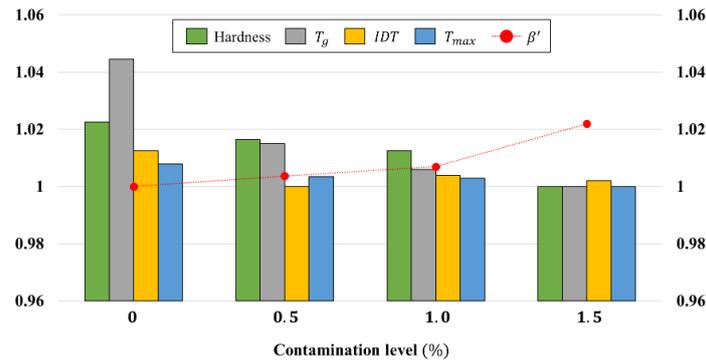
446

447 **5.3 Correlations between nonlinearity parameter and the mechanical, and thermal** 448 **properties**

449 The effects of contaminant showed that the perturbation of the chemical reactions, by the
450 contamination, in the epoxy system were seen in the changes in the mechanical degradation of
451 the epoxy-adhesive. To investigate the relationships between the nonlinearity parameter and
452 the degradation of material properties for the epoxy-adhesive due to the contaminant, possible
453 correlations were investigated.

454 The parameters related to the thermal and mechanical properties of the epoxy-adhesive and the
455 nonlinearity parameter were normalized to enable more convenient comparison and these
456 normalized values are shown in Fig. 12. The changes in nonlinearity parameter show a good
457 correlation with the thermal and mechanical properties with varying level of contaminant. If
458 the thermal and mechanical properties of the epoxy-adhesive are gradually degraded by the
459 contaminant, the nonlinearity parameter is seen to have a proportionally increase due to the
460 degree of degradation. On the basis of this correlation, it can be assumed that the SHG method
461 using the relative nonlinearity parameter (β') can potentially be used to nondestructively
462 measure the effect of the contaminant on the thermal and mechanical properties of the epoxy-
463 adhesive.

464



465

466 **Fig. 12** Relationships between the nonlinearity parameter and material properties of the
 467 epoxy-adhesive with different levels of contamination.

468

469 6. Conclusions

470 This study demonstrates that the SHG method using the nonlinearity parameter (β') can
 471 potentially be used to evaluate the effect of a contaminant on the material properties of an
 472 epoxy-adhesive. The experimental results show that the nonlinearity parameter has higher
 473 sensitivity to the level of contamination than the sound velocity. In addition, the changes in the
 474 nonlinearity parameter, with varying level of the contamination, are seen to correlate well with
 475 changes in the mechanical hardness. Thermal analyses also showed that the increased level of
 476 the contaminant gradually degrades the curing reaction and the thermal stability of the epoxy-
 477 adhesive, which correlates with increases in the nonlinearity parameter. The observed
 478 correlation between the nonlinearity parameter and mechanical, and thermal characteristics of
 479 the epoxy adhesive with varying degrees of contaminant demonstrates that the nonlinearity
 480 parameter has potential as a quantitative nondestructive method for use to evaluate the bond
 481 quality of the epoxy-adhesive.

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