

# New Generalized ANN Based Hybrid Broadband Response Spectra Generator using Physics Based Simulations

**Varun Sharma**

IIT Mandi: Indian Institute of Technology Mandi

**J. Dhanya**

IIT Mandi: Indian Institute of Technology Mandi

**Maheshreddy Gade** (✉ [maheshreddy@iitmandi.ac.in](mailto:maheshreddy@iitmandi.ac.in))

Indian Institute of Technology Mandi

**S. Jayalakshmi**

King Abdullah University of Science and Technology

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## Research Article

**Keywords:** Physics Based Simulations, PSHA, ANN, hybrid broadband 36 ground motion, spectral ordinate matching.

**Posted Date:** June 8th, 2022

**DOI:** <https://doi.org/10.21203/rs.3.rs-1672857/v1>

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4 Varun Sharma<sup>1</sup>, J. Dhanya<sup>2</sup>, Maheshreddy Gade<sup>1\*</sup> and S.  
5 Jayalakshmi<sup>1</sup>

6 <sup>1,2,3\*</sup>School of Engineering, IIT Mandi, Kamand, Mandi, 175005,  
7 Himachal pradesh, India.

8 <sup>4</sup>Division of Physical Science and Engineering, King Abdullah  
9 University of Science and Technology, Thuwal, Saudi Arabia.

10 \*Corresponding author(s). E-mail(s):

11 [maheshreddy@iitmandi.ac.in](mailto:maheshreddy@iitmandi.ac.in);

12 Contributing authors: [d21029@students.iitmandi.ac.in](mailto:d21029@students.iitmandi.ac.in);

13 [dhanya17@gmail.com](mailto:dhanya17@gmail.com);

14 [jayalakshmi.sivasubramonian@kaust.edu.sa](mailto:jayalakshmi.sivasubramonian@kaust.edu.sa);

15 **Abstract**

16 To evaluate the seismic risk associated with infrastructures, site-specific  
17 seismic hazard studies are needed to be performed. Further, for non-  
18 linear time history analysis, one requires broadband ground motion. In  
19 modern times using physics-based simulations (PBS) for deriving the  
20 ground motion for future earthquakes has got due consideration. The  
21 PBS helps in decreasing the uncertainties related to the hazard esti-  
22 mation compared to GMPEs. There is a certain threshold to the PBS  
23 methods with the limited computational facilities. Hence, certain hybrid  
24 methods are required to attain a Broadband spectra for the simulated  
25 ground motion. This study uses a new ANN-based model to generate  
26 broadband ground motion spectra using the low-frequency spectral accel-  
27 eration from PBS, source, path, and site parameters as input variables.  
28 A detailed parametric study and performance evaluation was made to

29 identify the optimal input parameters in conjunction with the best-suited  
30 ANN architecture. The performance of the ANN model is demonstrated  
31 for Iwate ( $M_w$  6.9,2008) earthquake. We found that the predicted values  
32 from the developed ANN model are in good agreement with the recorded  
33 data. Furthermore, time histories are generated using the spectral  
34 ordinate matching technique from the estimated broadband spectra.

35 **Keywords:** Physics Based Simulations, PSHA, ANN, hybrid broadband  
36 ground motion, spectral ordinate matching.

## 37 1 Introduction

38 Several past earthquakes have caused huge societal and life damage to  
39 mankind. The ever-growing population, economic activities, and rising infras-  
40 tructure demand escalate the seismic risk. In order to minimize the losses  
41 and to come up with better engineering solutions seismic hazard analysis is  
42 required. Hazard estimation provides a basic framework for building codes,  
43 insurance companies and mitigation strategies. In order to ensure public  
44 safety against a possible earthquake event, researchers are trying to come up  
45 with earthquake forecasting capabilities equivalent to that of weather fore-  
46 cast (Maechling et al., 2007). Although the target is far from accomplished,  
47 incorporating physics laws in ground motion simulations is a step forward. Tra-  
48 ditionally, characterization of earthquake hazard is done using Probabilistic  
49 Seismic Hazard Analysis (PSHA) (McGuire and Arabasz, 1990). The PSHA  
50 framework includes several empirical models that are typically subjected to  
51 variability in source, site, and path modeling. The PSHA framework includes  
52 several empirical models that are typically subjected to variability in source,  
53 site, and path modeling. The corresponding variability might result in signif-  
54 icant uncertainties in the hazard model, reducing the predictions' accuracy.  
55 One of the key contributors to the uncertainty in the seismic hazard frame-  
56 work is Ground Motion Prediction Equations (GMPEs). GMPEs represent the

57 probability of exceedance of an intensity measure for an earthquake event at a  
58 particular site accounting for source, site, and path effects. Although GMPEs  
59 are easy to compute, these equations are regression-based and do not com-  
60 pletely capture various physical phenomena like the source directivity and  
61 basin effect observed during an earthquake (Graves et al., 2011). In addi-  
62 tion, even though computationally efficient, GMPEs do not provide earthquake  
63 acceleration time histories that are required for complex non-linear problems.  
64 Also, the obtained Intensity Measure (IM) from GMPEs is an average of sev-  
65 eral sites spatially distributed over a large region (ergodicity) rather than  
66 multiple ruptures occurring at a single site, which results in high aleatory  
67 uncertainty. Further, the ergodic assumption in GMPEs shows an upward bias  
68 in hazard estimation (O’Connell et al., 2007). By including inelastic wave prop-  
69 agation effects that are site-specific through physics-based simulations (PBS),  
70 the aleatory uncertainty in the hazard estimation can be reduced (Milner et al.,  
71 2021). The PBS replaces the GMPE term and generates IMs based upon simu-  
72 lated ground motions, which reduces uncertainty in the PSHA framework and  
73 develops more realistic earthquake hazard models. With the advancement in  
74 computational infrastructure, researchers have developed physics-based earth-  
75 quake simulators (Paolucci et al., 2015; Cui et al., 2013; Shaw et al., 2018;  
76 Graves et al., 2011). In some of the recent studies, researchers proposed to  
77 replace the traditional GMPEs in PSHA with PBS results (Maechling et al.,  
78 2007). Platforms like Cybershake (Graves et al., 2011) and Cybershake NZ  
79 (Bradley, Tarbali, Lee, Huang, Motha, Bae, Polak, Zhu, Schill, Patterson, and  
80 Lagrava, Bradley et al.) have generated PBS for over 415,000 and 11,362  
81 rupture variations, respectively.

82 With all the benefits of PBS, the computational requirement remains a  
83 major challenge. The available infrastructure for PBS involves a frequency

84 threshold, i.e., 1-1.5Hz of accuracy (Paolucci et al., 2018). Generally, earth-  
85 quake ground motion is comprised of broadband frequencies(0-10Hz), PBS  
86 for which requires a very fine mesh size and large detailing of topological  
87 and geological features, which demands a huge computational cost. Recently,  
88 researchers are coming up with techniques to reduce these computational  
89 requirements (Cui et al., 2013; Shaw et al., 2018; Milner et al., 2021) by  
90 including various approximations. However, a standard methodology is yet to  
91 be achieved. A suitable alternative would be to develop broadband ground  
92 motion using hybrid methodologies combining low-frequency PBS with a suit-  
93 able high-frequency generator. The effectiveness of the corresponding hybrid  
94 approaches is evident as many researchers have successfully implemented them  
95 to simulate broadband ground motions (Smerzini and Villani, 2012; Razafindr-  
96 rakoto et al., 2018; Gade and Raghukanth, 2017; Jayalakshmi et al., 2021).  
97 With the recent advancements in the field of Artificial Intelligence(AI) and  
98 machine learning, researchers are including the AI-based methods in the field  
99 of earthquake engineering (Ahmad et al., 2008; Derras et al., 2014; Dhanya and  
100 Raghukanth, 2018a; Gade et al., 2021; Mignan and Broccardo, 2020; Dhanya  
101 and Raghukanth, 2022). Recently, Paolucci et al. (2018) have proposed an  
102 ANN model to predict high-frequency response spectra using PBS-based low-  
103 frequency spectra. The ANN model was designed and trained by utilizing the  
104 SIMBAD database, which consists of only 500 strong motion records corre-  
105 sponding to 130 earthquake events with  $M_w$  range of 5 to 7.3 and epicentral  
106 distance ( $R_{epi}$ )  $<$  35 km. Further, the efficiency of the proposed methodology  
107 was demonstrated by generating Broadband ground motion for the 2012 Po  
108 Plain earthquake  $M_w$  6. However, due to the limited range of  $M_w$  and  $R_{epi}$ ,  
109 the model is only applicable for specific events. Further, the developed ANN

110 model uses only Spectral Acceleration ( $S_a$ ) values for  $T > T^*$  (Period corre-  
111 sponding to threshold frequency) as the predictor variables. The application of  
112 the corresponding idea in a more general sense demands the inclusion of a more  
113 comprehensive dataset alongside source, path, and site parameters as predic-  
114 tor variables. Furthermore, an extensive parametric performance evaluation is  
115 needed to identify the best-suited ANN architecture.

116 The present study aims to develop a prediction model for high-frequency  
117 spectra using PBS-based low frequency  $S_a$  values, source, path, and site  
118 parameters as predictor variables. Further, a methodology is developed to gen-  
119 erate Broadband ground motion from the predicted ANN spectra using the  
120 low-frequency PBS. The comprehensive dataset available in the NGA-West2  
121 database was utilized in developing the model. Here, moment magnitude ( $M_w$ ),  
122 rupture distance ( $R_{rup}$ ), shear wave velocity in top 30m ( $V_{s30}$ ), focal mecha-  
123 nism ( $FM$ ) and  $S_a$  for  $T \geq T^*$  are considered as input variables. Additionally,  
124 the effectiveness of the developed model is demonstrated by simulating the  
125 ground motions for the Iwate ( $M_w$  6.9, 2008) earthquake. The model shows  
126 fairly accurate results compared with the recorded data for several stations.

## 127 2 Database

128 The present study utilizes spectral acceleration data available in NGA-West  
129 2, which is a comprehensive global database for ground motion time histo-  
130 ries [Taylor et al. \(2007\)](#). Here, horizontal rotd50 response spectra available  
131 at <https://peer.berkeley.edu/research/data-sciences/databases> is used. The  
132 database constitutes 21540 ground motion records from 600 events as on  
133 January 2015. . The spectral acceleration values are for horizontal rotd50 com-  
134 ponent. The data is filtered ([Dhanya and Raghukanth, 2018a](#)) in order to  
135 avoid unsuitable records. The filtration led to the elimination of the spurious

136 records and left with 13552 records from 288 events. The distribution for the  
137 sorted data among various ranges of distance and magnitude among various  
138 focal mechanism classes is shown in Fig. 1. The range of magnitude ( $M_w$ )  
139 and rupture distance ( $R_{rup}$ ) is 3 - 7.9 and 0.05km - 497 km, respectively and  
140  $V_{S30}$  ranges from 89 to 2016 m/s. The classification focal mechanism classes  
141 are based on rake angle, the ranges of which have been included in the Fig. 1.  
142 The filtered database consists of 180 strike-slip, 38 normal and normal oblique,  
143 and 70 reverse and reverse oblique events. The focal mechanisms ( $FM$ ) are  
144 assigned with flags 1, 2, and 3 for strike-slip, normal and normal oblique, and  
145 reverse and reverse oblique. Additionally, the spectral accelerations values of  
146 91 periods between 0 and 4s are considered for the analysis.

### 147 **3 ANN Model for Prediction of Short Periods** 148 **Spectra**

149 ANN models are generally used to develop non-linear relationships between a  
150 large set of input and output variables. The inspiration of the methodology  
151 is the functioning of the human brain, which can work on several parallel  
152 networks of interconnected neurons at an instant. The methodology is simple to  
153 use and highly efficient for the generation of predictor models. The architecture  
154 of an ANN model consists of a layer of input neurons that is connected with  
155 the hidden layers that are further connected with a layer consisting of output  
156 neurons (Wang, 2003). Each connection is assigned with certain weights, and  
157 the weights are adjusted in such a manner that it matches the desired output.  
158 Other important elements of an ANN network are the transfer function and

159 error function. The general representation of an ANN model is:

$$160 \quad h_i = \sigma\left(\sum_{j=1}^N W_{ij}x_j + T^{hid}\right) \quad (1)$$

161 where  $h_i$  is the output parameters,  $\sigma$  is the transfer function,  $W_{ij}$  is the  
162 weights,  $x_j$  is the input parameters and  $T^{hid}$  is the threshold associated with  
163 hidden neurons.

In this study, a feed-forward neural network with a multi-layer of perceptron (MLP) is developed to predict short period spectral ordinates ( $T < T^*$ ) based upon long period spectral ordinates ( $T \geq T^*$ ) and parameters representing source, path, and site. Here,  $T^*$  is the threshold or crossover period. The initial step in generating a neural network was deciding the functional form such that it captures the buried features within the data with minimal variance. For this purpose, several trials were performed using different combinations of input variables and transfer functions (Nayek and Gade, 2022). The corresponding details are included in the supplementary material. The final form of input and output variables is as follows:

$$164 \quad \log_{10}S_a(T < T^*) = f(\log_{10}S_a(T \geq T^*), M_w, \log_{10}V_{(s30)}, R_{rup}, \log_{10}R_{rup}, FM) \quad (2)$$

165 where  $M_w$  - Moment magnitude,  $S_a$  - Spectral Acceleration,  $R_{rup}$  - rupture  
166 distance,  $V_{s30}$  - shear wave velocity in the top 30m of soil and  $FM$  - focal  
167 mechanism.

168 The next decision in the development of a neural network is selecting an  
169 optimal number of hidden layers and hidden neurons. However, there are no  
170 stringent criteria for selecting the number of hidden layers for a neural network.  
From the past studies, it has been found that in most cases, a single layer of

171 hidden neurons is sufficient to capture the model characteristics (Wang, 2003).  
 172 Therefore, this study also employs a single layer of hidden neurons. Several  
 173 criteria exist for deciding the number of hidden neurons, and researchers have  
 174 taken the number equal to twice the number of input neurons (Berry and  
 175 Linoff, 2004). Nevertheless, no improvement has been observed in the model  
 176 performance when the hidden neurons are greater than the input variables.  
 177 Therefore, to avoid the problem of over-fitting, we have taken the number  
 178 of hidden neurons equal to the number of input neurons. Furthermore, an  
 179 appropriate scaling function is used to bound the data between 0 to 1 or -1 to  
 180 1 to maintain uniformity among the variables. Here, we scaled out parameters  
 181 between range -1 to 1 using the scaling, such that

$$182 \quad Y = a(Y - Y_{min}) - 1 \quad \text{where} \quad a = \frac{2}{Y_{max} - Y_{min}} \quad (3)$$

183 where,  $Y$  is the parameter value to be scaled,  $Y_{max}$  and  $Y_{min}$  the correspond-  
 184 ing maximum and minimum values. Further, the procedure includes training,  
 185 validation, and testing of the ANN model. For this purpose, a random divi-  
 186 sion of data is done into the training, validation, and testing sets in 75, 15,  
 187 and 15%, respectively. The purpose of the step is to make sure that the model  
 188 does not show any trend/bias towards a particular input parameter. In the  
 189 training phase, the error function between the predicted and actual values is  
 190 minimized using different algorithms. This study utilizes Levenberg-Marquardt  
 191 (LM) algorithm with the fitnet function available in the Matlab Deep learning  
 192 toolbox MATLAB (2019). Thus, we finalized a total of 88 cases having varied  
 193 combinations of input variables and transfer functions in arriving at the final  
 194 prediction model. In all these cases, the crossover period  $T^*$  is taken as 0.75s.

195 The performance of each of the model architecture is assessed based on the  
 196 following performance criteria:

197 1. Pearson correlation coefficient ( $R$ )

$$198 \quad R = \frac{\sum_{i=1}^N (O_i - \overline{O_i})(\hat{O}_i - \overline{\hat{O}_i})}{\sqrt{\sum_{i=1}^N (\hat{O}_i - \overline{\hat{O}_i})^2 \sum_{i=1}^N (O_i - \overline{O_i})^2}} \quad (4)$$

199 2. Performance Parameter ( $PP$ )

$$200 \quad PP = 1 - \frac{\langle \| O - \hat{O} \|^2 \rangle}{\sigma_O^2} \quad (5)$$

201 3. Root Mean Squared Error ( $RMSE$ )

$$202 \quad RMSE = \sqrt{\frac{\sum_{i=1}^N (O_i - \hat{O}_i)^2}{N}} \quad (6)$$

203 4. Standard deviation of error ( $\sigma(\epsilon)$ )

$$204 \quad \sigma(\epsilon) = \sqrt{\frac{\sum_{i=1}^N (O_i - \hat{O}_i) - \overline{(O_i - \hat{O}_i)}}{N - 1}} \quad (7)$$

205 Where,  $O = \log_{10} S_a(T > T^*)$  is the output from the models,  $N$  is the number  
 206 of data-points. The best model will have  $R$  and  $PP$  values closer to unity  
 207 and  $MSR$  and  $\sigma(\epsilon)$  minimum. We observed that the best transfer function  
 208 varies based on the form of input (Refer Supplement material). Furthermore,  
 209 the best performance was obtained for the model containing source, path,  
 210 site characteristics, and long-period spectral accelerations. The corresponding

211 model performed best with transfer functions as tan-sigmoidal between the  
 212 input to hidden layers and pure-linear between hidden to output layers. The  
 213 related functional form of the model is as shown further:

$$214 \quad \log_{10}S_a(T > T^*) = f_2(bias_2 + \sum_{k=1}^m W_{k,2}f_1(bias_{k,1} + \sum_{i=1}^n W_{ik,1}X_i)) \quad (8)$$

215 where,

$$216 \quad f_1(x) = \frac{1 - e^{-x}}{1 + e^{-x}} \quad \text{and} \quad f_2(x) = x \quad (9)$$

217 In eqn. 8 the  $X_i$  is the input consist of the parameters in eqn. 2,  $W_{ik,1}, bias_{k,1}$   
 218 are the unknowns between input-hidden layers and  $W_{k,2}, bias_2$  are the  
 219 unknown coefficients between the hidden-output layers. The best performing  
 220 the network architecture for the crossover period of  $T^* = 0.75s$  consists of 21  
 221 input neurons and 17 output neurons, with 836 unknown weights and biases.  
 222 The details of the network architecture can be understood from Fig. 3. Since  
 223 physics-based simulators have different threshold frequencies, ANN models are  
 224 also developed for additional periods of 0.5 and 1s. The corresponding archi-  
 225 tecture for crossover periods of 0.5s and 1s consists of 24 input neurons, 14  
 226 output neurons, 950 unknown weights and biases, and 18 input neurons, 20  
 227 output neurons, 722 unknown weights and biases, respectively. The perfor-  
 228 mance parameters corresponding to each crossover period ( $T^*$ ) are compiled  
 229 in Table 1. We obtained comparable performance at all crossover periods. Fur-  
 230 thermore, the performance and applicability of these models are investigated  
 231 in detail in the following section.

## 4 Performance Analysis of ANN Model

An essential procedure to evaluate the performance of the developed models is through residual analysis. Further, residual analysis is helpful in investigating whether the model has the ability to reproduce major features within the data. Residual is the difference between the actual and the model predicted value, and ideally, the sum and mean of the residual should be zero. In this study, the logarithmic residual between the predicted and the recorded  $S_a$  is plotted for three crossover periods ( $T^*$ ) is presented in Fig. 3. The plot shows that the mean residuals do not contain any trend. Further, it can be concluded that the mean value of residual value oscillates around zero, which depicts the accuracy of the method and proves that there does not exist a bias towards a particular period. Additionally, we observe that the residues are minimum at the crossover period. The corresponding feature of the models will facilitate avoiding any jump that might arise in typical hybrid broadband methodologies (Paolucci et al., 2018). Furthermore, there always exists a debate on ANN usage in natural phenomena. Since there exist several hidden layers in the network, it becomes obligatory to verify whether the developed model follows the physical laws. The variation of the predicted  $S_a$  values with  $M_w$ ,  $R_{rup}$  and  $V_{s30}$  for different fault mechanisms is shown in Fig. 4 and 5. The corresponding demonstration is made for a crossover period of 0.75s. Here, the long period spectral acceleration values are taken from the mean prediction by Dhanya and Raghukanth (2018b) for the same database. From Fig. 4, It can be observed that the  $S_a$  value decreases with an increase in  $R_{rup}$ , and the peak period of the spectra is shifting towards long periods with the increase in magnitude. Furthermore, from Fig. 5 it is observed that the spectral acceleration values increase with the decrease in  $V_{s30}$ , and the peak period gets shifted to long periods. It is also interesting to note that there are no jumps

259 at the crossover period. Thus it can be concluded from the performance eval-  
260 uation that the models are unbiased and able to capture the known physics of  
261 ground motion. Another interesting observation is that the model inherently  
262 maintains the compatibility at the crossover period. Nevertheless, we would  
263 like to state that all models listed in Table 1 performed equally well and can be  
264 applied suitably depending on the available computational facility. It would be  
265 interesting to observe the application of the ANN model to a real earthquake,  
266 a demonstration of that has been presented in the next section.

## 267 4.1 Case study of Iwate Earthquake, 2008 $M_w$ 6.9

### 268 4.1.1 Earthquake Source Model

269 On 14 June 2008, an earthquake of magnitude 6.9  $M_w$  occurred in  
270 the borders of Iwate and Miyagi districts of Japan. The focal mecha-  
271 nism is the reverse fault with W-NW and E-SE as the compression axis.  
272 The rupture models from several source-inversion studies are available  
273 for the event at [http://equake-rc.info/SRCMOD/searchmodels/viewmodel/](http://equake-rc.info/SRCMOD/searchmodels/viewmodel/s2008IWATEx01ASAN/)  
274 [s2008IWATEx01ASAN/](http://equake-rc.info/SRCMOD/searchmodels/viewmodel/s2008IWATEx01ASAN/). These rupture models differs in amplitude, location  
275 of large slip regions (or asperities), hypocenter location, fault dimensions and  
276 temporal parameters. These differences arise due to the assumptions used in  
277 each source-inversion. In this study, the rupture models of [Cultrera et al.](#)  
278 [\(2013\)](#) and [Asano and Iwata \(2011\)](#) have been used . The details of the source  
279 parameters for the rupture models are compiled in Table 2. The [Cultrera et al.](#)  
280 [\(2013\)](#) model is based upon a two-staged non-linear kinematic source inver-  
281 sion technique of the fault plane [Piatanesi et al. \(2007\)](#). The Cultrera's model  
282 uses Yoffe-type source time function to describe the temporal evolution of slip  
283 [\(Tinti et al., 2005\)](#). The [Asano and Iwata \(2011\)](#) model uses multiple time  
284 windows in the inversion, the temporal evolution of slip is represented by a

285 smooth ramp in the slip velocity function, with a constant rise time of 4.5 sec  
286 and an average rupture velocity of 2.4km/s ( 0.8Vs). The corresponding slip  
287 and rupture time distributions for the models are shown in Fig. 6.

### 288 4.1.2 Low-Frequency Physics Based Simulations

289 The low-frequency simulations are performed using a discrete-wavenumber  
290 finite element method [Olson et al. \(1984\)](#); [Spudich and Xu \(2002\)](#). To consider  
291 the slowest shear wave velocity, 2.7km/s a grid resolutions of  $dz = 150\text{m}$  is  
292 used to simulate ground motions up to a maximum frequency of 3Hz. Adopting  
293 a 1D Earth structure (Table 3), synthetic waveforms at all recording stations  
294 (Joyner-Boore distance  $R_{jb} < 150\text{km}$ ) are computed. However, it is beyond  
295 the scope for the numerical simulations to capture nonlinear site effects due to  
296 the resolution of the mesh. Therefore, we correct for the site effects by remov-  
297 ing the mean site residuals for each site class at selected natural Periods. The  
298 database for the Iwate event is available at NGA West-2, the data consists of  
299 spectral ordinates for 150 stations. The low-frequency PBS simulations are  
300 performed for all of the recording stations. For representation purpose three  
301 stations AKT017, AKT012, and IWTH17 having  $R_{rup}$  values 33.8, 58.1 and  
302 73.7 km respectively has been chosen. The low frequency time histories corre-  
303 sponding to both source models for the three stations are shown in Fig. 7. It  
304 can be noticed that the arrival time increases with the increase in distance of  
305 the station from the fault rupture. Also, for the [Cultrera et al. \(2013\)](#) model  
306 the peaks amplitudes are larger, possibly due to the proximity of the stations  
307 to largest asperity region of the source.

### 308 4.1.3 ANN Model predictions for the Iwate Earthquake

309 Using the long period PBS as input and the developed ANN model discussed  
310 in section 3, the broadband response spectra are developed for all recording

311 stations of the Iwate Earthquake. Further to check the model performance, the  
312 residuals between the simulated and recorded  $S_a$  values have been evaluated  
313 as shown in Fig. 8. The figure consists of bias for PBS and the developed ANN  
314 model (Model-1) indicated in blue and red respectively. It is observed that,  
315 among the considered source models, [Asano and Iwata \(2011\)](#) model showed  
316 lesser residual and standard deviation compared to [Cultrera et al. \(2013\)](#)  
317 model. Such an observation can be attributed to the variability associated with  
318 the slip inversion techniques and the data. However, it was noted that the mean  
319 bias is very close to zero, pointing toward the efficiency of the developed model.  
320 Additionally, it was also noted that the standard deviation in the short-period  
321 range is lesser compared to the PBS period range. Now, it will be interesting  
322 to check the merits of including path and site characteristics, contrary to the  
323 model proposed by [Paolucci et al. \(2018\)](#). Hence, we made a comparison of the  
324 same by estimating the bias using the predictions from the ANN model that  
325 considered only long-period spectral acceleration as input variables (Model-2,  
326 Refer Supplement Material, Sl no: 2 for the corresponding architecture details).  
327 The corresponding bias is indicated as green color in Fig. 8. It can be observed  
328 that the prediction variability is more for Model-2, and the mean bias also  
329 significantly deviated from the zero-line in comparison with that of Model-1.  
330 These observations confirm that a better prediction of the short period spectra  
331 can be made by including path and site characteristics in the prediction model.  
332 Furthermore, a comparison between the recorded and the predicted spectra  
333 corresponding to the two ANN models (i.e., Model-1 and Model-2) is made for  
334 the three stations (i.e., AKT017, AKT012, and IWTH17) and is shown in Fig.  
335 9. It can be observed from the figure that the predicted spectra from Model-1  
336 are comparable with the recorded spectra. However, in the case of Model-2,  
337 the two spectra are not in good agreement with each other, similar to the

338 observation from the bias plots (Fig. 9). Further, it is interesting to note that  
339 Model-1 can generate comparable spectra at short periods, even if PBS spec-  
340 tra are not in line with the recorded values. A trend that is found absent in  
341 the case of Model-2. These findings further boost the claim that the inclusion  
342 of source and site parameters as predictor variables in the ANN model leads to  
343 better prediction of short period spectra. Therefore, it can be concluded that  
344 the proposed ANN model assists in developing broadband spectra accurately  
345 with lesser computational effort. For non-linear structural analysis, however,  
346 we require simulated time histories. The next section represents the generation  
347 of broadband ground motion using PBS and ANN predicted spectra.

## 348 5 Generation of Broadband Ground Motion

Generation of broadband ground motions using the predicted response spectra is presented in the section. Here, the spectral ordinate matching method, which iteratively modifies the input seed ground motion until it matches the target spectra, is used to generate the ground motions. The transformation is done using either the frequency or wavelet transform methods (Alexander et al., 2014). In this study, the spectral ordinate matching is done in the frequency domain using the code of Ferreira et al. (2020), and PBS is used as input seed ground motion. Due to the deficiency of PBS waveform corresponding to higher frequencies, a broadband time history cannot be achieved directly. Therefore we require a modified seed input that can cater to all frequency ranges. The methodology for the generation of modified seed can be understood using Fig. 10. Here, the initial seed is modified by adding band-pass (1.33 - 15 Hz) filtered white noise. Here, the white noise signal is filtered using the Butterworth band-pass filter in MATLAB. Further, for generating a non-stationary ground motion, the filtered white noise is modified using an envelope function. Here

the envelope function is the realistic exponential function (Takewaki, 2004) given in the following equation:

$$c(t) = \exp(-\alpha t) - \exp(-\beta t) \quad (10)$$

349 Where,  $\alpha = 0.13$  and  $\beta = 0.45$ . The added white noise is consistent with  
350 the stochastic nature of the earthquake ground motion and provides a  
351 complete waveform that can be spectrally matched to the target response  
352 spectra. The filtered white noise is then summed up with the PBS sig-  
353 nals to generate a modified seed that is appropriate to be used as input  
354 for the spectral ordinate matching technique. The generated modified seed  
355 consists of intensity corresponding to all frequencies and can be spec-  
356 trally matched to the ANN generated target spectra as shown in Fig. 11.  
357 The recorded and the simulated time histories along with the fourier amplitude  
358 spectra is represented in Fig. 12 and 13. It can be inferred from the figure that  
359 the generated time histories are in reasonable comparison with the recorded  
360 one, having comparable peaks and duration. The Fourier amplitude spectra of  
361 the simulated time histories match reasonably well with the recorded values at  
362 higher frequencies, even if lower frequency values are not comparable, similar  
363 to what was observed before in the response spectra plots. The study for the  
364 Iwate earthquake shows that the model can accurately predict response spec-  
365 tra for earthquakes in active shallow crustal regions. Further, we can conclude  
366 that the developed methodology can produce reliable results in simulating  
367 broadband ground motion for future earthquakes. The spectra obtained from  
368 the developed model can be used for physics based seismic hazard studies, and  
369 the broadband ground motion can be used for non-linear structural analysis.

## 6 Summary and Conclusions

This study proposes a new ANN model that can predict a broad-band spectrum using the physics-based low-frequency simulation, source, and site parameters as the predictor variables. The performance study indicates that including all these factors makes the model robust and accurate. The generated model embraces the advantages of the physics-based simulations in simulated ground motion corresponding to a broader spectrum. The statistical study and residual analysis prove the accuracy of the generated model. To show the effectiveness of the methodology Iwate earthquake of 2008,  $M_w$  - 6.9 was used as a case study. The results show that the predicted spectra are comparable with the recorded ones. Also, the model can capture the short period  $S_a$  values when PBS  $S_a$  values are not in line with the recorded values. The model-generated spectra can be used for seismic hazard studies, leading to better hazard mitigation strategies. Further, time histories were obtained using the spectral ordinate matching method from the generated spectra. The simulated time histories are compared with recorded ones for various stations. The results show that generated time histories are in agreement with the recorded ones. Furthermore, broadband ground motion can be generated for scenario events with different source and site parameters. The simulated ground motions is helpful while performing non-linear structural analysis for the earthquake forces. Although the model shows good performance in predicting a real earthquake, a model based upon advanced machine learning techniques will be interesting to explore. Further, NGA-west2 database consist of only shallow crustal earthquakes in active regions. For wider applicability similar model can be developed using other regional/global databases.

## 7 Statements & Declarations

All the authors involved in the study have contributed equally in the collection of the dataset, generation of the model, simulation for the case study and preparation of the manuscript. For the study no funds or grants were received, neither study corresponds to any financial or non-financial interest. The data and codes generated in this study are available with the corresponding author upon personal request.

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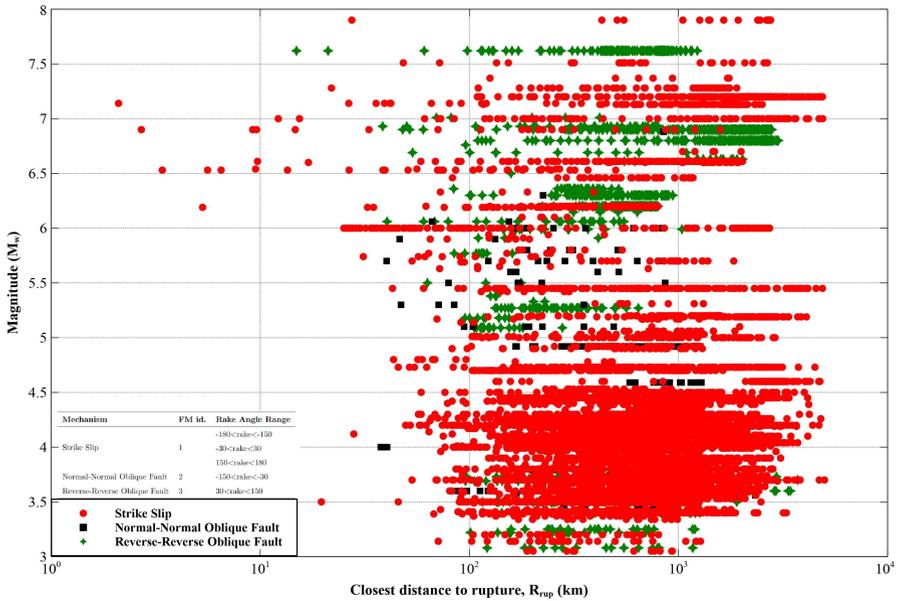
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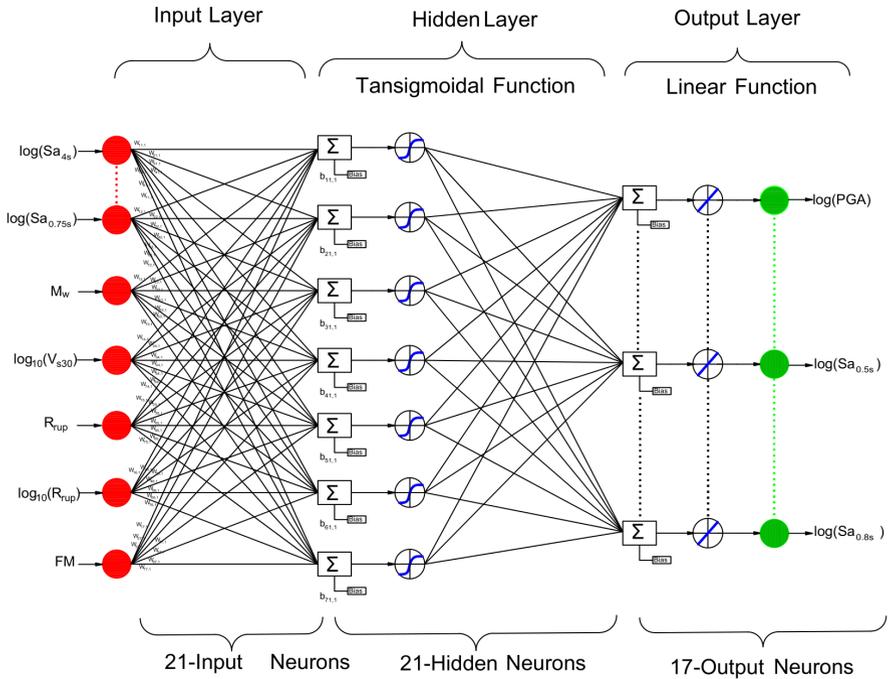
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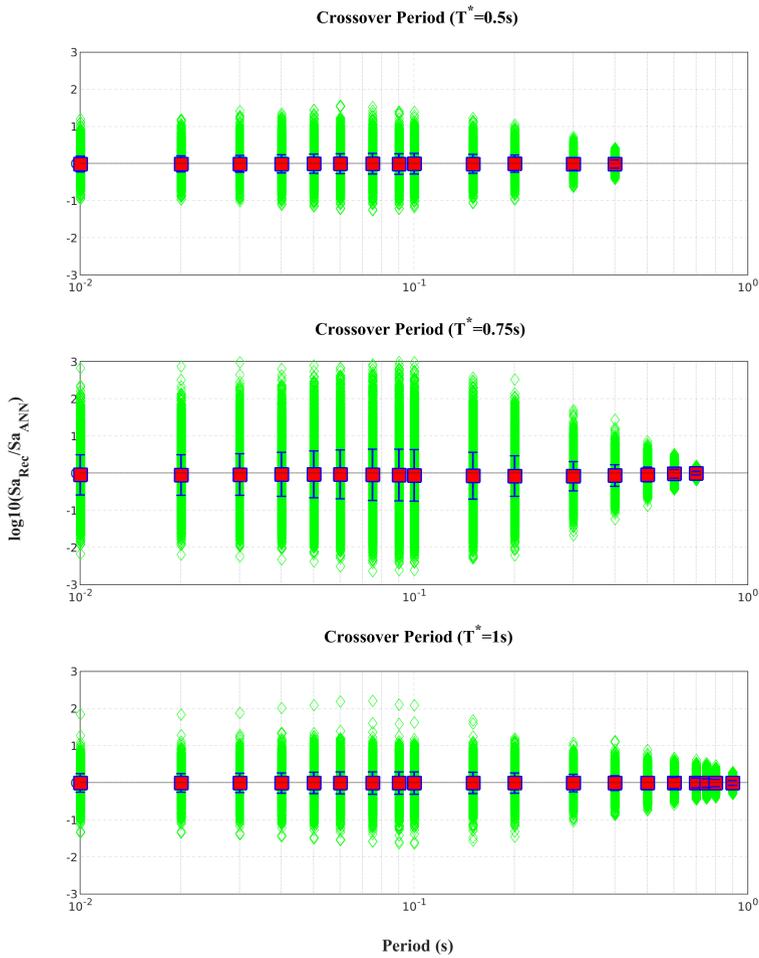
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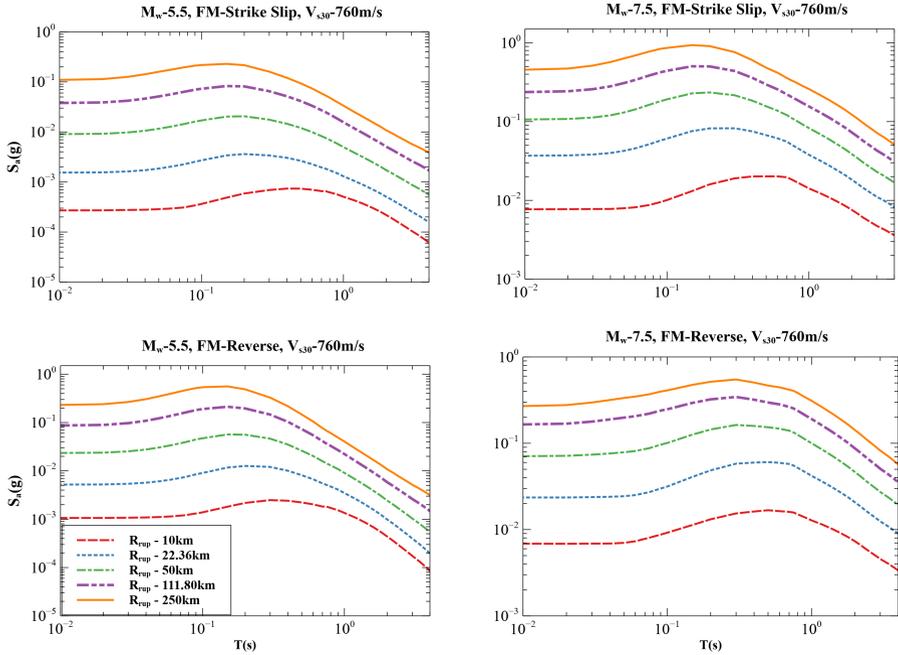
**Fig. 1:** Distribution of data, with respect to magnitude ( $M_w$ ), closest distance to fault ( $R_{rup}$ ) and the earthquake mechanisms, considered for the ANN model development



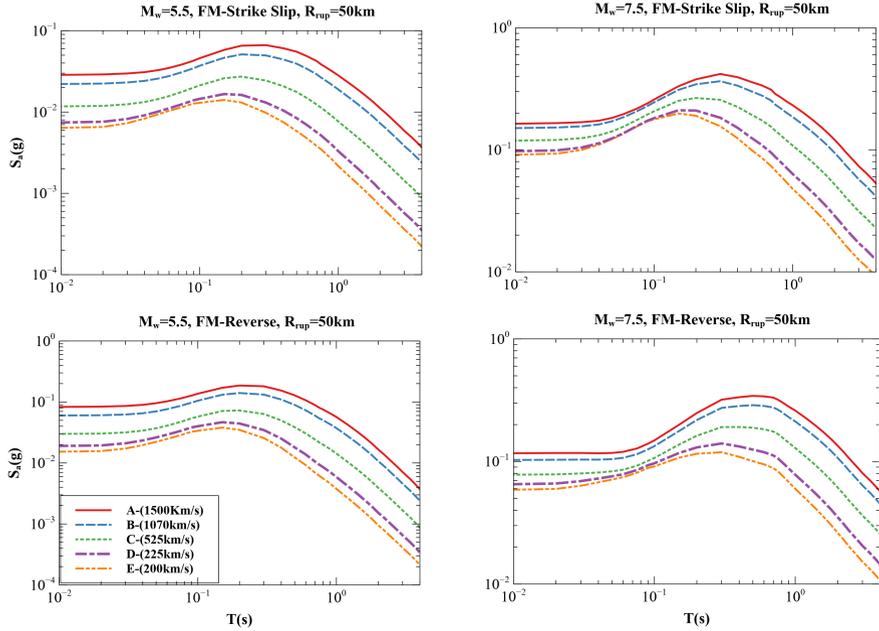
**Fig. 2:** The architecture of the artificial neural network (ANN) model to predict short period spectra from long period spectra, earthquake source, path and site characteristics. The represented architecture corresponds to that for a cross over period on 0.75s ( $M_w$  = moment magnitude,  $R_{rup}$  = closest distance to rupture, FM = focal mechanism,  $V_{S30}$  = average shear wave velocity of top 30 m,  $S_a$  = Spectral Acceleration,  $T^*$  (cross over period))



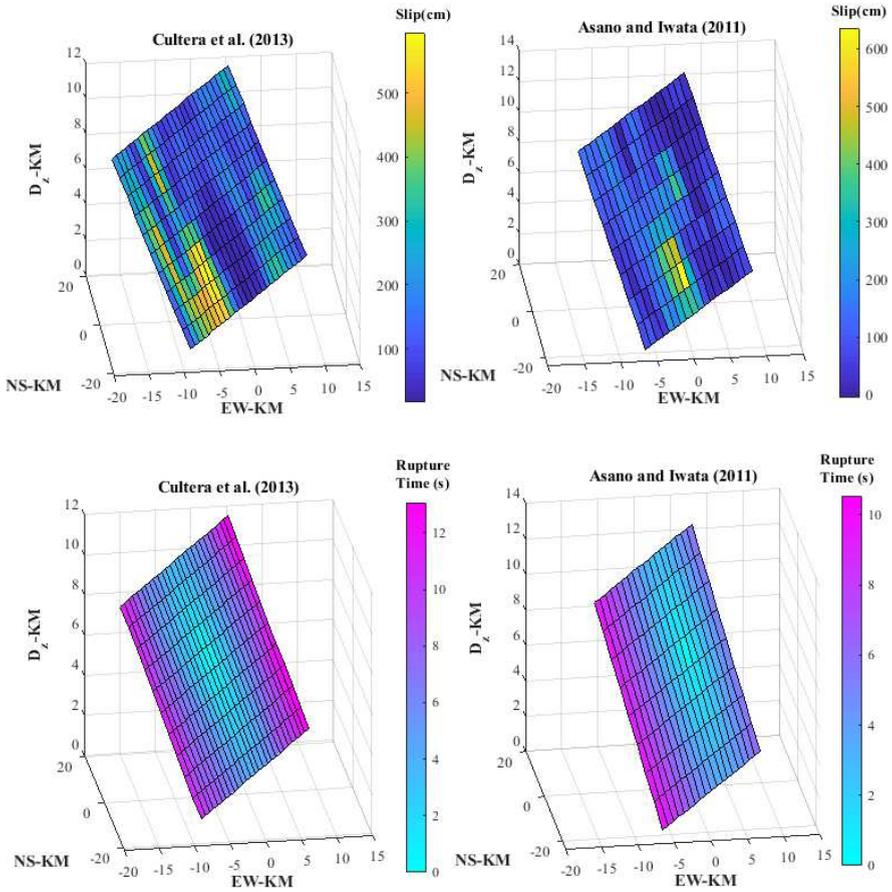
**Fig. 3:** Residuals along with bias estimation with time period for the ANN models developed from the present study corresponding to different cross over periods ( $T^*$ )



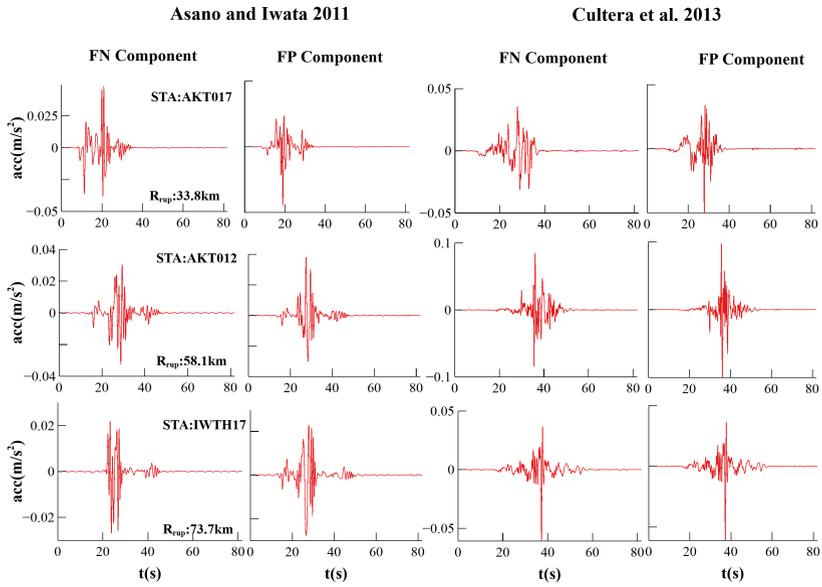
**Fig. 4:** Variation of Spectral Acceleration ( $S_a$ ) with respect to Rupture distance ( $R_{rup}$ ) for different Magnitude ( $M_w$ ) and Fault Mechanism (FM). Here the model with cross over period  $T^* = 0.75$ s is considered and low frequency spectral acceleration is taken from the mean value of prediction model developed by Dhanya and Raghukanth (2018)



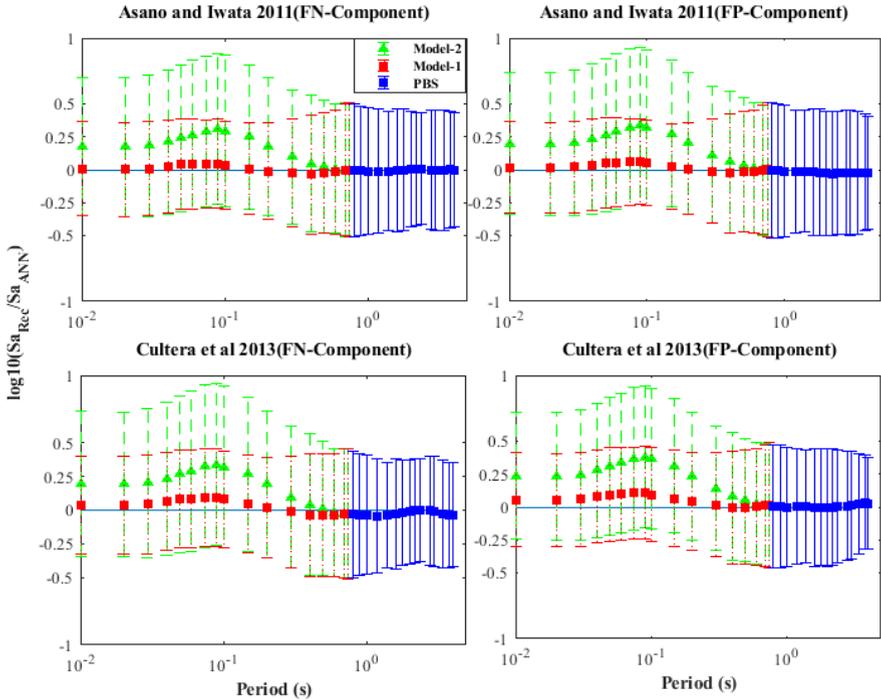
**Fig. 5:** Variation of Spectral Acceleration ( $S_a$ ) with respect to Rupture distance ( $V_{s30}$ ) for different Magnitude ( $M_w$ ) and Fault Mechanism (FM). Here the model with cross over period  $T^* = 0.75s$  is considered and low frequency spectral acceleration is taken from the mean value of prediction model developed by Dhanya and Raghukanth (2018)



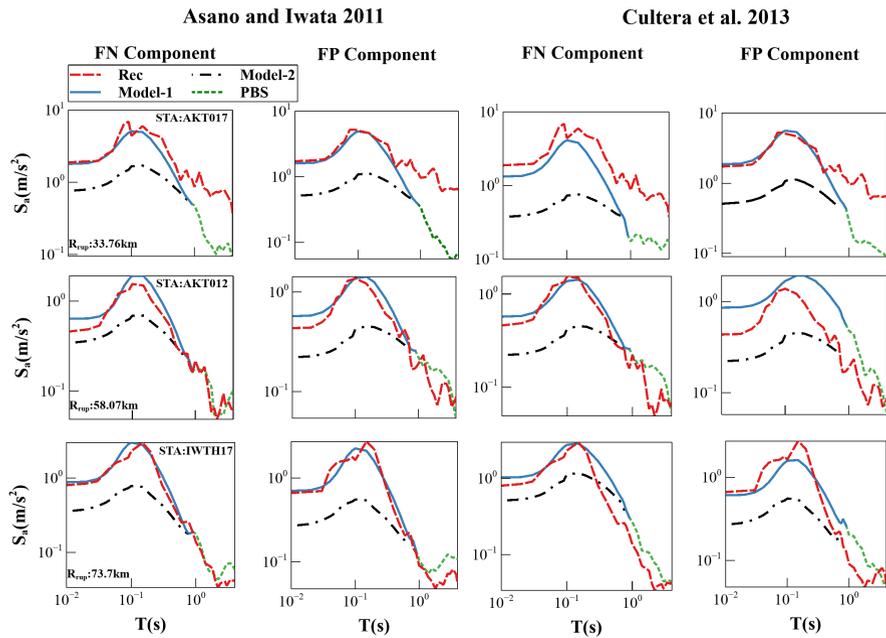
**Fig. 6:** Slip and rupture time distributions for Iwate Earthquake,2008 ( $M_w = 6.9$ ) (left) Cultrera et al. (2013) model , (right) Asano and Iwata (2011b) model



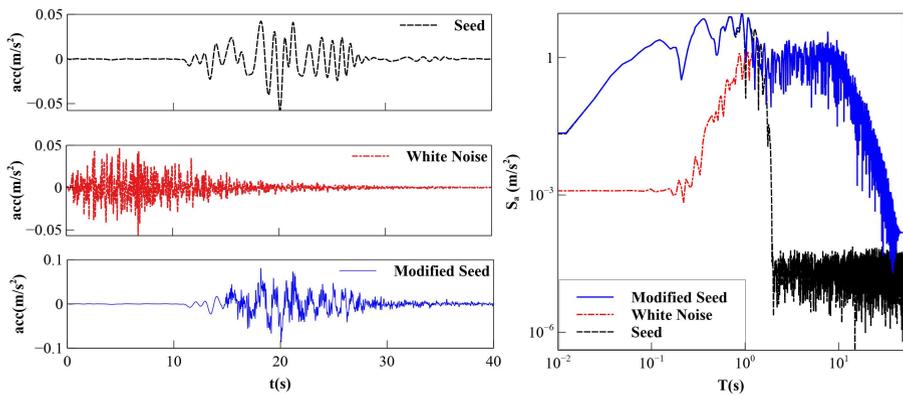
**Fig. 7:** Physics based input low-frequency ground motion for Iwate Earthquake, 2009 corresponding to different source models (Cultrera et al., 2013; Asano and Iwata, 2011b)



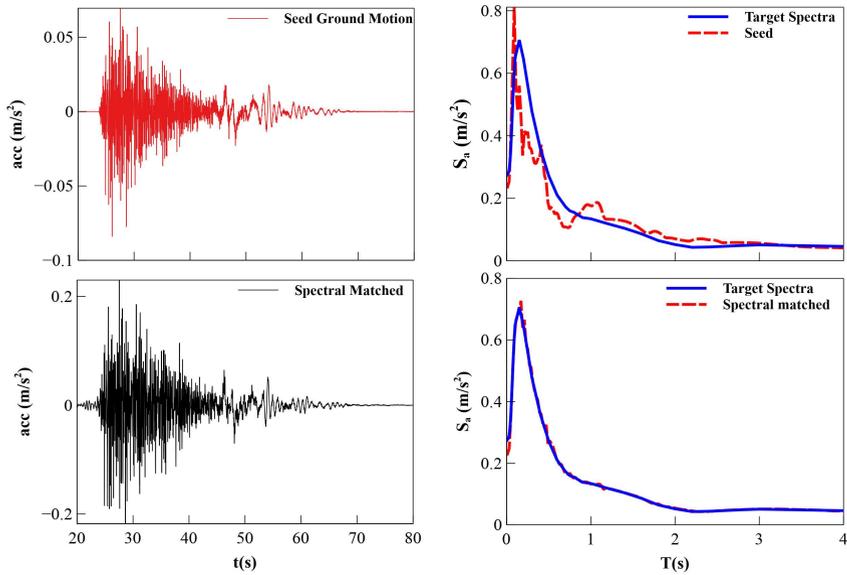
**Fig. 8:** Bias plots between recorded and simulated spectra for the ANN prediction models corresponding to fault normal and fault parallel components for Iwate Earthquake using the slip fields reported by Asano and Iwata (2011b) and Cultrera et al. (2013) respectively. Here, spectral acceleration corresponds to the PBS is in the higher period part ( $T^* = 0.75\text{-}4\text{s}$ ) and from the ANN models with the corresponding LF inputs for high frequency part ( $T^* < 0.75$ ). [Note: input variable for Model-1 were ( $M_w$ ,  $FM$ ,  $R_{rup}$ ,  $\log_{10}(R_{rup})$ ,  $\log_{10}(V_{s30})$ ,  $\log_{10}(Sa \geq T^*)$ ) and Model-2 were ( $\log_{10}(Sa \geq T^*)$ )]



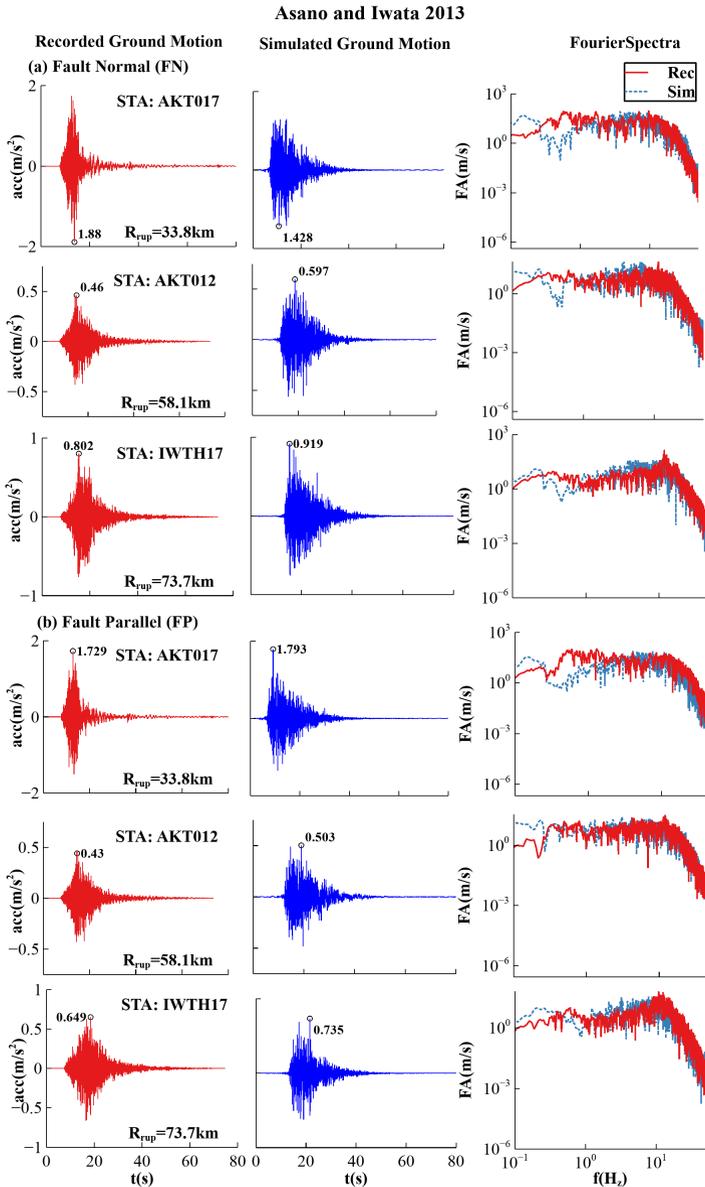
**Fig. 9:** Comparison plots between recorded, physics based simulation (PBS) and ANN models predicted response spectra at stations AKT017, AKT012 and IWT017 corresponding to Asano and Iwata (2011b) and Cultrera et al. (2013) rupture model



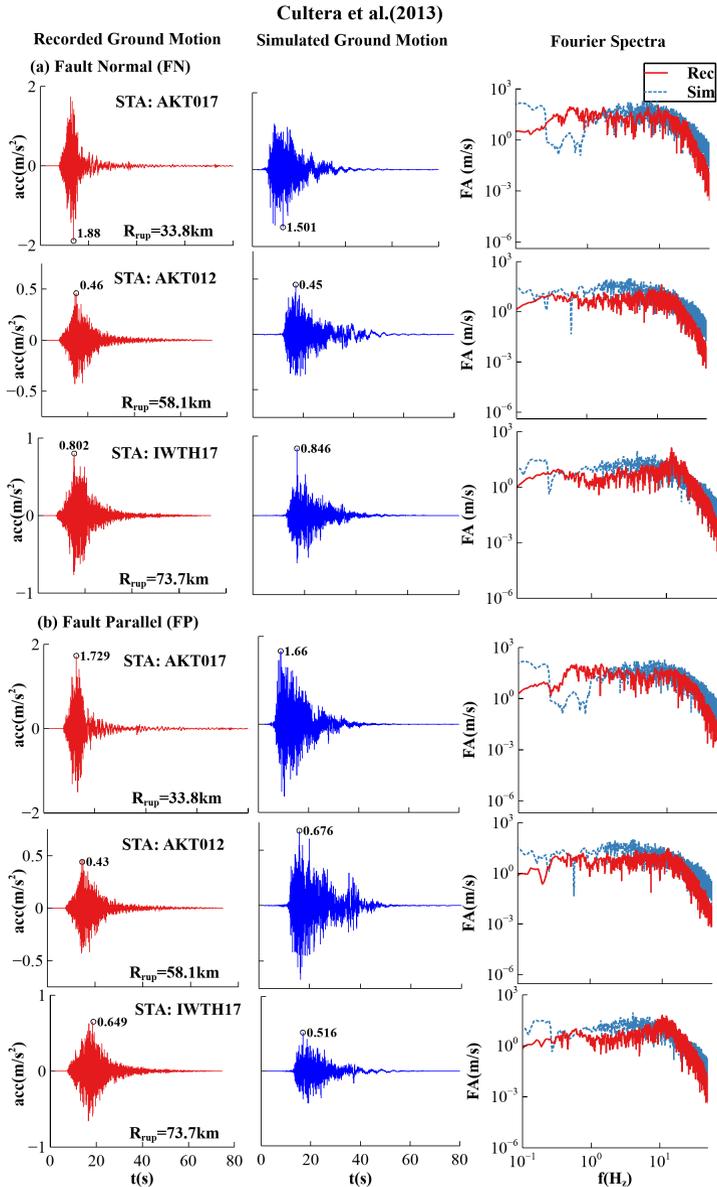
**Fig. 10:** Procedure for generation of modified seed from seed obtained from Physics Based Simulations (PBS) by addition of filtered white noise



**Fig. 11:** Spectral ordinate matching representation on the transformation of input seed ground motion signal to output signal that matches with the target spectra



**Fig. 12:** Time histories and Fourier amplitude plots for the simulated and recorded data corresponding to recording stations AKT017, AKT012 and IWT017 using Asano and Iwata (2011b) source model



**Fig. 13:** Time histories and Fourier amplitude plots for the simulated and recorded data corresponding to recording stations AKT017, AKT012 and IWTH17 using Cultrera et al. (2013) source model

**Table 1:** Statistics of the Best Performing ANN models corresponding to various cross-over periods using the with source and site parameters  $M_w$ ,  $FM$ ,  $R_{rup}$ ,  $\log_{10}(R_{rup})$ ,  $\log_{10}(V_{s30})$

No. of inputs	No. of outputs	Crossover Period (T*)	Transfer Function		Performance Parameters			
			I-H	H-O	$R$	$PP$	$MSE$	$\sigma_\epsilon$
24	14	0.5	tansig	purelin	0.9756	0.9518	0.0566	0.2379
21	17	0.75	tansig	purelin	0.9766	0.9537	0.0567	0.238
18	20	1	tansig	purelin	0.978	0.9564	0.0561	0.2369

**Table 2:** Source models detail of Iwate Earthquake,2008 ( $M_W$ -6.9) available from SRCMOD database

<b>S.No.</b>	<b>Source Parameter</b>	<b>Asano and Iwata (2011b)</b>	<b>Cultrera et al. (2013)</b>
<b>1</b>	<b>Fault Dimension</b>		
	Length (km)	38	42.66
	Width(km)	18	17.38
	Height from Top (m)	0.8	1.34
<b>2</b>	<b>Hypocentre Location</b>		
	Longitude (°)	39.030	39.027
	Latitude (°)	140.881	140.878
	Depth(km)	7.77	6.5
<b>3</b>	<b>Seismic Moment(Nm)</b>	2.76E+19	3.65E+19
<b>4</b>	<b>Strike(°)</b>	209	209
<b>5</b>	<b>Dip(°)</b>	51	40
<b>6</b>	<b>Rake(°)</b>	108.31	105
<b>7</b>	<b>Maximum Slip (m)</b>	5.942	6.36

**Table 3:** Velocity Profile considered for the physic based simulation of Iwate Earthquake,2008 ( $M_W$ -6.9)

Depth (km)	Vp(Km/s)	Vs(km/s)	Density (g/cm)
0	4.8	2.7	1.8
2	5.1	2.9	1.8
4	5.3	3	2.5
14	6.4	3.6	2.8
25	6.8	3.9	2.8
27	7	4	2.8
30	7.2	4.1	2.8

## Supplementary Files

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