

Multilayer perception and radial basis function models for predicting trends of rainfall in Asian megacity Dhaka, Bangladesh

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Research Article

Keywords: Multilayer perception neural network, Radial bias function neural network, multi-collinearity assessment, Dhaka

Posted Date: June 6th, 2022

DOI: <https://doi.org/10.21203/rs.3.rs-1720286/v1>

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1 **Multilayer perception and radial basis function models for predicting trends**
2 **of rainfall in Asian megacity Dhaka, Bangladesh**

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23
24
25 **Abstract**

26 Rainfall prediction is a fascinating topic, particularly in an urban city experiencing climate change;
27 it is also required for hydrologic system analysis and design. Most real-time rainfall prediction
28 algorithms use conceptual models that simulate the hydrological cycle in a changing climate.
29 However, calibration of “conceptual” or “physically based models” is typically challenging and
30 time-consuming due to the large number of variables and factors. Simpler “artificial neural network
31 (ANN)” predictions may thus seem promising. To this end, this study aimed to evaluate the
32 performance of two of the most commonly used ANN models, namely “Multilayer Perception
33 (MLP)” and “Radial Bias Function (RBF)”, by predicting the rainfall trend patterns in the mega
34 city of Dhaka, Bangladesh. In this perspective, rainfall is considered as a dependent variable and
35 the rest of the parameters are considered as independent variables for predicting the trends of
36 rainfall in this region. In the prediction models, fifteen conditioned atmospheric and meteorological
37 parameters were used, and the multi-collinearity of these parameters was checked by the “Variance
38 Inflation Factor” and “Tolerance” methods. The performance of the ANN models was evaluated
39 by comparing the predicted and residuals and also by using AOC and ROC curves. The importance
40 study from the MLP model revealed that PM₁₀, O₃, PM_{2.5}, NO_x, and wind speed are the highest
41 causal factors influencing the rainfall changes in Dhaka, Bangladesh. Though both ANN models
42 produced similar robustness in rainfall prediction, results showed that MLP performed well with
43 an AUC value of 0.941, compared to the RBF model with an AUC value of 0.915. Therefore, the
44 application of the MLP model can be suggested as an alternative to predict the pattern of rainfall
45 as well as meteorological and atmospheric variables based on historical recorded datasets.

46 **Keywords:** Multilayer perception neural network, Radial bias function neural network, multi-
47 collinearity assessment, Dhaka

48 **1. Introduction**

49 Changing patterns of rainfall have a direct impact on water supplies since they are an essential
50 aspect of the hydrological cycle (Islam et al., 2012). Water resource managers and hydrologists are
51 increasingly concerned about the impact of climate change on rainfall patterns (Jhajharia et al.
52 2014; Gajbhiye et al., 2015). The variations in rainfall quantity and frequency directly affect the
53 stream flow pattern, the allocation of run-off, ground water reserves, and soil moisture (Srivastava
54 et al., 2014; Islam et al., 2022). Because of the significant variations in the rainfall pattern, drought
55 and flood-like hazardous occurrences might occur on a regular basis (Srivastava et al., 2015). As a
56 result, the most important approach to long-term water resource management is studying how
57 rainfall patterns and distribution are changing as a result of climate change. Precipitation patterns
58 are crucial in an ever-changing environment for making better decisions and improving
59 communities' capacity to survive significant weather events. If the air humidity is high and
60 profound and significant convection develops, surface rainfall is due to intensify even more at
61 increased aerosol concentrations. Greater urban surface area is unlikely to have a significant
62 influence on urban-induced rainfall. Larger urban areas, on the other hand, can interrupt or split
63 precipitation convection structures that originate outside cities and pass over them. Rainfall over
64 and/or leeward of cities can be increased or decreased by these urban-modified rainfall patterns.
65 Due to human activity, aerosols have a variety of sizes and chemical compounds that are discharged
66 into the urban atmosphere. Anthropogenic aerosols, in combination with toxic gases, degrade urban
67 air quality and are detrimental to human health. In hydrological and climatological research and
68 practice, the pattern of rainfall is a crucial input and a critical concern (Sangati and Borga 2009;
69 Islam et al. 2012). Hydrological modeling and drainage system design need this data, as does flood
70 forecasting (Lagouvardos et al. 2013). As a result, examining the changes in trend and presence of
71 a trend in rainfall is one of the most important areas of hydrology, climatology, and meteorology
72 research throughout the world (Islam et al., 2012; Chatterjee et al., 2016; Tian et al., 2017; Talae,

73 2014). Statistical tests such as "regression" (Piao et al., 2010), the "Mann–Kendall" test (Mann,
74 1945), the "Kendall rank correlation" test (Kendall, 1995), "Sen's slope estimation" (Pingale, 2014),
75 and the "Spearman rank correlation" test (McGhee, 1985) have all been used in the majority of
76 investigations. The Mann-Kendall test was used in this investigation since it is one of the most
77 frequently used worldwide techniques for trend identification in hydrology, climatology, and
78 meteorology (Batisani and Yarnal, 2010; Du and Shi, 2012; Singh, 2008; Islam et al. 2019).

79 For planners, predicting the future is more helpful than trend research because it allows them to
80 prepare for future climatic changes, which are more likely to occur. In addition to the complex
81 global climate model, statistical approaches and machine learning techniques (Darji et al. 2015)
82 might be used for regional predicting of climatic variables in the future. A significant number of
83 databases, a high-configuration system, modern technology, and a technical specialist are needed
84 to run the physical models. There is no substitute for physical models in terms of efficiency or cost.
85 A number of statistical approaches have restrictions, such as the "auto regressive (AR)" model
86 regresses past values, while the "moving average (MA)" model employs past error as the
87 explanatory factor, and the "auto regressive moving average (ARMA)" model can only be
88 performed for stationary time series data. Recent work has focused on the implementation of AI
89 models such as machine learning techniques (Pal and Talukdar 2020). Due to the fact that it doesn't
90 need a lot of information yet can handle complex and large data sets if given, AI models perform
91 quite well.

92 Artificial neural network (ANN) has been extensively applied in various fields of water resource
93 planning and management as well as environmental research. It is possible to construct an ANN
94 by using several linked or weighted processing elements (PEs) or neurons, which are then
95 assembled into layers and interconnected. Data is fed into the input layer and processed by the

96 network until an output is generated at the end of its path. It is via these weighted connections that
97 each neuron receives several inputs from its neighboring neurons. The total of these weighted
98 inputs plus the addition of a standard cutoff generates the argument for a transfer function (often
99 "linear," "logistic," or "hyperbolic tangent"), which in turn provides the final output of the neuron.
100 According to Darji et al. (2015), a thorough study on the use of neural networks for rainfall
101 forecasting, back propagation based neural networks perform well. Rather than relying on a single
102 technique, we built a neural network around the "multilayer perception algorithm (MLP)" and
103 "Radial Basis Function (RBF)". The MLP and RBF-based ANNs use a back propagation technique
104 for their computations. The use of MLP-RBF-based ANN is becoming more popular because of
105 the high reliability of their findings in predicting a wide range of hydrological and climatic events
106 (Memarian & Balasundram, 2012; Samantarayet al., 2020; Liu, 2019). In the current study, MLP
107 and RBF models were applied to predict the trends of rainfall in the Asian mega city of Dhaka,
108 Bangladesh.

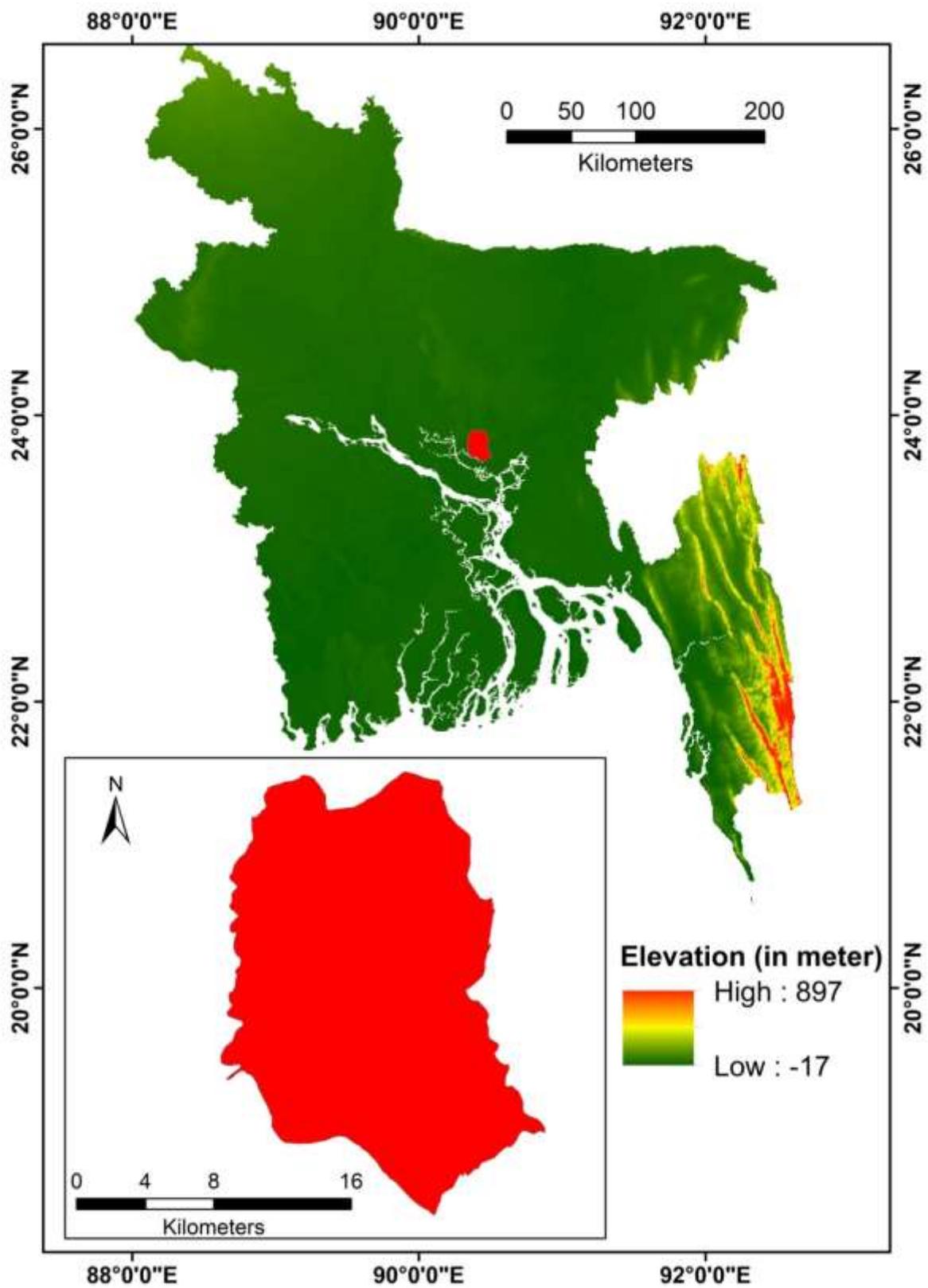
109 **2. Materials and methods**

110 **2.1. Study area**

111 Bangladesh is a low-lying, riverine country that is one of the most densely populated in the South
112 Asian region. It has a 580 km long coastline along the Bay of Bengal. The climate of this country
113 is a subtropical monsoon, with moderately warm temperatures, seasonal rainfall variations, and
114 increased relative humidity. Bangladesh's summer (March to June), monsoon (June to October),
115 and winter (October to March) are generally recognized as distinct seasons of Bangladesh (Mallick
116 et al. 2022). Heavy rainfall is one of the main climatic characteristics of Bangladesh because of its
117 geographical location in the southern corner of the foothills of the Himalayas. The monsoon season
118 brings 80% of the country's total rainfall. The monsoons are caused by differences in air pressure

119 caused by the differential heating of land and sea in Bangladesh. Annual rainfall has ranged
120 between 32,800 mm and 47,800 mm per year over the last 50 years (Fattah and Morshed, 2022).

121 Dhaka, the capital city of Bangladesh (Figure 1), is one of the fastest-growing megacities in the
122 world and has been chosen as a study area in this research. Dhaka district is located between north
123 latitudes 23°53' and 24°06' and the east longitudes of 90°01' and 90°37'. It is the world's eighth-
124 largest and fourth-most densely populated city, with 8.9 million residents in the main city (Dhaka
125 Metropolitan Area) and around 21.7 million in the entire Dhaka (Faisal et al. 2021). According to
126 the Köppen climatic classification, the city has a tropical savanna climate and a distinct monsoonal
127 season. With a distinct monsoonal season, temperatures range from 19°C in January to 29°C in
128 May. Between May and October, nearly 87 percent of the average annual rainfall (2,123 mm) falls.
129 Rapid population growth, unplanned urbanization, and industrialization have led to an increase in
130 urban activities in Dhaka City, which has been affecting the climate as well as the environment
131 (Chowdhury et al. 2021). Moreover, the geographical location of the city (lower reaches of the
132 Ganges Delta) and the flat land close to sea level leave the city susceptible to flooding, especially
133 in the rainy season due to heavy rainfall. Though the city's residents have faced water logging
134 problems in recent years, the ground water level of Dhaka City is declining at a rate of 2-3 m/year
135 due to less rainfall in other seasons and excessive settlement and population growth (Mamoon et
136 al. 2020).



137

138 **Figure 1** Location map showing the study area

139 **2.2. Database and quality check**

140 The amount of rainfall in any geographical location is affected by many atmospheric conditions,
141 including air pollutants (SO₂, PM_{2.5}, PM₁₀, O₃, NO_x, NO, NO₂, CO) and meteorological factors
142 such as "air temperature, solar radiation, relative humidity, wind speed, wind direction". To predict
143 the rainfall, change pattern in our study area, we have collected the atmospheric data from the
144 "Ministry of Environment", and the meteorological data from the "Bangladesh Meteorological
145 Department (BMD)". The quality control of the datasets was checked by BMD staff.

146

147 **2.3. Methodology**

148 As given Fig. 2, the process of predicting rainfall trend pattern consists of the following steps:

- 149 1. Input of air quality and meteorological parameters
- 150 2. Pre-processing of the input dataset
- 151 3. Building ANNs model with training (70%)
- 152 4. Validating ANNs model with testing (30%)
- 153 5. Importance of variable analysis by ANNs model
- 154 6. Evaluating the model by the taking difference between predicted and residual outputs

155

156

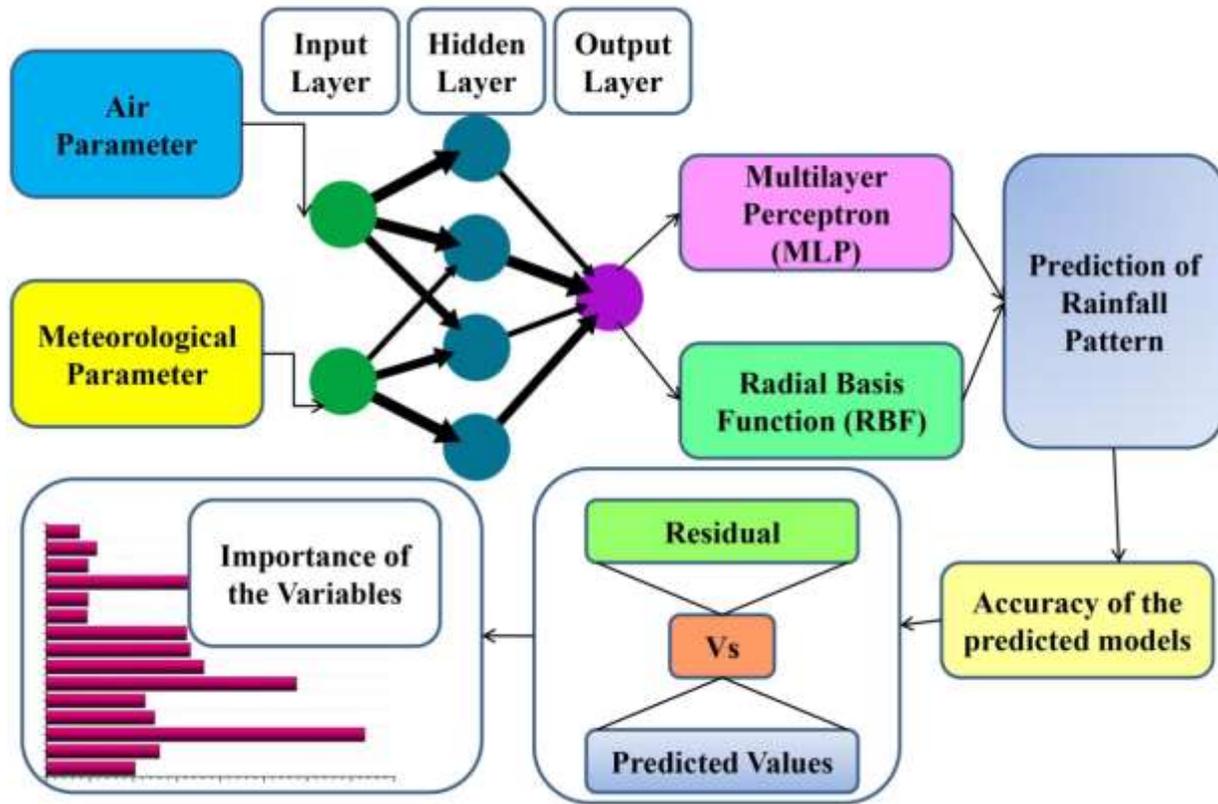


Figure 2 Flow Chart adopted for the current study

157

158

159

160 2.4. Trends of rainfall prediction

161 Multilayer Perception

162 The ANN is a machine learning-based computing method of the biological brain. The ANN-based
 163 Multilayer Perception (MLP) model is considered the most popular model in feedforward networks
 164 (Kuo et al. 2007, Hanoon et al. 2021). The MLP model is a set of organized, interconnected layers
 165 or nodes, namely “input”, “hidden”, and “output layers”. The data is delivered in the input layer,
 166 and the neurons in the input layer transfer the weighted data to the hidden layers with the randomly
 167 set bias. A transfer function is used to generate an output response at the node after determining
 168 the net sum at the hidden node (Hanoon et al. 2021; Memarian and Balasundram, 2012).

169 In this study we have used two activation function namely hyperbolic tangent function (HTF) and
 170 the logistic function (LF). The HTF ranges between -1 and $+1$ while the LF ranges between 0 and
 171 $+1$. The two equations are expressed as follows:

$$172 \quad \phi(y_i) = \tanh(\mathbf{w}_i) \quad (1)$$

$$173 \quad \phi(y_i) = (1 + e^{-\mathbf{w}_i})^{-1} \quad (2)$$

174 Here y_i denotes “the outcome of the i^{th} neuron, \mathbf{w}_i denotes the total weight of the input neurons.
 175 The equation 1 represents the HTF and equation 2 represents the LF”.

176 The MLP network was trained using an error corrective learning approach. The desired output must
 177 be known in this technique. The instantaneous error ($\varepsilon_i(n)$) is defined as “the difference between
 178 the desired response $\delta_i(n)$, and the system response at PE i at iteration n , $y_i(n)$ ”.

$$179 \quad \varepsilon_i(n) = \delta_i(n) - y_i(n) \quad (3)$$

180
 181 Each weight in the network can be updated using gradient descent learning theory. The weights
 182 update processing could take place after each training pattern has been presented, or after full sets
 183 of training patterns have been presented. A training epoch is deemed complete in both
 184 circumstances when each training pattern has been presented to the MLP once. Even in simple
 185 things, an accurate MLP needs to be well-trained for many epochs. The change of weight can be
 186 calculated by the “back propagation algorithm (equation 4) of momentum learning, which helps to
 187 calculate a cost function's sensitivity with respect to each weight in the MLP network and then
 188 updates each weight according to the sensitivity” (Behrang et al. 2010).

$$189 \quad w_{ij}(n + 1) = \mathbf{w}_{ij}(n) + \partial \left(\mathbf{w}_{ij}(n) - \mathbf{w}_{ij}(n - 1) \right) + \eta \varepsilon_i(n) \mathbf{x}_j \quad (4)$$

190 Here, “ ∂ = Momentum, η = step size, $\varepsilon_i(n)$ = local error/ instantaneous error”.

191 **Radial Basis Function**

192 The “Radial bias function neural network (RBFNN)” is a non-normalized method of the Gaussian
193 distribution nonlinear-function with a lot of excellent features for better learning. Nonlinear
194 dynamic systems can also be learned, identified, synchronized, and controlled using Gaussian
195 neural networks (Gholamreza et al. 2016).To solve the problems more intelligently the RBFNN
196 model is used and it is expected to execute more precise simulations even in complex situation
197 (Gholami et al. 2019). The architecture of the adopted RBFNN in this study is presented in Figure
198 6. This model is made up of three layers: input, hidden/radial basis, and output, all of which are
199 made up of neurons or nodes. The input layer work as the container of input variables, radial layer
200 contains the function of the radial basis. The output layer is linked with the radial basis nodes by
201 linear weights and shows the output of the problem (Mustafa et al. 2012).

202 In Figure 6, the notation SO₂, PM_{2.5}, PM₁₀, O₃, NO_x, NO, NO₂, CO, V_wind_speed represents
203 the input layers, H(1), H(2), H(3),..... H(10) represents the hidden layers contains the radial basis
204 function, and the Rain is the output layer. If we represent the output as R, the relation between the
205 input variables and output for the i^{th} radial basis layer of the RBFNN model is as follows:

$$206 \quad R(\mathbf{x}) = w_o + \sum_{i=1}^N W_i \times H_i(\mathbf{x}) \quad (5)(5)$$

207 Here, $R(\mathbf{x})$ denotes “the output of the input vector \mathbf{x} , H_i denotes the basis function, w_o denotes the
208 bias, W_i denotes the linear weight between the output layer and the hidden layer, N denotes the
209 number of neurons in the radial basis node”.

210 The basis function $H_i(\mathbf{x})$ is the normalized-Gaussian function which is shown in following:

$$211 \quad H_i(\mathbf{x}) = \exp\left(-\frac{\|\mathbf{x}-\phi_i\|^2}{2\sigma_i^2}\right) \quad (6) \quad (6)$$

212

213 Here, $\|\cdot\|$ represents “the Euclidean distance, ∂i are width parameter and \emptyset_i is the center parameter
214 of the basis function which was obtained by using random sampling method (Broomhead and
215 Lowe, 1988) of the input data. $H_i(\mathbf{x})$ ”. The matrix form of the equation 6 can be expressed by
216 equation 7.

$$217 \quad R(\mathbf{x}) = \mathbf{w}H \quad (7)$$

218 Here, \mathbf{w} = Weight vector.

219 For training the RBFNN model, two steps are followed. Firstly, established the width/ spread (∂)
220 and the centre \emptyset of the basis function from the input layer. After that adjusted the weights \mathbf{w} in
221 order to reduce the error function (ε) by using equation 8.

222

$$223 \quad \varepsilon = 0.5 \sum_{j=1}^M \sum_{i=1}^N [R_i(\mathbf{x}_j) - T_{ij}]^2 \quad (8)$$

224 Here, “ $R_i(\mathbf{x}_j)$ denotes the network output and T_{ij} denotes the target”.

225 Using the normalization technique of spread/ width (∂) determination, the spread of the basis
226 function (∂) was calculated, after the establishment of the centre of the basis function (\emptyset). The
227 equation for ∂i is expressed as:

$$228 \quad \partial i = 2 \sum_{j=1}^{N_p} \frac{|\delta_{j=1} - \delta_j|}{N_p} \quad (9)$$

229 Here, “ N_p = Number of centers of basis function, $\delta_{j=1}$ and δ_j denotes the successive centers of the
230 basis functions. The network weights (\mathbf{w}) were estimated using the pseudo-inverse equation once
231 the basis function's center and spread were determined” (Bishop, 1995).

232
$$\mathbf{w}^t = [\boldsymbol{\phi}^t \boldsymbol{\phi}]^{-1} \times \boldsymbol{\phi}^t \times \mathbf{T} \quad (10)$$

233 Here, $\mathbf{T} = [T_{ij}]$, $\boldsymbol{\phi} = H_i(\mathbf{x})$

234 **Multi-collinearity assessment**

235 In regression related research, collinearity means the non-independence of predictor variables. To
236 identify the multi-collinearity among the input variables of the prediction model of this study, we
237 used two collinearity-diagnostic factors, known as Variance Inflation Factor (VIF) and Tolerance.
238 They are calculated as:

239
$$Tolerance = 1 - R^2 \quad (11)$$

240
$$VIF = (1 - R^2)^{-1} = Tolerance^{-1} \quad (12)$$

241 The VIF is the inverse of tolerance (1/Tolerance), and the value of VIF is always ≥ 1 . VIF values
242 more than 10 are frequently interpreted as showing multi-collinearity, $1 < VIF < 5$ indicates
243 moderate correlation among variables, and $VIF \geq 5$ indicates multi-collinearity among the
244 variables. $VIF > 10$ means that regression coefficients aren't very well estimated when there is a
245 lot of multi-collinearities in the data (Talukdar et al. 2021; Shrestha, 2020).

246 **Model assessment**

247 In machine learning, the evaluation of the performance of the models is one of the most essential
248 tasks. The performance of the MLP and RBFNN models was evaluated by using the "receiver
249 operating characteristic (ROC)" curve and the area under the ROC curve (AUC). The ROC and
250 AUC are popular tools for evaluating the performance of binary classifiers. The value of AOC is
251 near to 1, which indicates excellent measures, while close to 0 indicates the worst measures. When
252 the AUC is 0.5, the model has no capacity for class separation (Namdar et al. 2021).

253 **3. Results**

254 **3.1. Multi-collinearity assessment**

255 VIF and tolerances were utilized in this research to identify multi-collinearity among independent
256 variables. Talukdar et al. (2021) report that if the VIF score is more than 10 and the tolerance value
257 is less than 0.2, it's a problem. As found by the findings of the multi-collinearity test, most of the
258 components have VIF and tolerance values of less than 10 and more than 0.2, respectively (Table
259 1). As a result, multi-collinearity between independent variables is not an issue. In the present
260 research, all fifteen conditioning factors were employed to predict rainfall trends.

261
262
263

Table 1 Results of multi-collinearity test

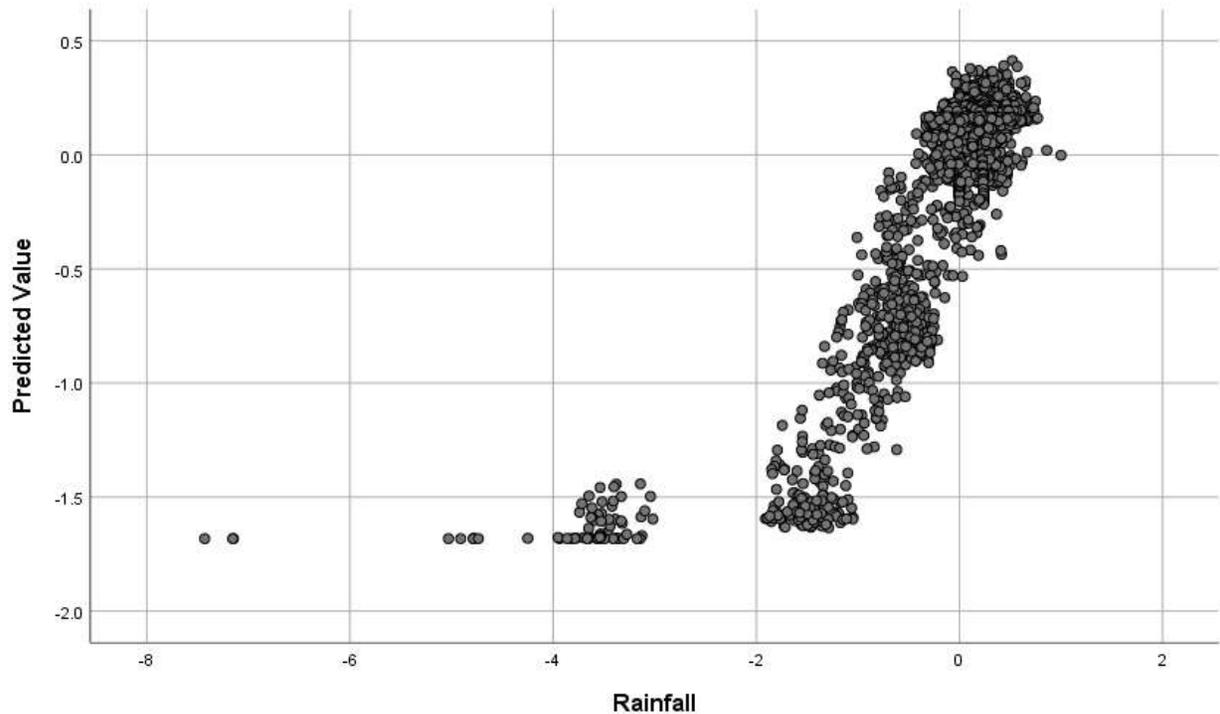
Parameters	Collinearity Statistics	
	Tolerance	VIF
SO2	0.36	2.79
NO	0.77	1.28
NO2	0.84	1.18
NOX	0.20	4.93
CO	0.55	1.83
O3	0.55	1.81
PM2.5	0.66	1.49
PM10	0.20	4.93
Wind Speed	0.43	2.33
Wind Direction	0.31	3.24
Temperature	0.66	1.52
RH	0.71	1.39
Solar Radiation	0.57	1.76
BP	0.78	1.28
V_Wind_Speed	0.65	1.53

264
265

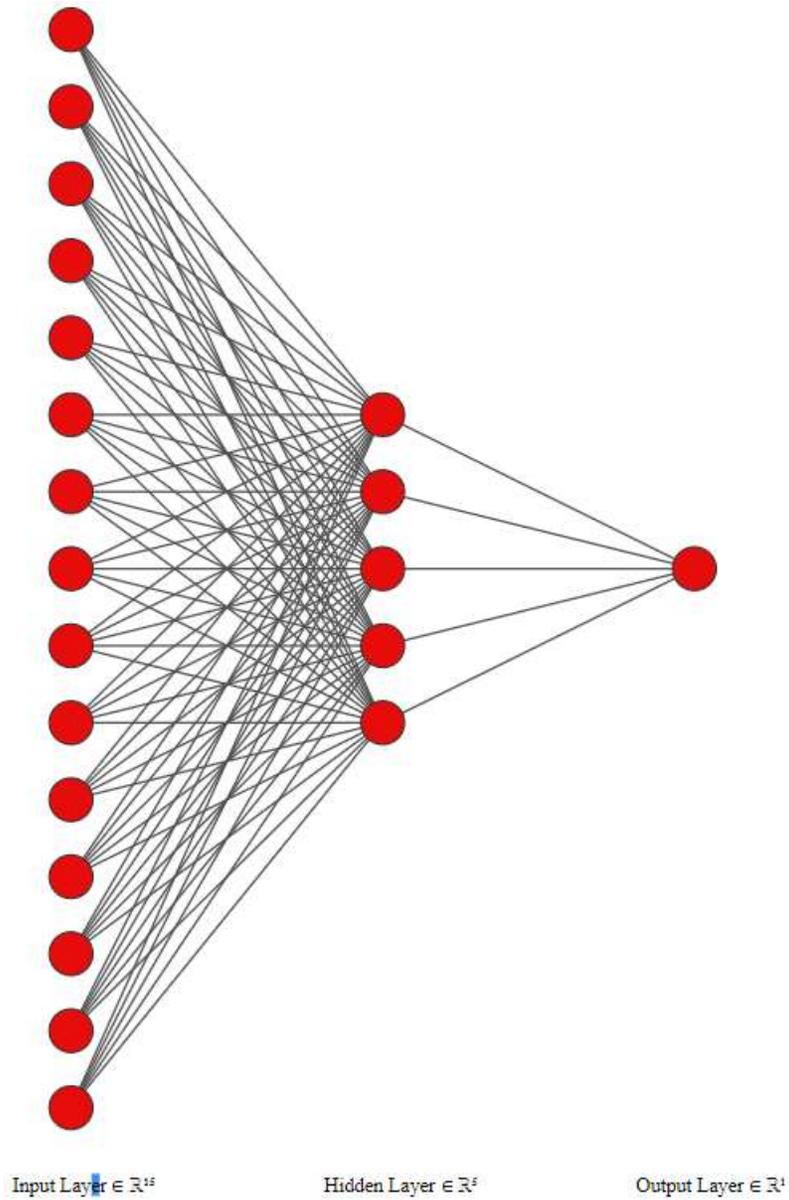
266 **3.2. Trends of rainfall pattern**

267 The predicted and actual rainfall in the MLP classifier were plotted and shown in Figure 3. The
268 plot illustrates that the expected values are proportional to observed values, and the majority of the
269 observed and predicted values show positive trends and good agreement with the perfect line of

270 agreement. The MLP model behaved well and effectively decreased network errors to provide
271 predicted values that were very close to the observed data.



272
273 **Figure 3** Comparison between predicted and actual rainfall in MLP classifier.
274 Figure 4 illustrates the structure of the neural network in the MLP classifier. Conditioning variables
275 were used as inputs in the model, and fifteen units were used in the input layers. The number of
276 hidden levels in the MLP model was determined to be one, with five units in each hidden layer.
277 The activation function in the hidden layer was a hyperbolic tangent for the model. The model's
278 output was rainfall, and the output layer's activation function was identity. For training data, the
279 Sum of Squares Error and Relative Error were found to be 6741.319 and 0.341, respectively. On
280 the other hand, Sum of Squares Error and Relative Error were both determined to be 2032.520 and
281 0.301 for the testing data.



282

283

Figure 4 Structure of the neural network in MLP classifier.

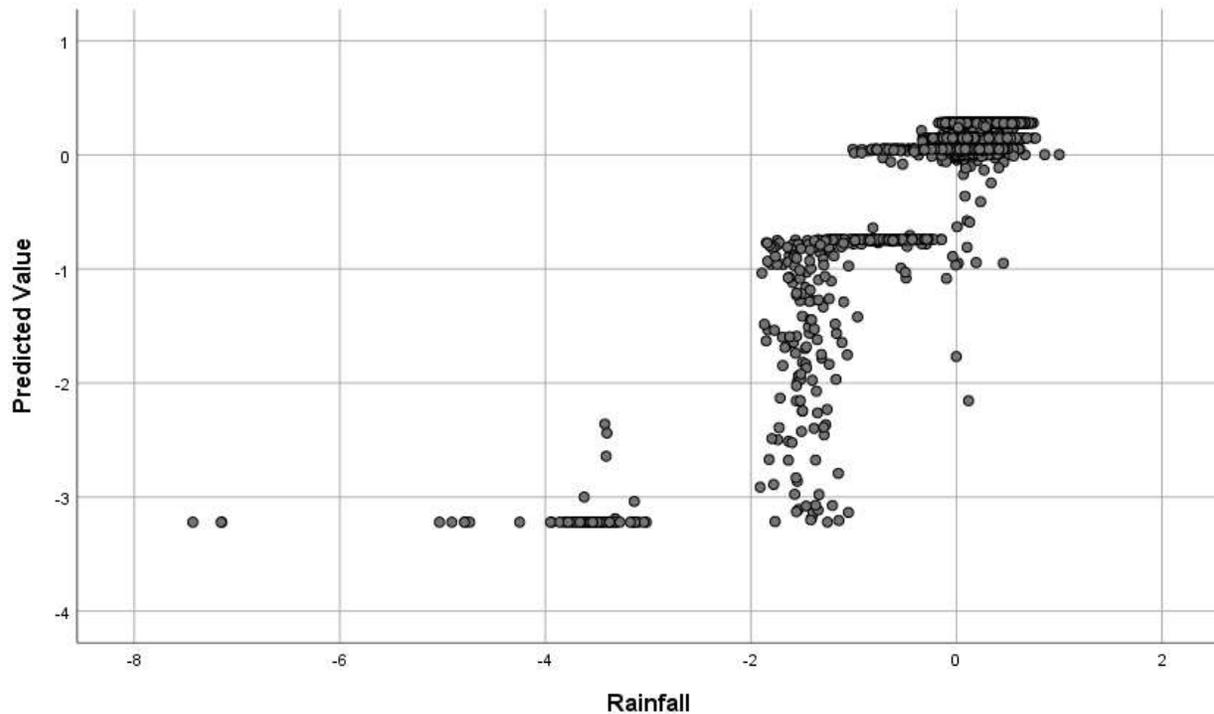
284

285 Figure 5 depicts the comparison between the projected and observed rainfall based on the RBF

286 classifier. Between all of the observed and projected data, a perfect line of agreement could be

287 established. The concordance between predicted and observed data during testing may demonstrate

288 the RBF model's ability to generalise successfully. The RBF model performed well, with network
289 defects reduced to levels that were very near to those seen in the actual data.

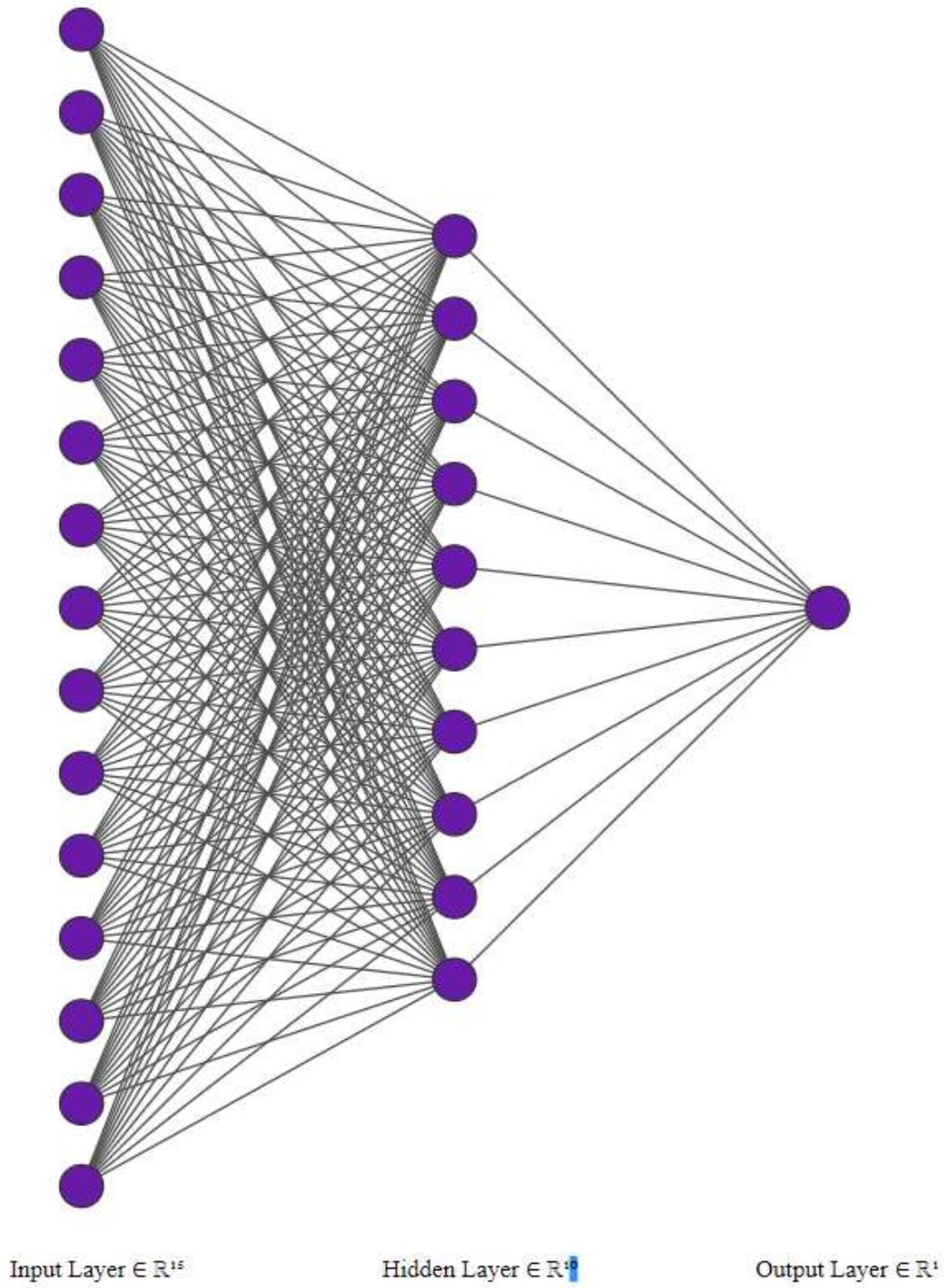


290

291 **Figure 5** Comparison between predicted and actual rainfall in RBF classifier.

292 The architecture of the neural network used in the RBF classifier is shown in Figure 6. Model
293 inputs were provided through conditioning variables, and fifteen units were employed in the
294 model's initialization and initialization layers. The number of hidden levels in the RBF model was
295 discovered to be ten, and the number of units in each hidden layer was determined to be one. The
296 number of hidden units is the one that yields the smallest error in the testing data. The activation
297 function in the hidden layer was a Softmax for the model, which was used to create the model.
298 Rainfall was the model's output, and the activation function in the output layer was the same as the
299 model's activation function. The Sum of Squares Error and the Relative Error for training data were
300 determined to be 4092.408 and 0.207, respectively, for the training data. The Sum of Squares Error

301 and the Relative Error, on the other hand, were both judged to be 1457.757 and 0.207 for the testing
302 data, respectively.

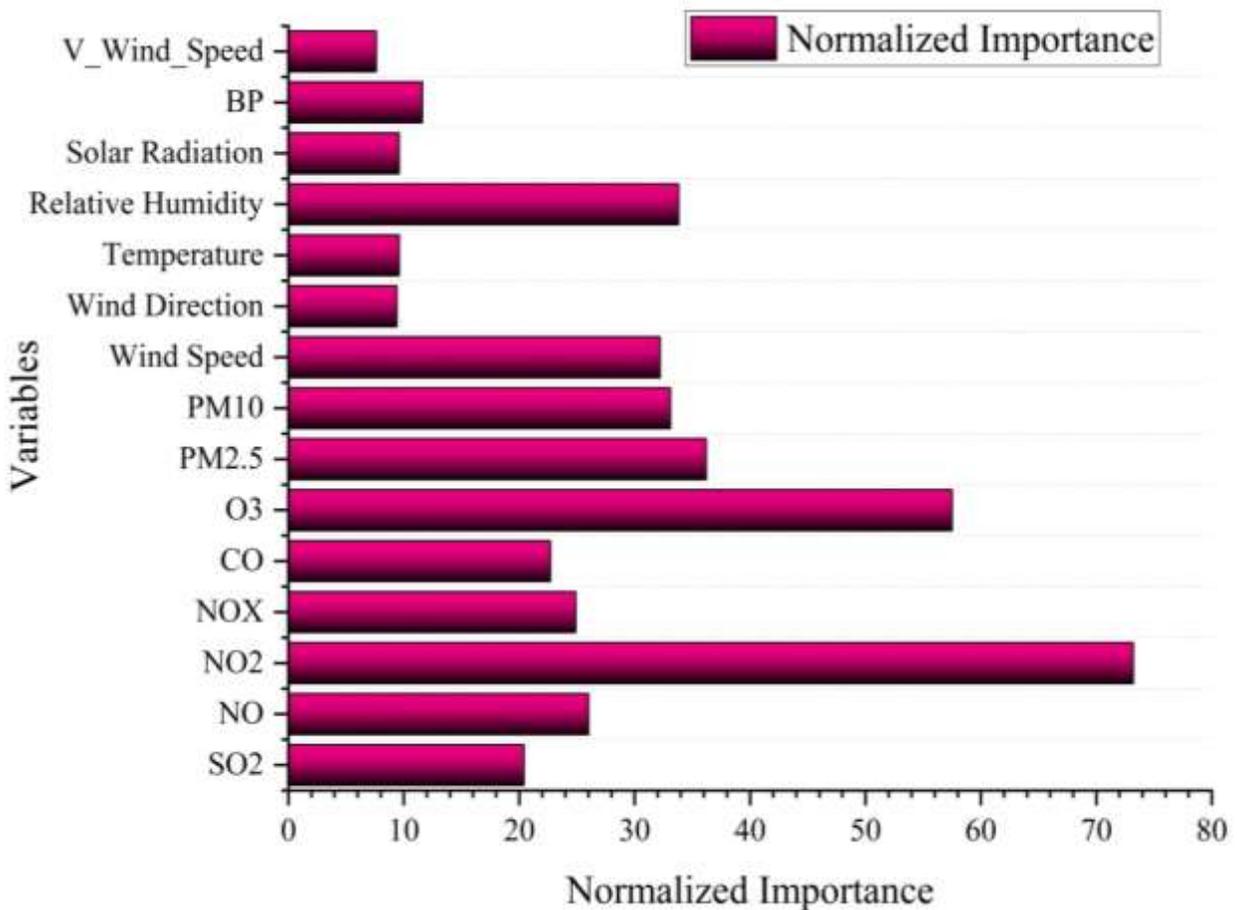


303

304 **Figure 6** Structure of the neural network in RBF classifier.

305 **3.3. Importance of the variables**

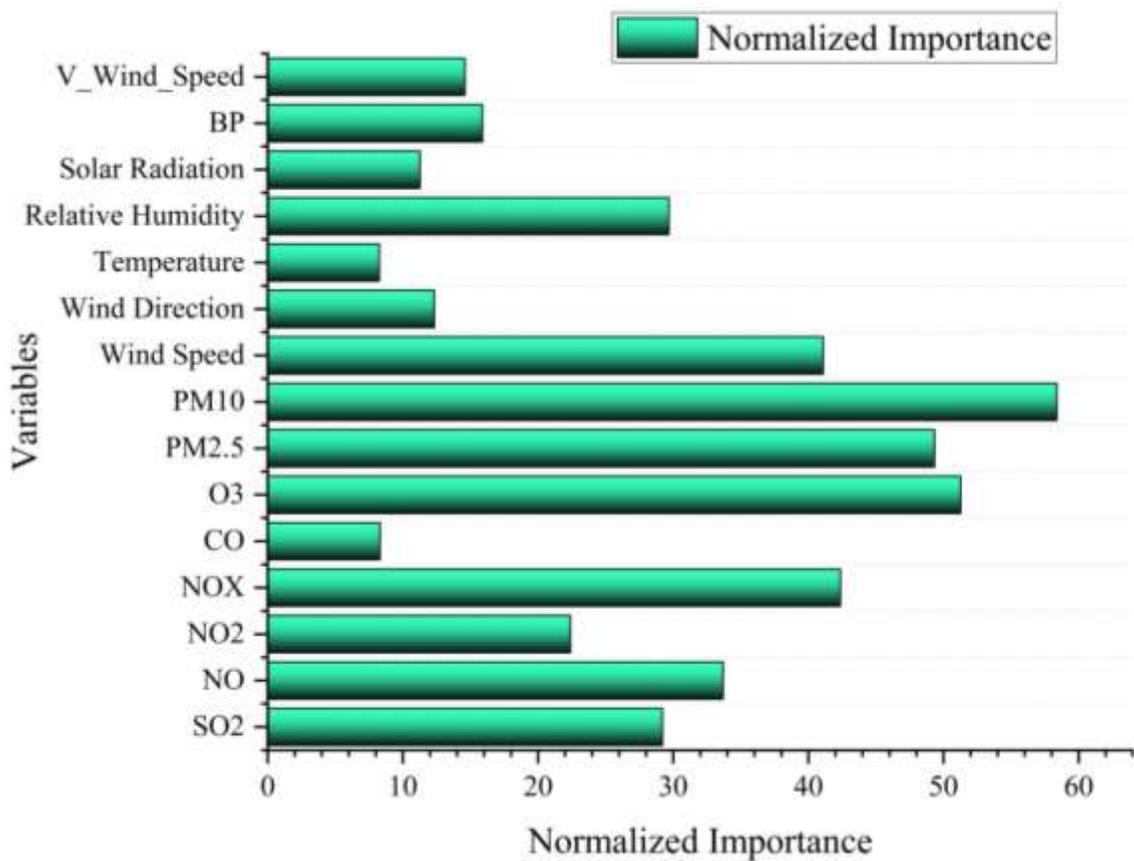
306 The normalized importance of the conditioning variables in the MLP classifier is shown in Figure
307 7. The highest order of importance was found for PM₁₀ (58.39), followed by O₃ (51.26), PM_{2.5}
308 (49.33), NO_x (42.37) and wind speed (41.1). Temperature and CO, on the other hand, were shown
309 to have normalised importance of 8.26 and 8.3, respectively. According to the classification, 2, 4,
310 3, 1, 3, 2 variables were found for 0-10, 10-20, 20-30, 30-40, 40-50 and 50-60 normalized
311 importance classes, respectively.



312

313 **Figure 7** Importance of the variables in MLP classifier.

314 Figure 8 depicts the normalized importance of the conditioning variables in the RBF classifier with
 315 respect to each other. PM₁₀ was shown to be the most significant component for predicting the
 316 trends of rainfall pattern. O₃, PM_{2.5}, NO_x, and wind speed were also influential component for the
 317 prediction under RBL model. Temperature, CO, solar radiation and wind direction were found the
 318 less important variables.



319

Figure 8 Importance of the variables in RBF classifier.

320

321

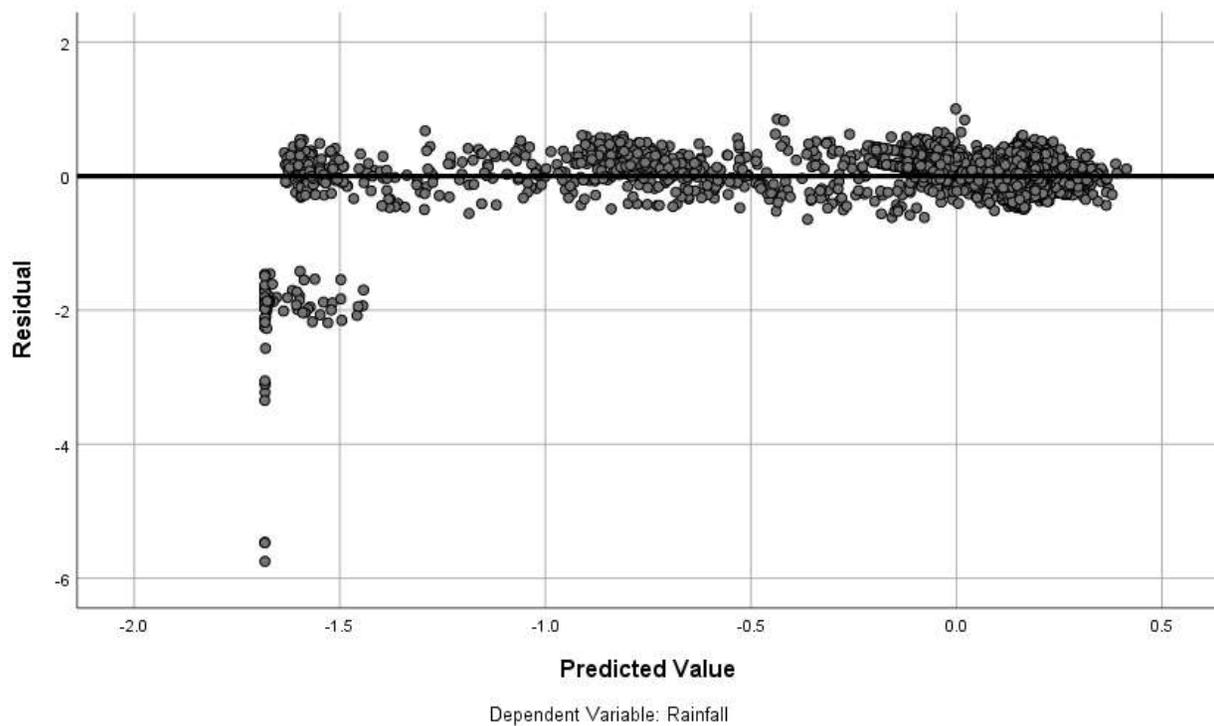
322 3.4. Accuracy of the predicted models

323 The predicted and residual values in the MLP classifier were plotted as shown in Figure 9. As seen

324 in the plot, the majority of the values were close to the zero values. The MLP model showed higher

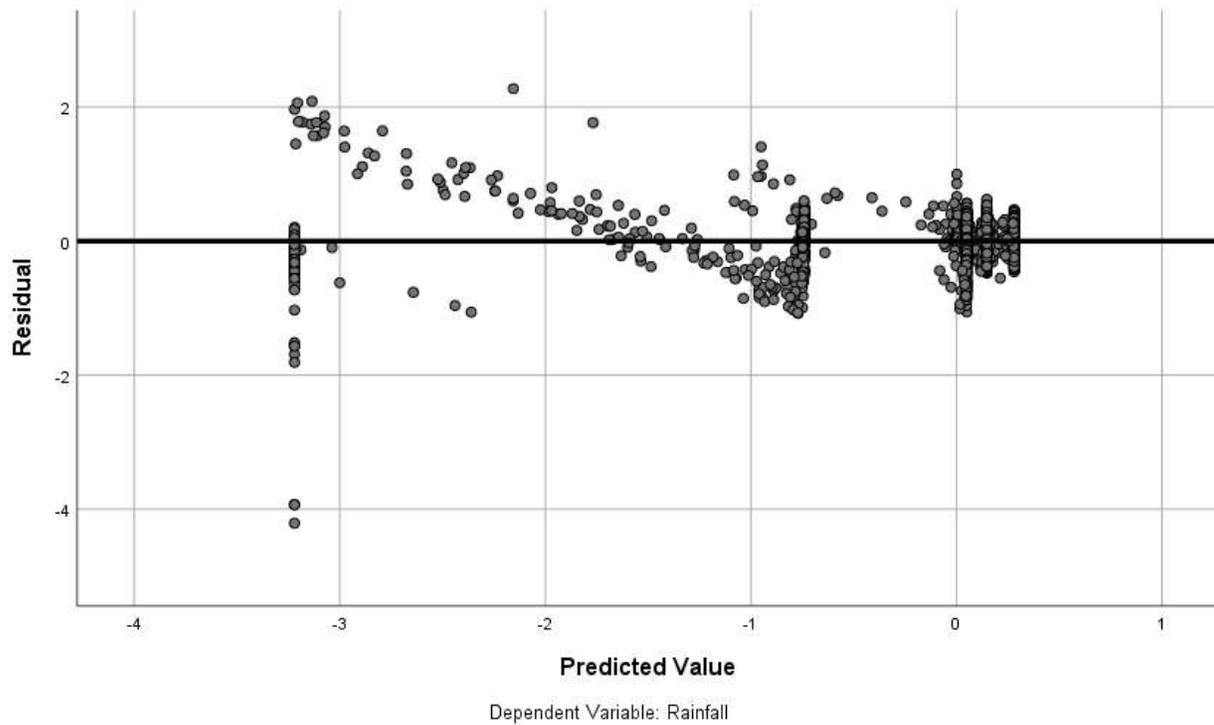
325 accuracy in predicting the rainfall trend and reduced the network error to deliver results that were
326 very close to the desired ones.

327 Figure 10 depicts a visualization of the predicted and residual values in the RBF classifier. The
328 vast majority of the values were in the area of zero, as seen in the plot. While the MLP model also
329 demonstrated more accuracy in predicting the rainfall pattern, it also showed lower network error,
330 resulting in results that were very close to the anticipated ones.



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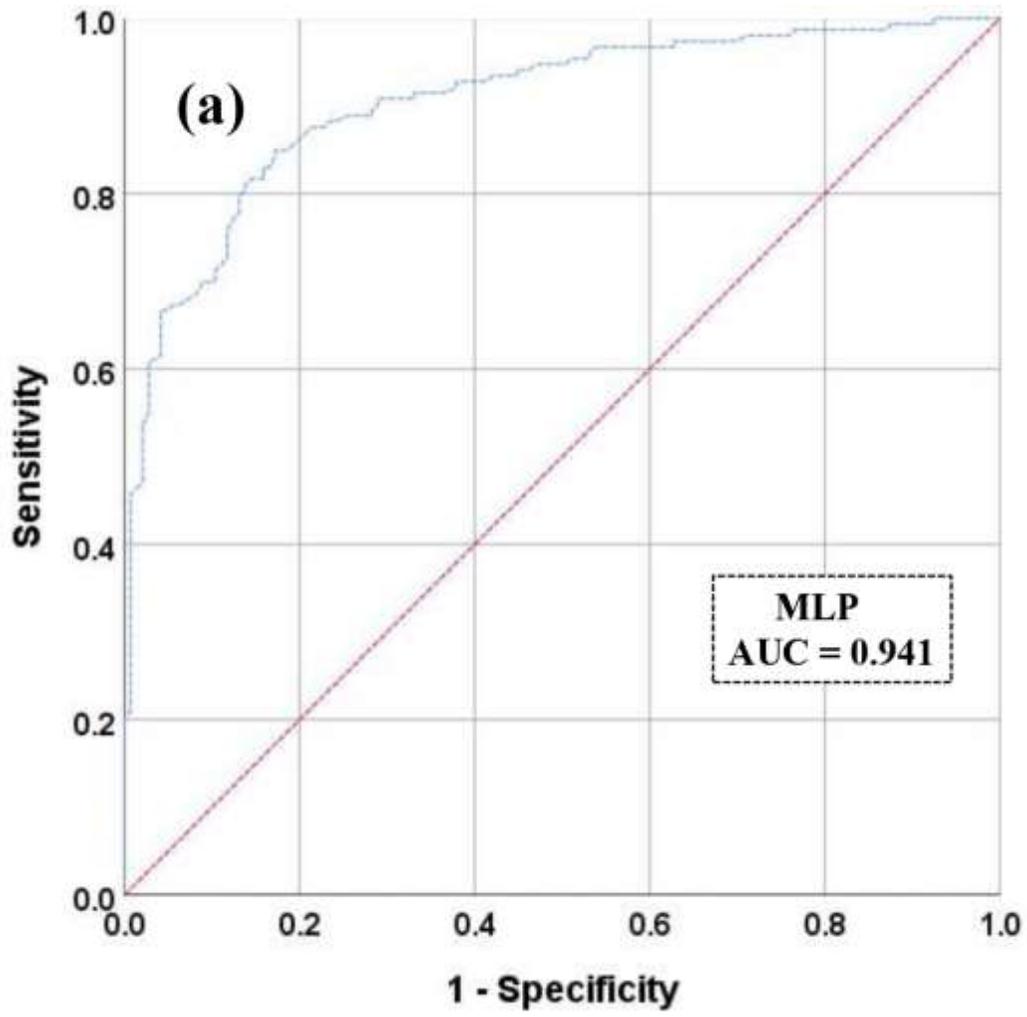
Figure 9 Accuracy of the MLP classifier.



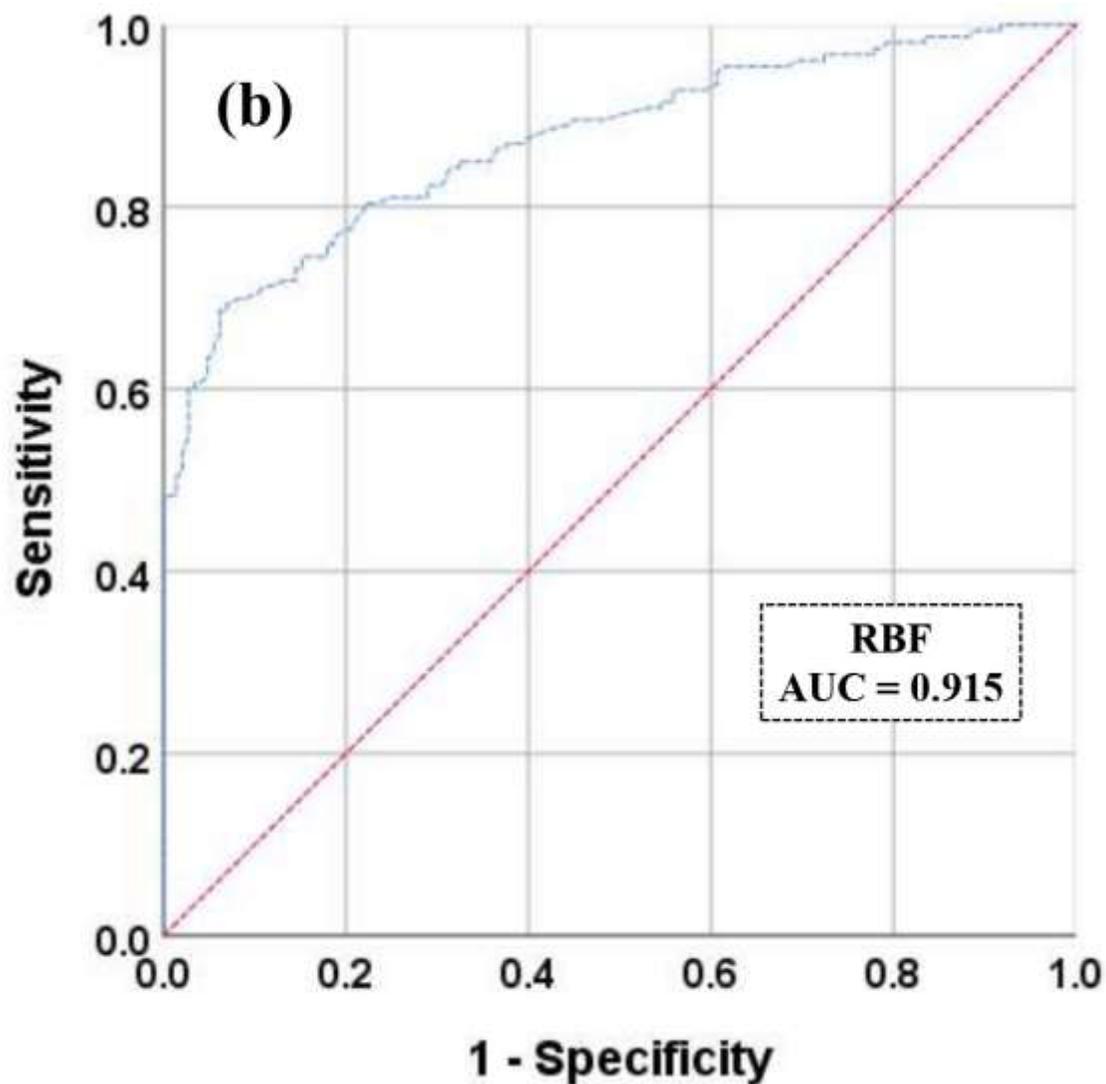
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Figure 10 Accuracy of the RBF classifier.

336 The AUC of ROC curves was used to assess the accuracy of the predicted models. According to
337 the results, the AUC under the ROC is 0.941 and 0.915 for the MLP and RBF classifiers,
338 respectively (Figure 11). Despite the fact that both models produced AUC values more than 0.8,
339 the findings might be regarded adequate. However, it can be stated that the MLP model
340 outperformed the RBF model.



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Figure 11 ROC curve of the MLP (a) and RBF (b) model.

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3.5. Function of hidden layer in parameter estimates

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The functions of different hidden layers in parameter estimates for the MLP and RBF classifiers

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are shown in Table 2 and Table 3 respectively. For the MLP classifier, fifteen input layers predict

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five units under a hidden layer, which were applied to predict the output rainfall. As found by the

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result, the fifth unit of the hidden layer has the highest weight in rainfall, followed by the fourth

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and third. For the RBF classifier, fifteen input layers predict ten units under ten hidden layers,

350 which were applied to predict the output rainfall. The first hidden layer has the highest weight in
 351 rainfall, followed by the eighth and second for this classifier.

352 **Table 2:** Parameters estimates of MLP model

		Predicted					
Predictor		Hidden Layer 1					Output Layer
		H(1:1)	H(1:2)	H(1:3)	H(1:4)	H(1:5)	Rain
Input Layer	(Bias)	-.503	.502	-.556	-.338	.964	
	SO2	.014	-.224	.106	-.409	.047	
	NO	-.097	.098	.320	-.048	-.257	
	NO2	-.342	.186	.431	-.150	.246	
	NOX	.244	-.329	.469	.351	-.017	
	CO	.038	.184	-.177	.208	.008	
	O3	-.017	.257	-.064	.126	.333	
	PM2.5	-.265	-.125	-.261	.039	.192	
	PM10	-.179	.000	-.104	.148	-.023	
	Wind Speed	.520	-.464	-.700	-.286	-.043	
	Wind Direction	.236	-.300	-.105	-.222	.081	
	Temperature	.688	-.372	.604	.501	-.127	
	RH	-.170	-.506	.075	.264	-.284	
	Solar Radiation	-.097	.401	-.269	.287	.035	
	BP	.468	-.283	-.353	.144	-.077	
	Vertical Wind Speed	.103	-.126	.297	-.104	.012	
Hidden Layer 1	(Bias)						-1.430
	H(1:1)						-1.917
	H(1:2)						-1.282
	H(1:3)						.640
	H(1:4)						1.199
	H(1:5)						2.245

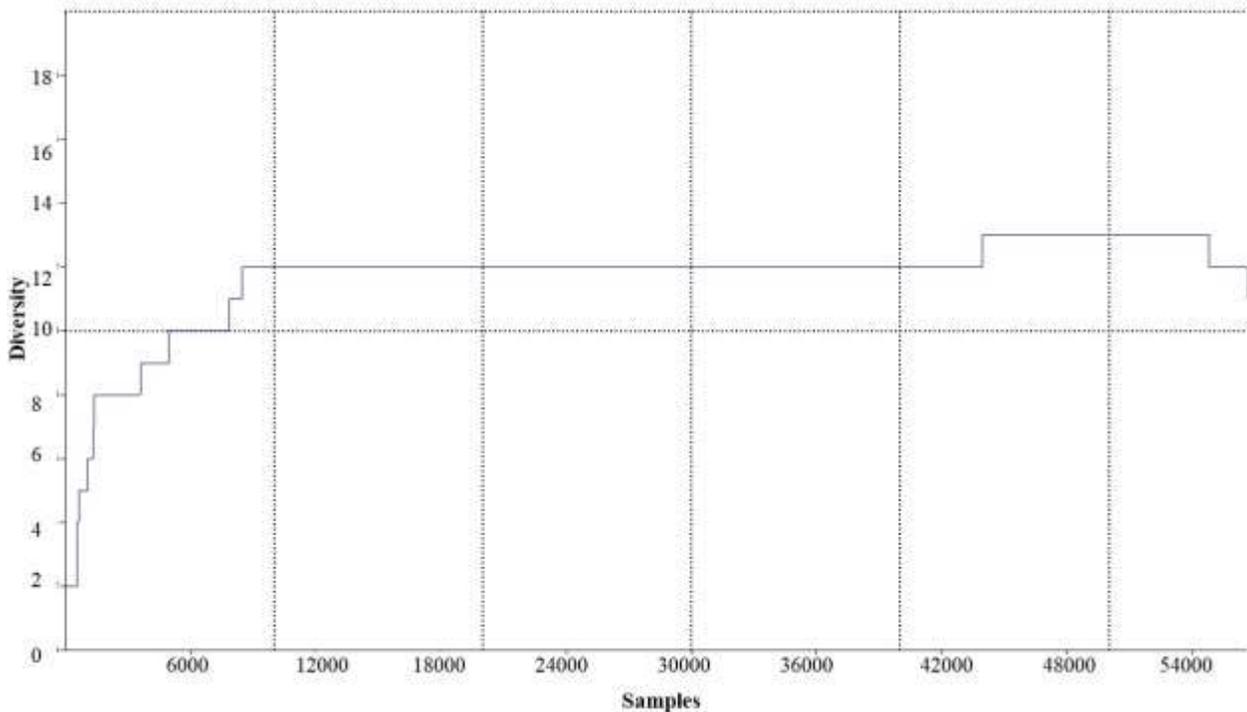
Table 2: Parameters estimates of RBF model

		Parameter Estimates (RBF)										
		Predicted										
Predictor		Hidden Layer ^a										Output Layer Rain
		H(1)	H(2)	H(3)	H(4)	H(5)	H(6)	H(7)	H(8)	H(9)	H(10)	
Input Layer	SO2	.434	.416	-.080	-.138	.184	.094	.040	.025	-8.904	-11.161	
	NO	.353	-3.683	.056	-.017	.098	.117	.095	.166	-4.830	-15.732	
	NO2	.452	-2.493	.059	.076	.052	.097	.102	.388	-6.903	-15.355	
	NOX	.242	-5.258	.115	.101	.132	.146	.143	.050	-5.702	-14.000	
	CO	3.004	-1.017	1.411	.681	-.236	-.153	-.118	-.795	-2.787	.476	
	O3	.097	-1.069	-.140	-.151	2.394	-.100	.065	-.083	-5.889	-9.680	
	PM2.5	-.341	-3.678	.192	.189	.209	.216	.217	-2.267	-5.559	-13.686	
	PM10	-2.291	-2.321	-.995	-.302	.329	.337	.336	-2.319	-4.068	-10.741	
	Wind Speed	-3.221	-3.223	.264	.283	.313	.312	.315	-3.222	-3.247	-3.471	
	Wind Direction	-3.112	-3.229	.269	.289	.306	.310	.314	-3.111	-3.729	-4.810	
	Temperature	-.793	-1.060	-.719	-.595	-.456	-.498	1.720	-.806	-1.361	-2.397	
	RH	-2.840	-3.616	-.064	.200	.340	.320	.340	-2.960	-4.106	-4.344	
	Solar Radiation	-3.202	-3.277	.296	.301	.305	.305	.324	-3.215	-3.289	-3.308	
	BP	-2.382	-2.421	-2.379	-1.152	.361	.361	.544	-2.382	-2.574	-2.755	
	Vertical Wind Speed	.527	3.299	-.015	6.748	-.276	-.267	-.033	1.142	3.047	4.290	
Hidden Layer	Unit Width	.911	1.690	.735	1.708	.756	.370	.371	.787	1.849	5.331	
	H(1)											1.437
	H(2)											.242
	H(3)											-.012
	H(4)											.027
	H(5)											-.018
	H(6)											-.011
	H(7)											.007
	H(8)											.748
	H(9)											-3.852
	H(10)											-16.762

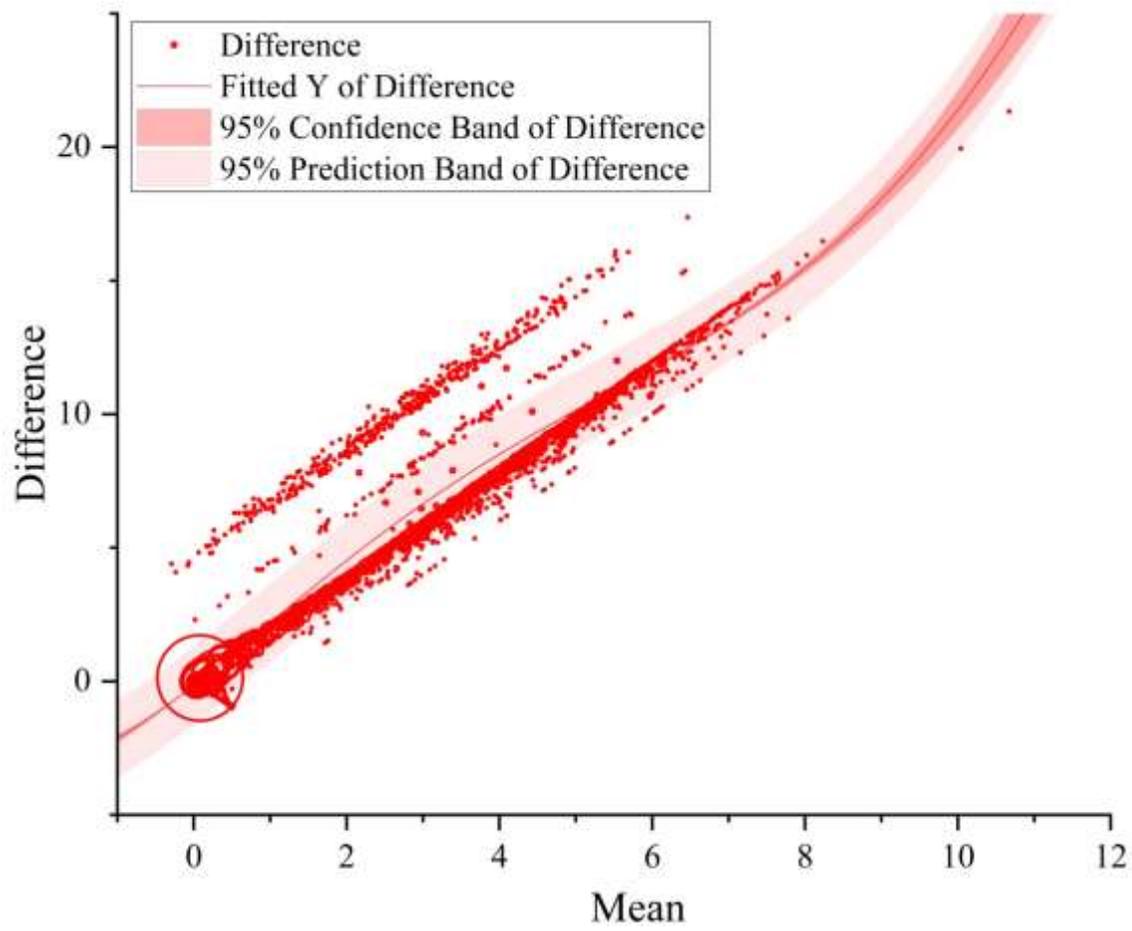
a. Displays the center vector for each hidden unit.

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 362 Figure 12 illustrates the diversity of the samples under the study. For sample sizes less than 8500,
 363 the diversity increased with the increase in sample size. The diversity remained the same for the
 364 sample size of 8500–44000. For a sample size greater than or equal to 44000-55000, the diversity
 365 increased a little more and decreased again for a sample size greater than or equal to 55000. In this
 366 study, the sample size was 56649, and the diversity was close to 11. The variation of the samples
 367 from the mean value is shown in Figure 13. From which we can easily understand about the
 368 difference of the samples from the mean value. The probability of rainfall has been estimated with
 369 considering upper and lower percentile (Figure 14). From this estimation we found that there is a
 370 increasing probability of rainfall in future period. These scenarios suggest the extreme climatic
 371 condition and its associated water logging condition the study region.



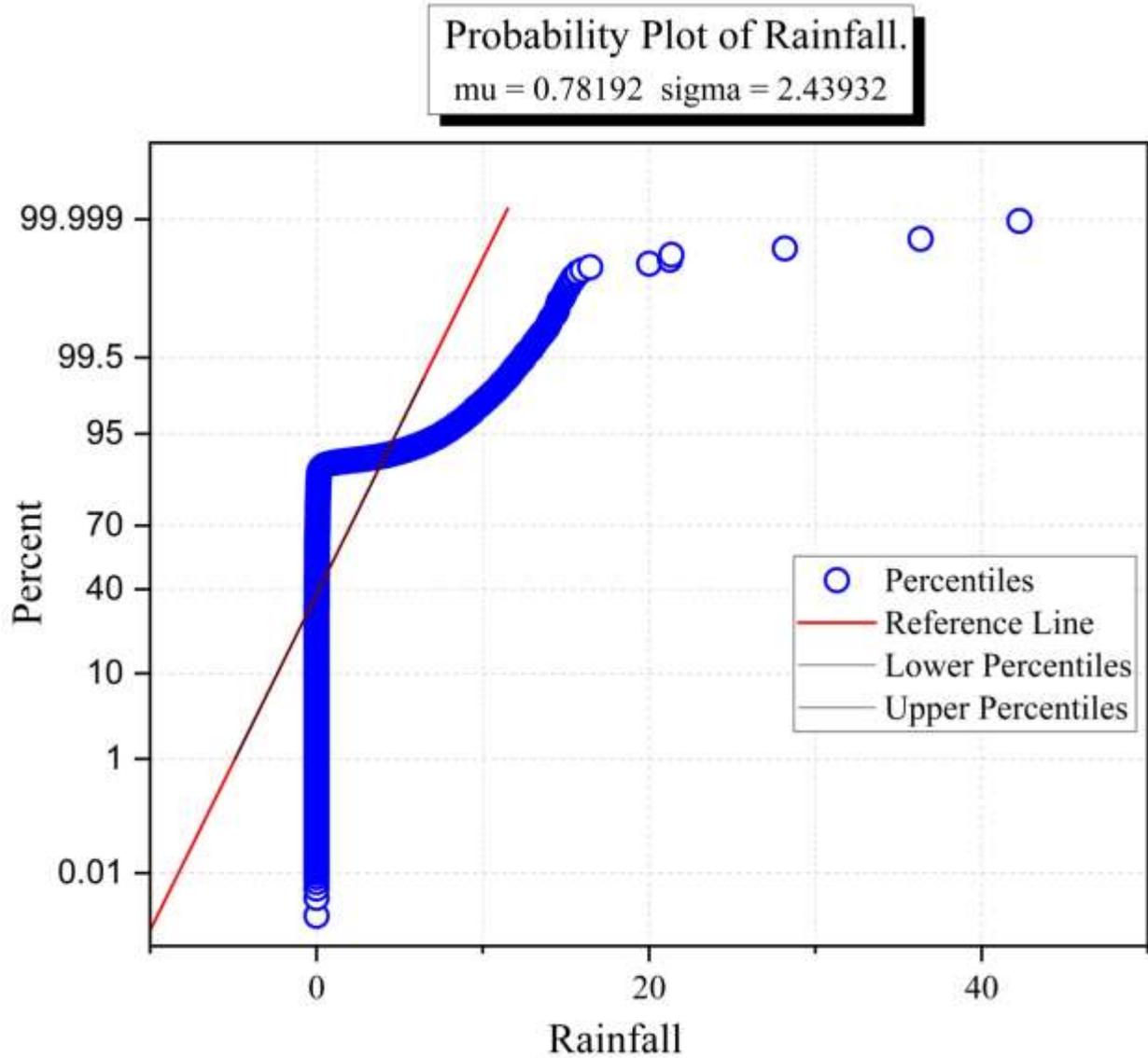
372
 373 **Figure 12** Diversity of samples in the current study



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Figure 13 Variations of the samples from mean value



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Figure 14 Probability of the rainfall in Dhaka megacity

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379 **4. Discussion**

380 One of the most important aspects of managing climate-induced water-related problems in cities is
 381 forecasting rainfall patterns. The occurrences of rainfall in a specific region can be used to
 382 determine the overall climatic pattern. Rainfall and temperature are critical climatic inputs for
 383 economic productivity, particularly in light of climate change (Rahman and Islam 2019; Jhajharia

384 et al. 2021; Talukdar et al. 2022). However, because of their probable interaction, precise study
385 and modelling of the combined distribution of rainfall and temperature is challenging. Most
386 scientists agree that there is a strong association between rainfall and temperature across tropical
387 oceans and land (Jhajharia and Singh 2011). The most important fundamental physical elements in
388 the climate are rainfall and temperatures, as these variables govern the environmental state of a
389 place, which influences economic activity. Several methods are available and applied for predicting
390 trends in rainfall patterns. This study aimed to evaluate and compare two different methods in order
391 to select the best fit method for predicting the trends of rainfall patterns in Dhaka City. Fifteen air
392 parameters and meteorology-related conditioning parameters were employed to predict rainfall
393 trends and, according to VIF and tolerance values, most of the parameters have no multi-
394 collinearity. Here, rainfall is considered as a dependent variable and the rest of the parameters have
395 been considered as independent variables. Both the MLP and RBF models performed well, with
396 network faults reduced to values very close to those observed in the real data. In both models, PM_{10}
397 was the most significant component for predicting the trends of rainfall patterns.
398 In the last few years, the connection between rainfall and synoptic atmospheric parameters has le
399 d to the development of the weather-state model (Hughes et al. 1995; Shafie et al. 2012; Islam et
400 al. 2020). The AUC under the ROC is 0.941 and 0.915 for the MLP and RBF classifiers,
401 respectively. The MLP outperformed the RBF model in terms of performance. There is an
402 increasing probability of rainfall in this region in upcoming times. So, it directly indicates the water
403 logging condition of this study region. Citizens were reminded of the chaos that regularly surrounds
404 metropolitan regions at this time, when roads turn into canals even if there is mild rain, as the
405 monsoon pounded cities. During the monsoon, waterlogging, which is a precursor to urban floods,
406 is a familiar sight in this region. Even as the weather system has changed, more high-intensity rain
407 has fallen on fewer rain days, resulting in increased urban floods. Others have been caused by three

408 to six-hour bouts of high-intensity rain that abruptly overwhelmed drainage infrastructure. The
409 pattern of urban floods and waterlogging in urban areas of Bangladesh has persisted this year as
410 well (Islam et al. 2021).

411 Compared to the applied MLP and the RBF models, the MLP performance is superior to the RBF,
412 whereas the values of relative error and sum of square error for the MLP model are higher than
413 those for the RBF model. Although the RBF model provides a lower error than the MLP model
414 with a higher degree of efficiency in terms of error matrices, the relative error for the RBF model
415 is consistently less than half of the relative error for the MLP model. Johnson and King (1988)
416 reported that the MAPE of around 30% is regarded as a rational prediction as it is close to 10% and
417 can be considered as precise, which is similar to our study.

418 Although the accuracy of the RBF model is less than that of the MLP model, other meteorological
419 and environmental processes can be simulated by using both models with acceptable accuracy. The
420 MLP model outperforms the RBF model in terms of stability. Although using artificial intelligence
421 to predict was a viable method for generating a conservative estimate for the real monitoring
422 dataset, the MLP model may have had a limit. The main drawback is the need for trial and error to
423 find the best network structure. Future studies should combine the neural network model with a
424 genetic algorithm to find the ideal neural network structure. PM_{10} , $PM_{2.5}$, and wind speed data
425 might be used to assess the model's predicting ability.

426 **5. Conclusion**

427 Because of their ability to identify functional correlations between the model's inputs and outputs
428 while explicitly considering the data generation process, machine learning-based ANN models are
429 effective and powerful tools for simulating complex and poorly understood natural processes. In
430 this study, we employed two ANN models of feed-forward networks, namely the MLP and RBF

431 models, to predict the rainfall trend pattern of a South Asian megacity, Dhaka, Bangladesh. Fifteen
432 atmospheric and meteorological factors were considered as input variables in both models. For
433 predicting rainfall patterns in this region, rainfall is regarded as a dependent variable, whereas the
434 remaining elements are considered independent variables. In the RBF model, ten basis radial
435 functions were used. The multi-collinearity assessment among the input variables shows that most
436 of the components have VIF and tolerance values of less than 10 and more than 0.2, i.e., no multi-
437 collinearity. This type of outcome is helpful for projecting rainfall trends while considering various
438 climatic and atmospheric parameters. The findings showed that the MLP is the leading machine
439 learning-based ANN model compared to the RBF model in predicting rainfall trend patterns with
440 an AUC value of 0.941.

441 **Acknowledgement**

442 The authors highly acknowledge the Bangladesh Meteorological Department (BMD) and Atomic
443 Energy Commission (AEC) for providing the required datasets to conduct this study. The authors
444 also thank the Department of Disaster Management, Begum Rokeya University, Rangpur, for
445 providing the necessary supports to conduct this study.

446 **Code availability**

447 Code will be available upon reasonable request on corresponding authors

448 **Data availability**

449 Data will be available upon reasonable request on corresponding authors

450 **Author contribution**

451 Islam, A.R.M.T., designed, conceptualized, drafted the original manuscript; Pal, S.C., Chakraborty
452 R., Sarkar S.K, planned the documents; Fattah, M.A., and Mallick J., involved in the literature

453 review, software, mapping, statistical analysis, interpretation of the analysis and discussion; Pal,
454 S.C., and Chakraborty R., contributed to instrumental setup, data analysis, validation; Rahman
455 M.S., contributed to data collection and extraction; Islam, A.R.M.T., Mallick, J., Fattah, M.A., and
456 Sarkar S.K., had done the internal review and proofreading during the manuscript drafting stage.

457 **Ethical approval**

458 Not applicable

459 **Consent to participate**

460 Not applicable

461 **Consent to publish**

462 Not applicable

463 **Conflict of interest**

464 None

465 **Funding information**

466 The authors extend their appreciation to the Deanship of Scientific Research at King Khalid

467 University for funding this work through General program under grant number (RGP2/169/43)

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Supplementary Files

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