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Abstract: Arc plasma shape under pulsed and continuous ultrasound field were studied in this research using self-developed welding device which combines arc and ultrasound field coaxially. The results show that, compared with the arc of conventional tungsten inert gas welding, the shape of arc under pulsed ultrasound field relate to the pulse frequency. From 1 Hz to 20 Hz, the arc plasma expands and contracts periodically in one pulse. When more than 20 Hz, the arc plasma contracts as the pulse frequency increases. During high pulse frequency, the arc shape become steady and similar to those in continuous ultrasound field. When in 500 Hz, the contraction ratio of arc projected area under pulsed ultrasound field reaches 38 %, comparing with 30 % of the same power continuous ultrasound field, i.e., in high frequency, low power pulsed ultrasound can obtain arc control effect similar to high power continuous ultrasound, raising ultrasound energy efficiency. The mechanism of ultrasonic influence on arc is analyzed based on sound pressure and acoustic streaming.

Keywords: Pulsed ultrasound; TIG; Plasma; Acoustic streaming

1 Introduction

In stainless steel and non-ferrous metal welding, tungsten inert gas welding (TIG) has the characteristics of stable welding process, good protection and satisfactory weld bead formation, which is one of the most widely used welding methods^[1-3]. Researchers

24 are committed to developing high-efficiency TIG, developing various TIG welding
25 methods such as pulsed current TIG ^[4], magnetic control TIG ^[5], laser–TIG hybrid
26 welding ^[6], twin-electrode TIG ^[7], activated flux TIG ^[8] and so on. As a new welding
27 and arc control method, ultrasonic assisted arc welding has the advantages of non-
28 contact, no electrical interference, controllable parameters and easy adjustment. It has
29 gradually become a research hotspot. Ultrasound is used to improve arc stability in
30 underwater welding ^[9], to suppress hot cracks in superalloy welding ^[10] and to reduce
31 the formation of Laves phase in nickel alloy welding ^[11]. In general, the impact of
32 ultrasound refines grain size in weld seam (especially columnar grain in fusion line) ^[12],
33 increases weld penetration ^[13], promotes uniform composition ^[14].

34 Professor Yang Chunli of Harbin Institute of Technology first realized the coaxial
35 composite of ultrasound and arc ^[13]. Experiments showed that when using 30 A welding
36 current, the force of hybrid arc is more than twice the conventional TIG arc pressure.
37 The arc force distribution transforms from a double-sided exponential function to a
38 close Gaussian function, which favor deep penetration and high productivity ^[15]. The
39 double exposure holographic interferometry also verified that the arc contracts under
40 ultrasound field: the central energy density of the arc is more concentrated and the arc
41 temperature increases ^[16]. Added ultrasonic to the TIG process, the weld grains vary
42 from columnar shape to equiaxed ^[12], and the weld porosity is reduced ^[17]. The main
43 influencing factors of the ultrasound field distribution are the height of the radiator, the
44 shape of the radiator, the diameter of the radiator and the frequency of ultrasound. When
45 the height of the radiator is an integer multiple of the half wavelength of the ultrasonic
46 wave, a standing wave sound field is formed, and the acoustic energy intensity reaches
47 maximum ^[18]. When the ultrasonic frequency and the output amplitude increase, the
48 sound pressure amplitude increases. When the shape of radiator changes from a plane
49 to a concave surface, the acoustic pressure increases and becomes more concentrated
50 ^[19].

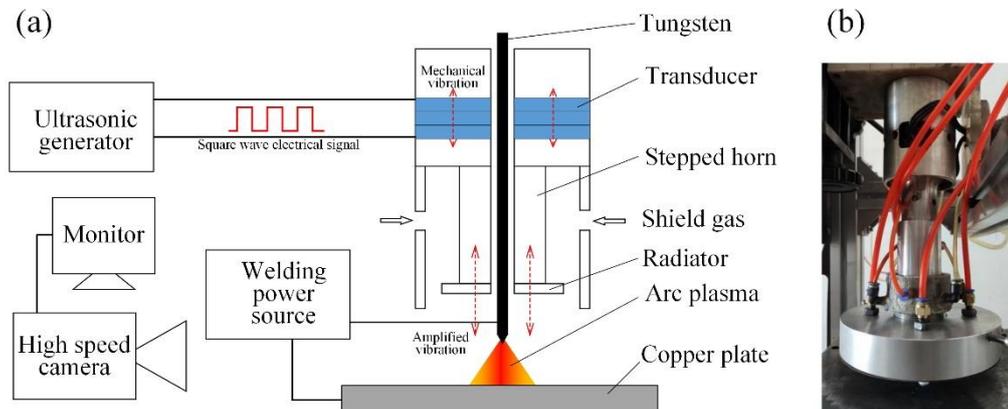
51 However, researches reported mostly focus on the design of hybrid welding
52 equipment and the phenomenological rule of continuous ultrasound-assisted TIG (U-
53 TIG), lack of in-depth study of the mechanism between ultrasound and arc plasma. In

54 order to utilize ultrasonic efficiently and better regulate the welding process, this paper
55 proposes pulsed ultrasound assisted tungsten inert gas welding (PU-TIG). The
56 morphology of arc plasma in pulsed ultrasound field are studied in this paper, which
57 provides a reference for developing ultrasound-arc hybrid welding.

58 2 Materials and methods

59 2.1 Equipment

60 German LORCH V24 TIG welding power was used in this study and work in
61 DCRP mode to obtain stable arc. The ultrasonic system uses the commercial HDF01
62 intelligent ultrasonic generator. The generator can output square wave or continuous
63 waves, with maximum output power of 3000 W. The ultrasonic frequency is 20 kHz.
64 The self-designed ultrasonic-arc hybrid torch uses transducer (made by series
65 piezoelectric ceramics) to convert pulse current of the ultrasonic generator into
66 mechanical vibration. The mechanical vibration is amplified by the stepped horn and
67 then emits to the arc plasma zone. The long tungsten pole passes through the hole in the
68 center of the horn. The schematic diagram of the study equipment and the physical
69 diagram of the composite torch are shown in Fig.1 (a) and (b).



70

71 Fig.1. Working way of the system. (a) diagrammatic sketch; (b) hybrid welding torch.

72 In this study, the copper plate acts as anode. The shielding gas is 99.99 % argon.
73 The peak power of pulsed ultrasound is 2100 W, the background power is 900 W, the
74 frequency ranges from 0 Hz to 500 Hz, and the duty cycle is 50 %. Other welding
75 parameters are shown in Table 1.

76

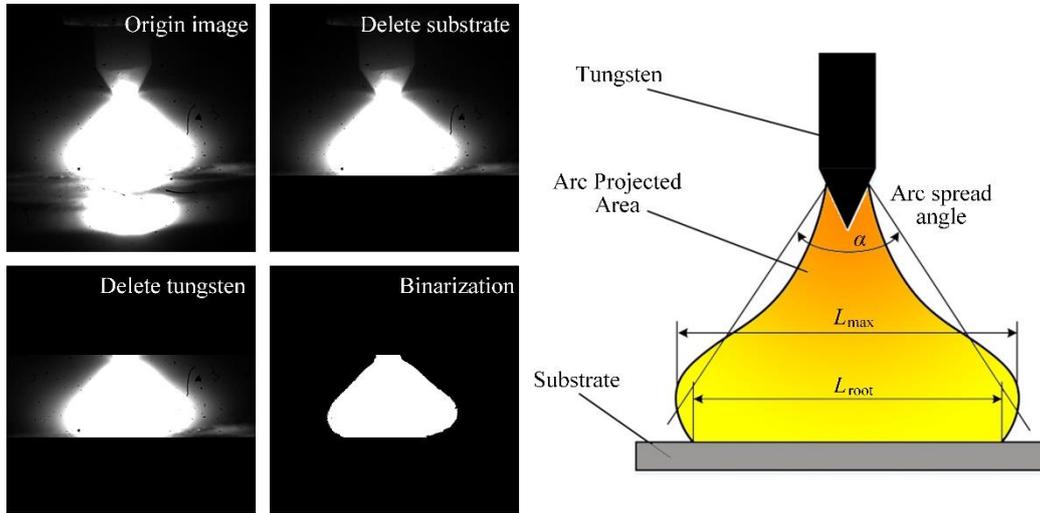
Table 1. Welding parameters.

weld current (I/A)	height of tungsten (l/mm)	angle of tungsten ($\alpha/^\circ$)	shielding gas flow (V/L·min ⁻¹)	height of acoustic (H/mm)
70	3	45	15	12

77 High-speed cameras Phantom V341 by American Vision Research Corporation
78 was used to record arc image. The exposure parameter of the camera with filter was set
79 as 2000 frames and exposure time 60 μ s.

80 2.2 Arc shape study conditions

81 The arc image obtained by high-speed camera are processed as shown in Fig.2.
82 Simplify the image and extract necessary parameters to describe the arc shape. The arc
83 projected area is defined as the number of bright pixels.



84

85

Fig.2. Arc image processing and parameter extracted from image

86 In order to study the influence of ultrasound on the arc plasma, several geometric
87 parameters are defined:

$$\Delta S = \frac{S_{\text{TIG}} - S_{\text{U}}}{S_{\text{TIG}}} \cdot 100\% \quad (1)$$

88

$$\Delta L_{\text{max}} = \frac{L_{\text{max-TIG}} - L_{\text{max-U}}}{L_{\text{max-TIG}}} \cdot 100\% \quad (2)$$

$$\Delta L_{\text{root}} = \frac{L_{\text{root-TIG}} - L_{\text{root-U}}}{L_{\text{root-TIG}}} \cdot 100\% \quad (3)$$

89

90

91

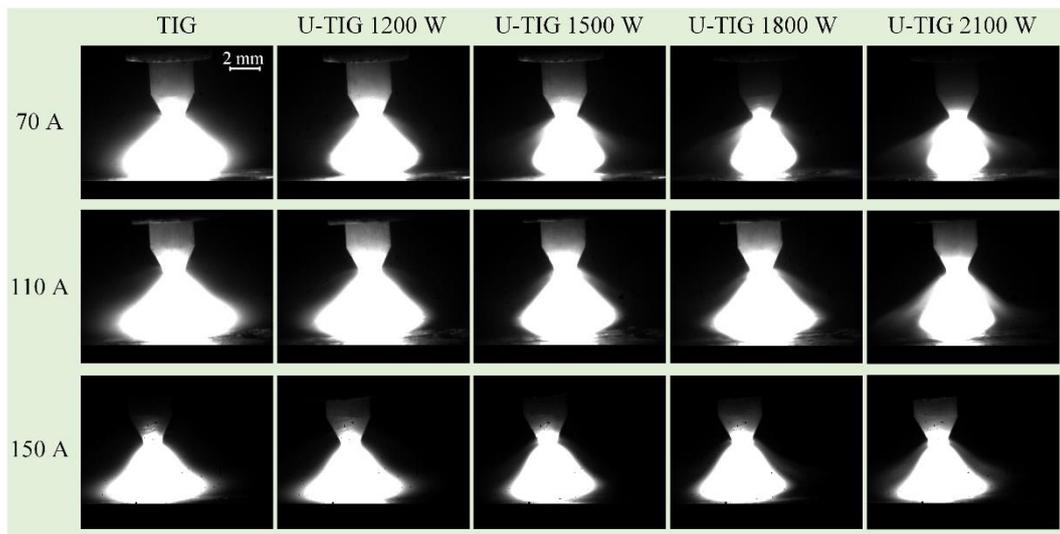
where ΔS is the change rate of arc projected area, S_{TIG} is area of TIG arc, S_{U} is arc area of U-TIG or PU-TIG, ΔL_{max} is change rate of maximum arc width, $L_{\text{max-TIG}}$ is maximum arc width of TIG, and $L_{\text{max-U}}$ is maximum arc width of U-TIG or PU-TIG,

92 ΔL_{root} is change rate of bottom arc width, $L_{\text{root-TIG}}$ is bottom arc width of TIG, and $L_{\text{root-}}$
93 U is bottom arc width of U-TIG or PU-TIG.

94 **3 Results**

95 **3.1 Influence of ultrasonic power on arc behavior**

96 Arc images of TIG and different ultrasonic power U-TIG are shown in Fig.3. In
97 the welding current of 70 A, the arc exhibits different degrees of contraction under
98 continuous ultrasound. As the ultrasonic power increases, the arc shows more shrinkage,
99 which is manifested by a reduction in arc width and a decrease in arc spread angle.
100 Comparing the arc images of U-TIG of different welding currents, the degree of
101 shrinkage reduced as the welding current increases. This is because arc with a large
102 current have the ability to resist external disturbances.



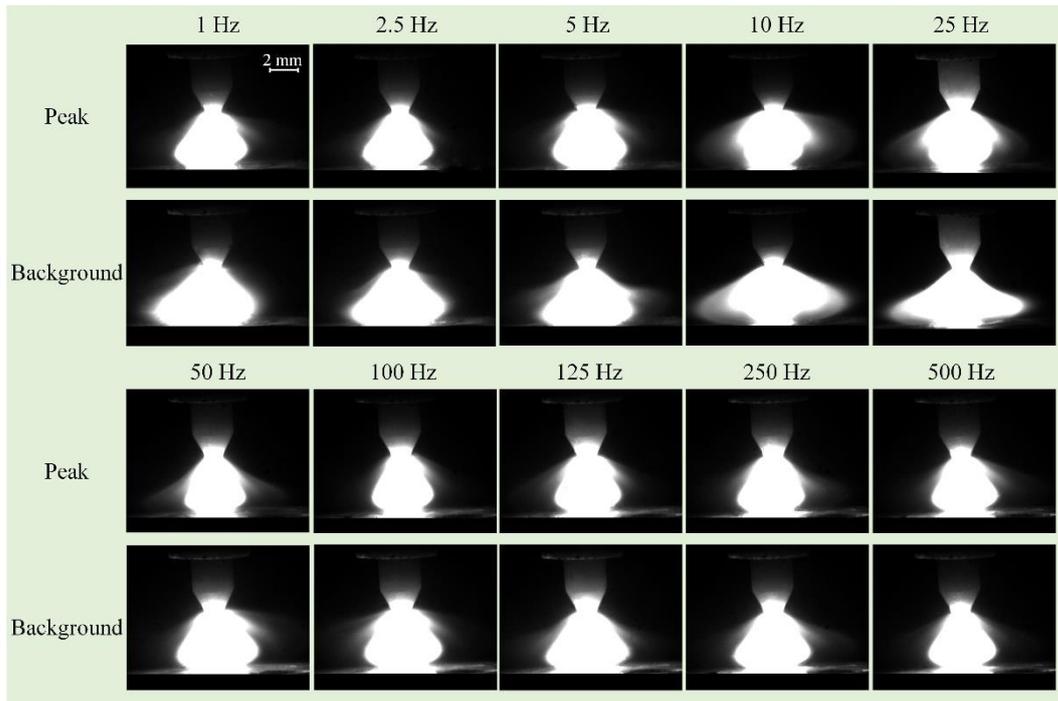
103

104

Fig.3. Influence of ultrasonic power on U-TIG arc behavior.

105 **3.2 Influence of pulse frequency on PU-TIG arc behavior**

106 The PU-TIG arc images of different ultrasonic pulse frequencies are shown in
107 Fig.4. In low pulse frequency (for example, less than 20 Hz), the arc shape remain
108 unchanged during the period of the ultrasonic peak and background value. During the
109 peak value, the arc shrinks, which is manifested by a significant decrease in the
110 maximum arc width.



111

112

Fig.4. Influence of pulse frequency on PU-TIG arc behavior.

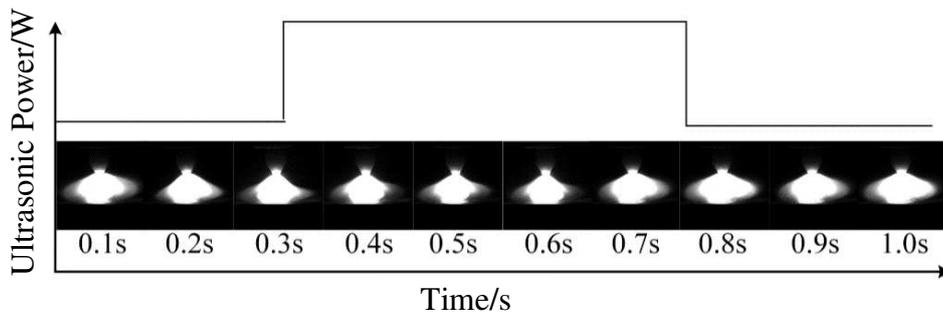
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116

At the pulse frequency of 10 Hz, arc shape in one cycle are shown in Fig.5. In 0.1 s~0.2 s and 0.9 s~1.0 s, the arc is stable and diffused. In 0.4 s~0.7 s, the arc is stable and contracted. At about 0.3 s and 0.8 s, the ultrasonic output power changes abruptly, while the arc shape are in a transitional period.



117

118

Fig.5 Arc shape during one pulse cycle.

119

120

121

122

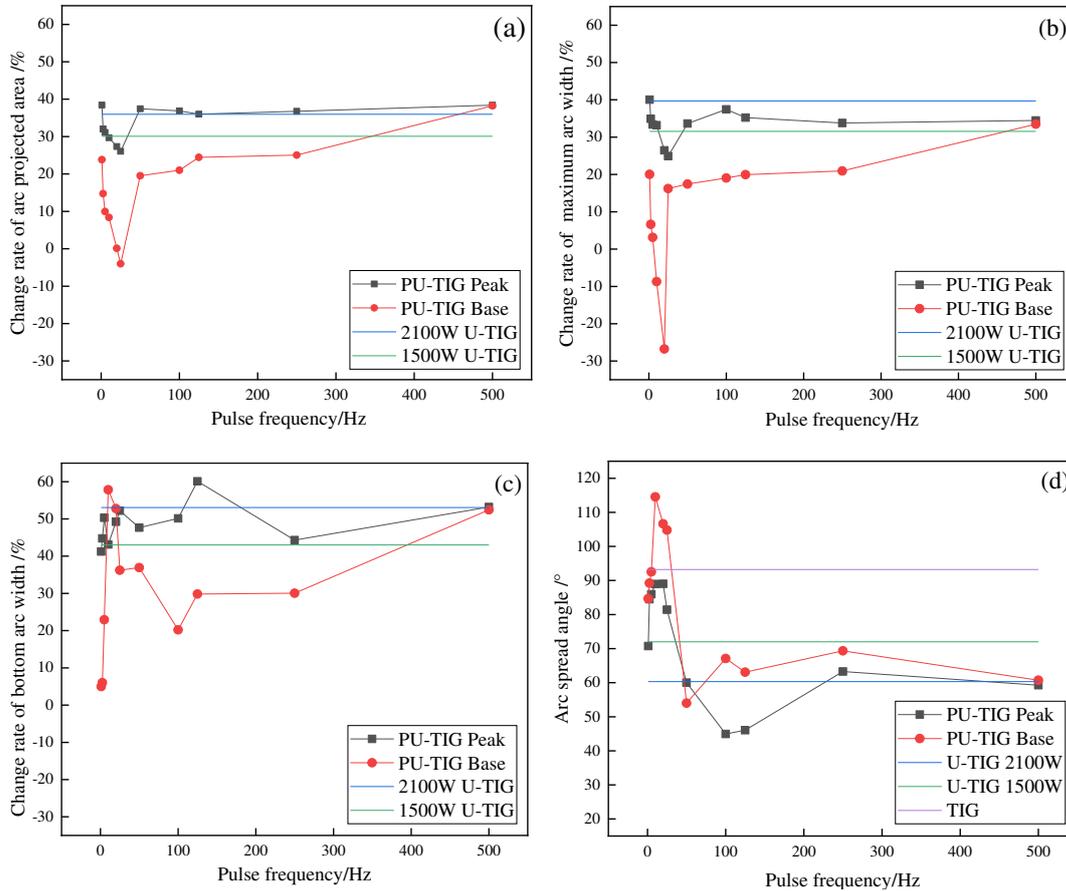
As the pulse frequency increases, although the arc still exhibits the same periodic jitter as the ultrasonic frequency, the arc shape change cannot keep up with the ultrasonic pulse period. In high frequency, arc shape between the background value and peak value tends to be consistent.

123

124

In order to quantify the trend of this change, multiple geometric parameters are defined as Eq.(1) to (3) , and the results are shown in Fig.8. from the 1 Hz to 500 Hz,

125 arc shrinks more significantly in peak value compared with background value. And as
 126 the pulse frequency increases, the arc area change at the peak value stage is small, and
 127 the arc area changes greatly at the base value stage. The arc spread angle PU-TIG is
 128 overall smaller than TIG.



129

130

131 Fig.6. Effect of Pulse Frequency on PU-TIG Arc Shape. (a) change rate of arc projected area; (b)
 132 change rate of maximum arc width; (c) change rate of bottom arc width; (d) arc spread angle

133 It can be seen from the above that in the high pulse frequency, the effect of pulsed
 134 ultrasound on the arc shape is nearly consistent with continuous ultrasound. Fig.7 is a
 135 comparison of PU-TIG and U-TIG arc shape. The average power of pulsed ultrasound
 136 is 1500 W. At 500 Hz, the arc shape of PU-TIG approaches the contraction mode at
 137 peak value. That is, increasing the ultrasonic pulse frequency allows the PU-TIG with
 138 lower average ultrasonic power to obtain an arc shape similar to those of high power
 139 U-TIG.

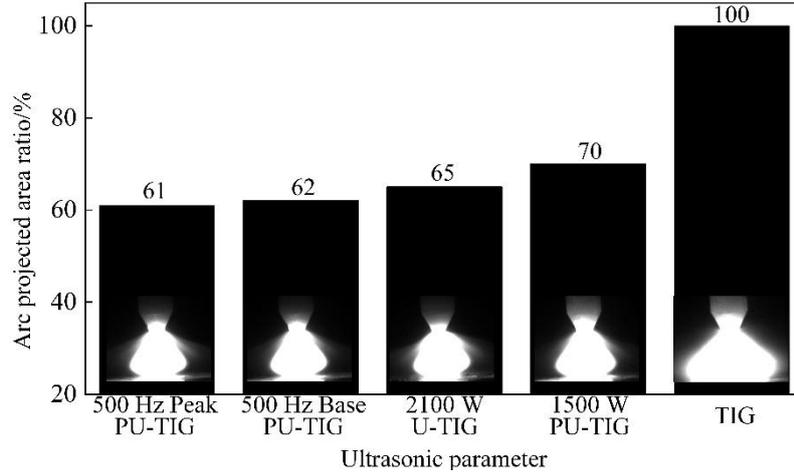


Fig.7. Arc projected area comparison.

4 Analysis and discussion

4.1 Effect of acoustic standing wave on plasma

When the distance between the radiator and reflector is an integer multiple of the half-wavelength of the sound wave, an acoustic standing wave field is created [20]. To consider the case of plane simple harmonic wave propagating along the x-axis. The sound pressure of the incident wave is p_i , and the reflected sound pressure is p_r . The frequency of the incident wave is same as the reflected wave, while the propagating direction is opposite. This two wave interfere and form a synthetic sound pressure p , which can be described with mathematical expression [21]:

$$p_i = p_{im} e^{j(\omega t - kx)} \quad (4)$$

$$p_r = p_{rm} e^{j(\omega t + kx)} \quad (5)$$

$$p = p_i + p_r = 2p_{rm} \cos kx e^{j\omega t} + (p_{im} - p_{rm}) e^{j(\omega t - kx)} \quad (6)$$

where p_{im} and p_{rm} are the amplitude of sound pressure of incident wave and the reflected wave respectively, $\omega = 2\pi f$ is circular frequency, t is time, $k = 1/\lambda$ is wave number. From Eq.6, at $x = n\lambda/2$ ($n = 1, 2, \dots$), the sound pressure reaches maximum; at the $x = (2n - 1)\lambda/4$ ($n = 1, 2, \dots$), the sound pressure is minimum.

In high-pressure condition, arc contracts and transform from diffused bell shape to compact cylinder shape [22]. The arc voltage increase as the ambient pressure rises and becomes brighter [23]. The Saha's equation can be used to describe thermal ionization [24]:

160
$$\frac{\alpha^2}{1-\alpha^2} \cdot p = \frac{2z_+}{z} \left[\frac{2\pi m_e}{h^2} \right]^{3/2} (kT)^{5/2} \exp\left[-\frac{eU_i}{kT}\right] \quad (5)$$

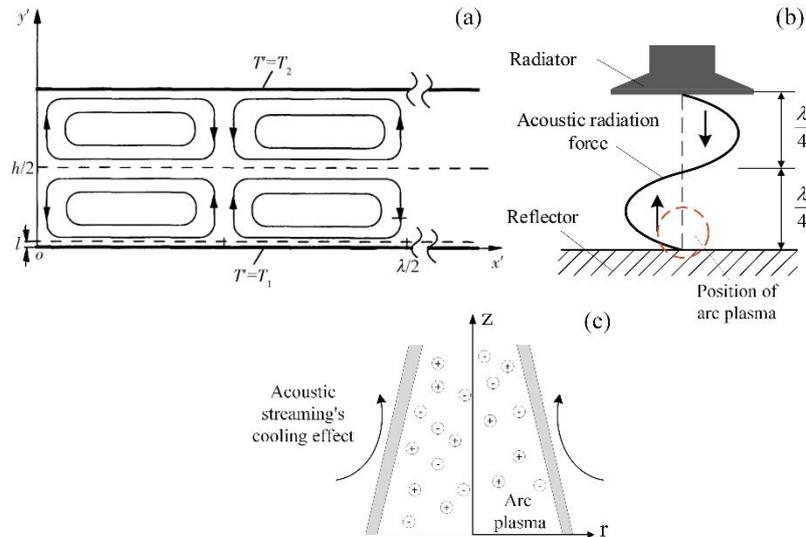
161 where α is the degree of ionization of plasma, p is ambient pressure, z_+ and z is internal
 162 partition function of ion and atom respectively, which describe the sum of possible
 163 energy states, m_e is the mass of electron, k is Boltzmann's constant, h is Planck's
 164 constant, T is the thermodynamic temperature, eU_i is the energy of the i -th energy level.
 165 When the degree of ionization is low and the temperature T is constant, the relationship
 166 between α and p is simplified as [25]:

167
$$\alpha \propto \frac{1}{p^{1/2}} \quad (6)$$

168 With the increase of pressure, the degree of ionization decreases, i.e., the
 169 conductivity of the plasma decreases [26]. In order to maintain the set welding current,
 170 the drive——arc voltage must rise, which has been proved by measurement [22][23] [27].
 171 The arc plasma must contract to increase the ion density to maintain conductivity.

172 **4.1.2 Effect of acoustic streaming on plasma**

173 When the acoustic energy is large enough, the density of medium substituted into
 174 the Navier-Stokes equations should be a function of pressure instead of a fixed value
 175 [28]. It leads to a non-zero time averaged pressure, which is the so-called acoustic
 176 radiation pressure [20]. The value of acoustic radiation pressure is proportional to the
 177 energy density of sound wave [29]. If the medium is viscous or has boundaries, the
 178 energy of the sound wave dissipates and thereby acoustic radiation pressure difference
 179 forms. When acoustic radiation pressure difference acts on solid particles, it is called
 180 acoustic radiation force, which is used in acoustic suspension [20][30]. It cause the
 181 medium to flow when act on the the medium itself——acoustic streaming [31]. Rayleigh
 182 firstly studied the acoustic streaming phenomenon between two parallel plates in the
 183 air [32]. Two clockwise and two counter clockwise circulations are formed between
 184 parallel plates as shown in Fig.8 (a).



185

186 Fig.8 Mechanism of acoustic streaming and its effect on arc. (a) Rayleigh's acoustic streaming in
 187 a standing wave field [32]; (b) distribution of acoustic radiation force; (c) cooling effect of acoustic
 188 streaming on arc;

189 The energy of the acoustic streaming created by ultrasound is sufficient for drying
 190 [33] and melt processing [34]. When acoustic streaming acts on the arc, it is equivalent to
 191 add a forced-cooling convection. It blows away the low temperature neutral particles
 192 and promote deionization of arc plasma. The heat lost in the form of radiation also
 193 increases under high pressure [35]. Based on the principle of minimum voltage [36], when
 194 the heat loss of the arc increases, in order to maintain the balance of heat production
 195 and heat dissipation, the arc contract to reduce the surface area and thus reduce the heat
 196 dissipation. In other word, cooling limits the range of ions and confines them to smaller
 197 zone. When the density of particles increases, it is easier for electrons to transferred its
 198 energy to neutral particles and ions through collision [37]. For the temperature of the
 199 electron is higher than other particles, temperature homogenization means increase in
 200 temperature of the arc, which was proved by holographic interference measurement [16].

201 4.1 Mechanism of ultrasonic on plasma

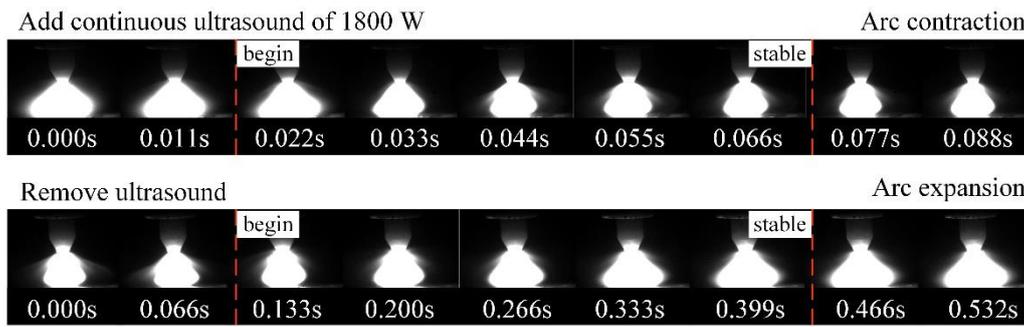
202 From part 3.2, when pulse frequency is more than 250 Hz, the arc area of pulsed
 203 ultrasound is smaller than that of un-pulsed ultrasound. It can be explained by the
 204 magnetic contraction of arc. According to right hand grip rule, the wires conducting the
 205 same direction current attract each other. For a cylindrical conductor of fluid, the radial

206 pressure is [25]:

$$207 \quad P_r = K \frac{I}{\pi R^2} (R^2 - r^2) \quad (6)$$

208 where P_r is the pressure at radius r , K is a constant, I is current, R is radius of the
209 cylindrical conductor.

210 From Eq.6, the decrease of conductor radius will lead to the increase of contraction
211 force. As a result, the contracted arc should exhibit a more significant magnetic
212 contraction effect. To confirm this suppose, a comparative test was made as shown in
213 Fig.9. It takes 0.044 s for the arc to shrink to stable and takes 0.266 s to expand. The
214 speed of arc expansion is lower than that of contraction. Arc cannot expand completely
215 under high-frequency pulse ultrasonic and thus its shape is similar to that of continuous
216 ultrasonic.



217

218 Fig.9. The speed of arc contraction and expansion.

219 5 Conclusion

220 (1) With the increase of ultrasonic power, the degree of contraction of the arc gradually
221 increases, which is represented by the reduction of arc area, arc width and diffusion
222 angle. As the arc current increases, the contraction of the arc weakens.

223 (2) At low pulse frequency (<20 Hz), the arc shape has a relatively stable period. At the
224 peak value of ultrasound, the arc contracts obviously, and the arc expands at the
225 background value; at high pulse frequency (>250 Hz), the difference of arc shape
226 between peak and background reduces, which tends to contract stably.

227 (3) At high pulse frequency, lower power pulsed ultrasound can obtain the arc shape
228 similar to higher power continuous ultrasound. The ultrasound utilization is improved.

229 (4) A local high pressure zone and acoustic streaming formed by ultrasound standing

230 wave enhance the cooling of arc and make it shrink.

231 **Ethical Approval**

232 Not applicable

233 **Consent to Participate**

234 Not applicable

235 **Consent to Publish**

236 Not applicable

237 **Authors Contributions**

238 Not applicable

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241 **Competing Interests**

242 No conflict of interest exists in the submission of this manuscript, and the manuscript is approved

243 by all authors for publication.

244 **Availability of data and materials**

245 Not applicable

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Figures

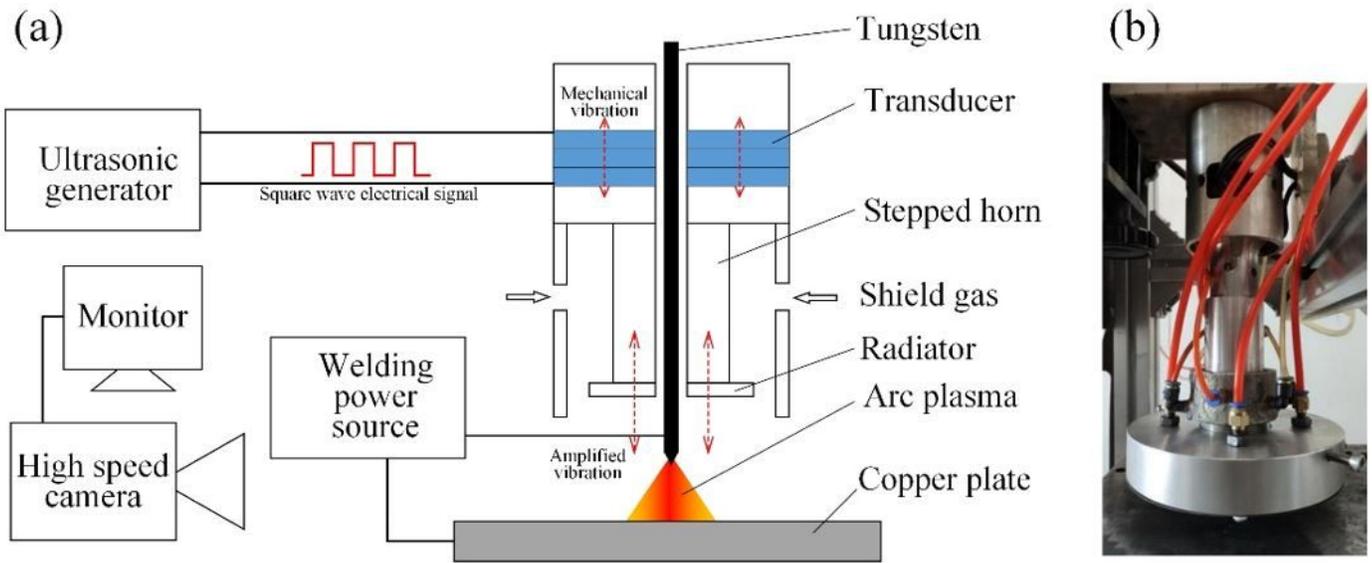


Figure 1

Working way of the system. (a) diagrammatic sketch; (b) hybrid welding torch.

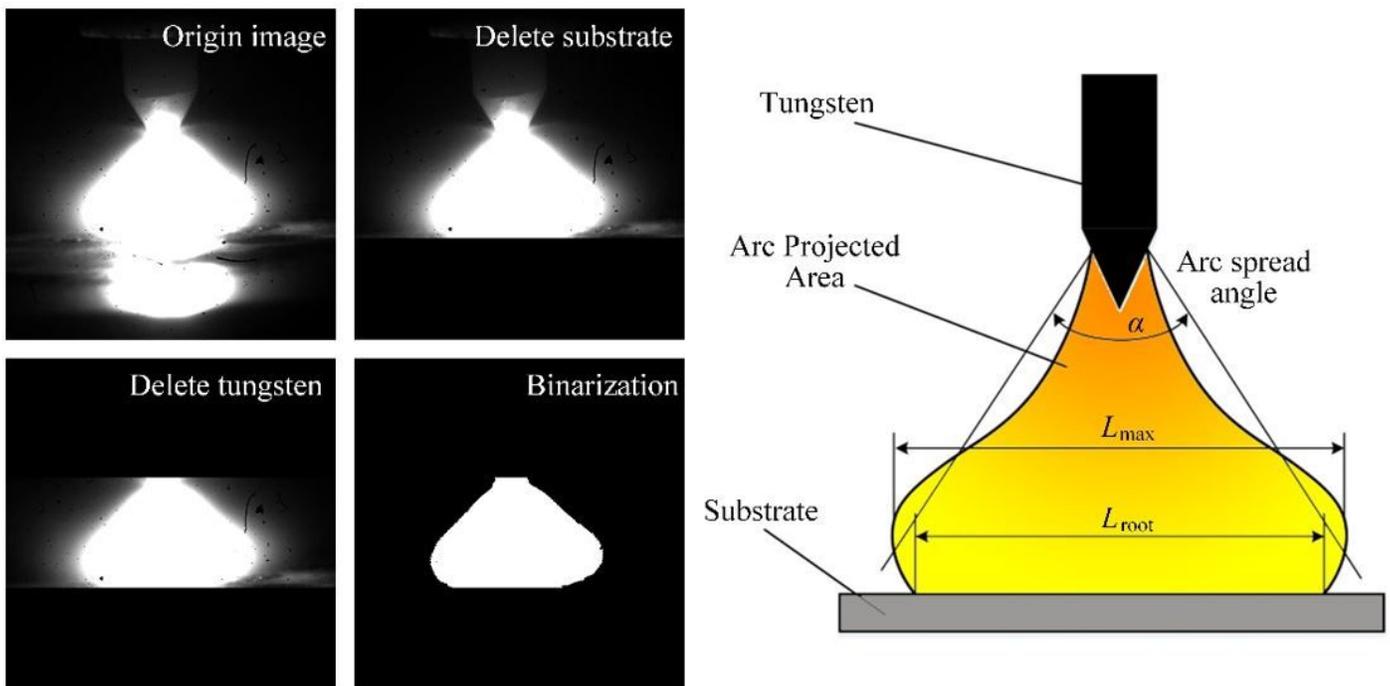


Figure 2

Arc image processing and parameter extracted from image

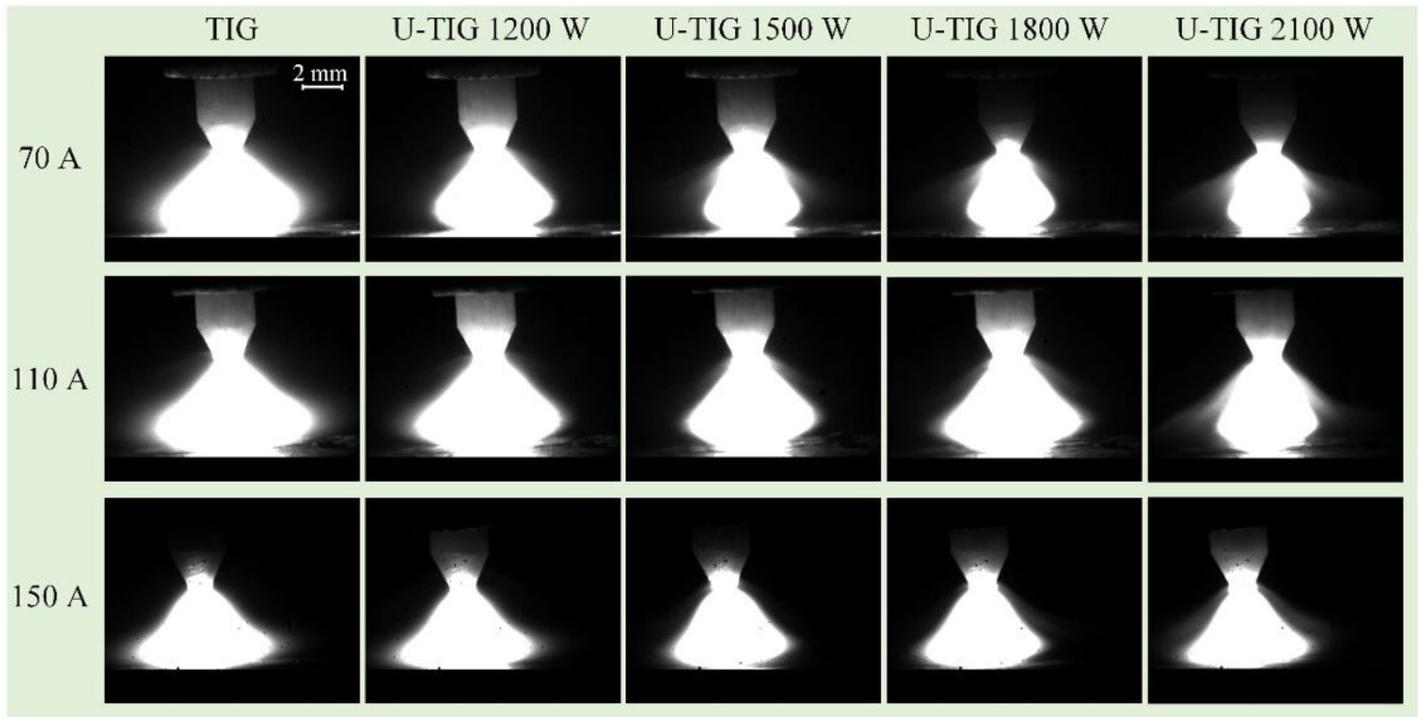


Figure 3

Influence of ultrasonic power on U-TIG arc behavior.

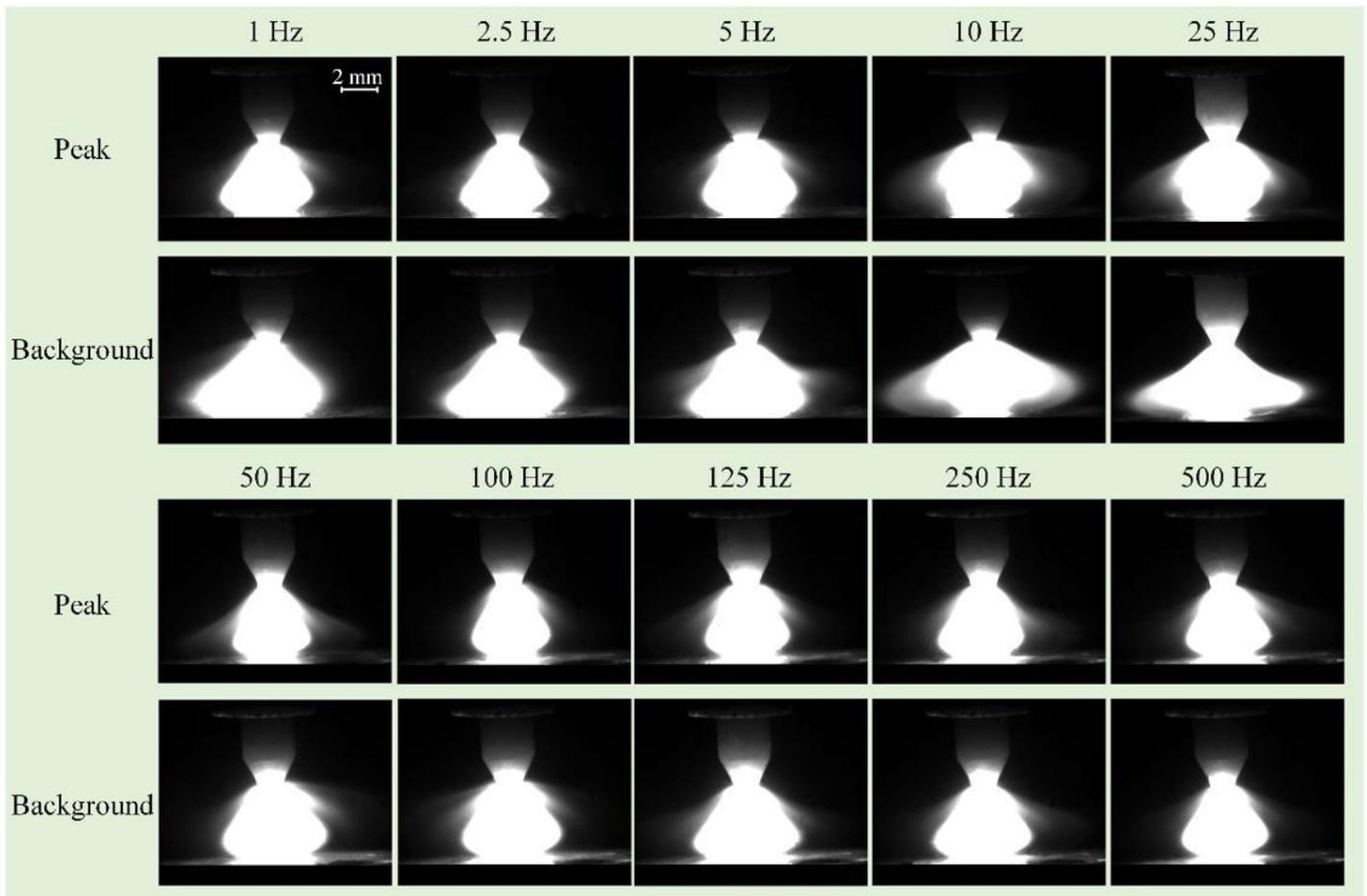


Figure 4

Influence of pulse frequency on PU-TIG arc behavior.

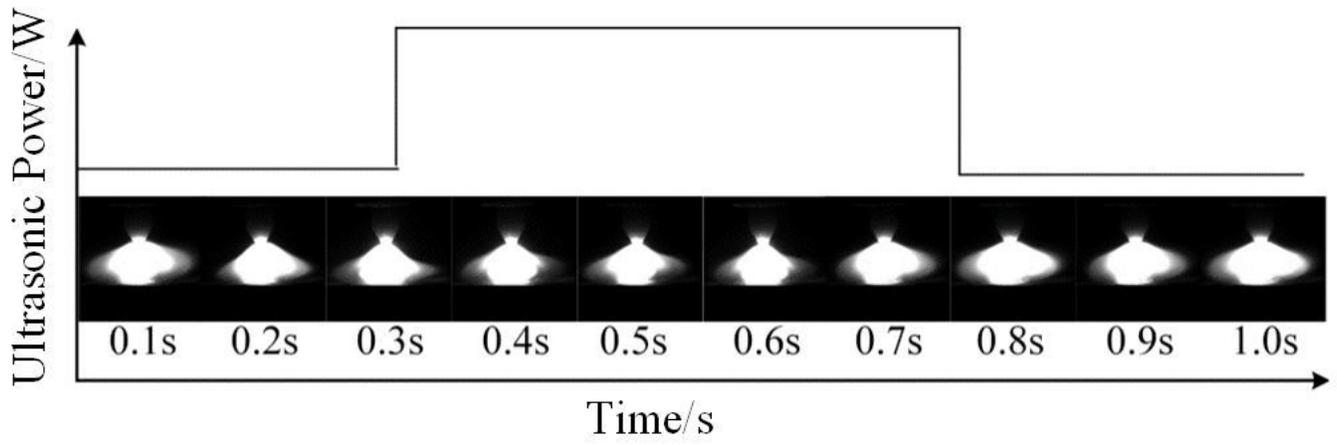


Figure 5

Arc shape during one pulse cycle.

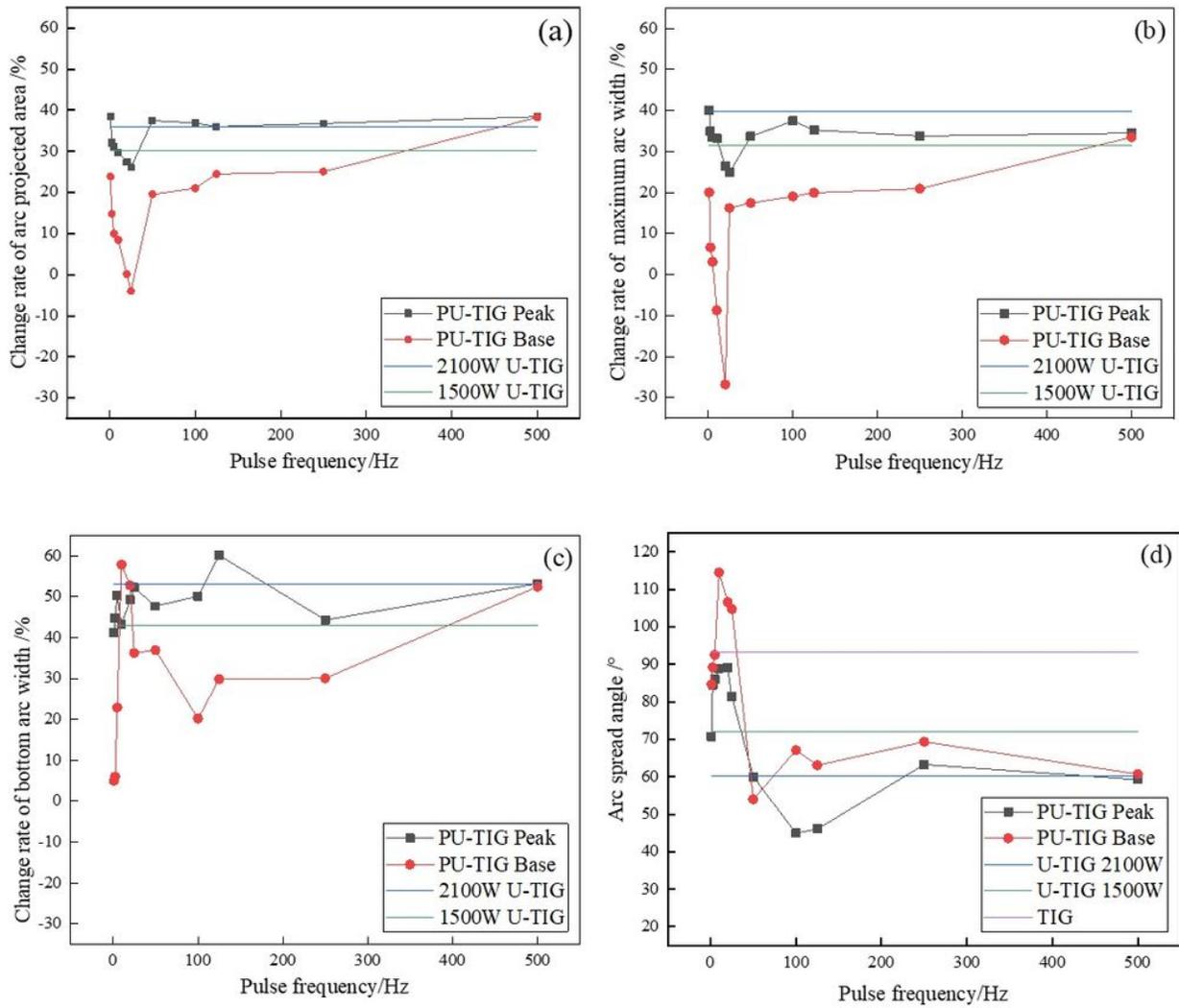


Figure 6

Effect of Pulse Frequency on PU-TIG Arc Shape. (a) change rate of arc projected area; (b) change rate of maximum arc width; (c) change rate of bottom arc width; (d) arc spread angle

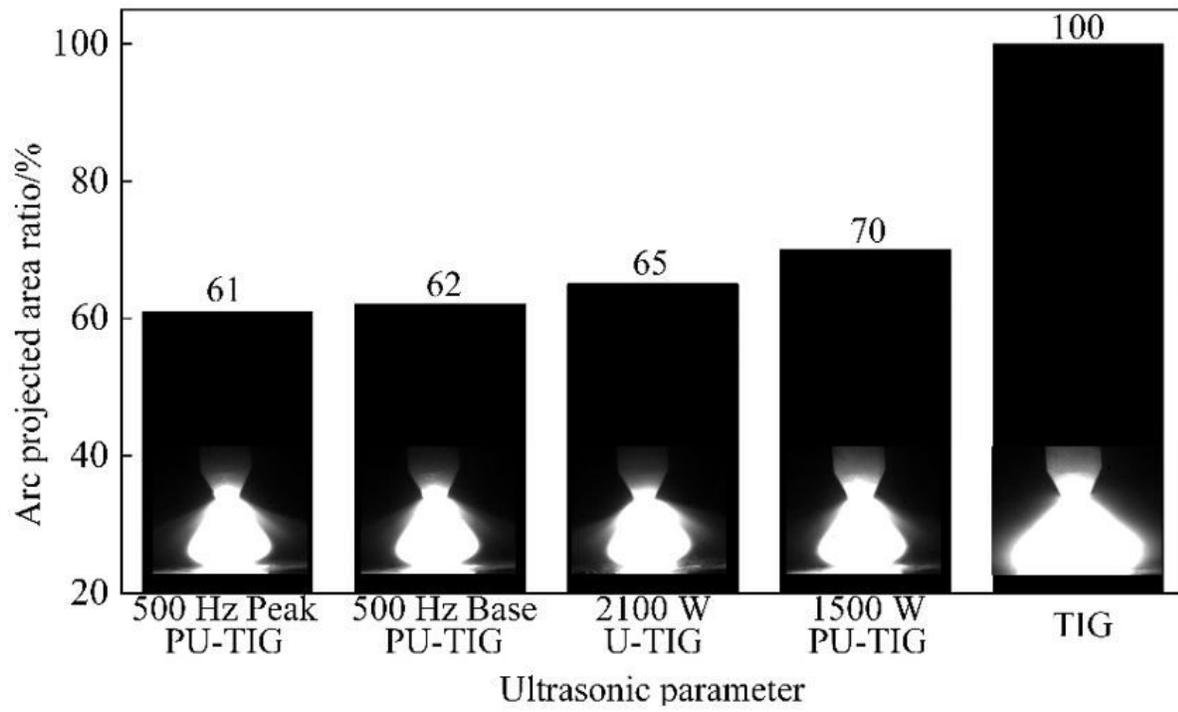


Figure 7

Arc projected area comparison.

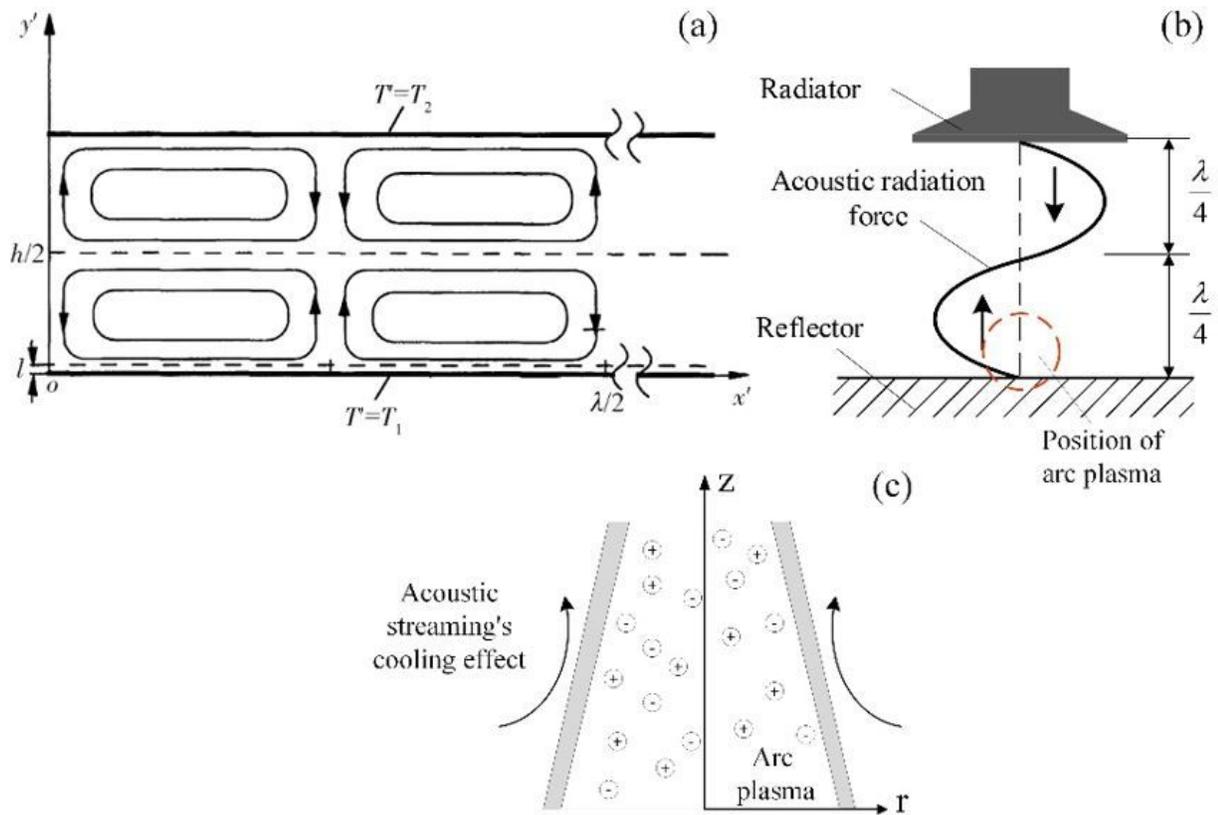


Figure 8

Mechanism of acoustic streaming and its effect on arc. (a) Rayleigh's acoustic streaming in a standing wave field [32]; (b) distribution of acoustic radiation force; (c) cooling effect of acoustic streaming on arc;

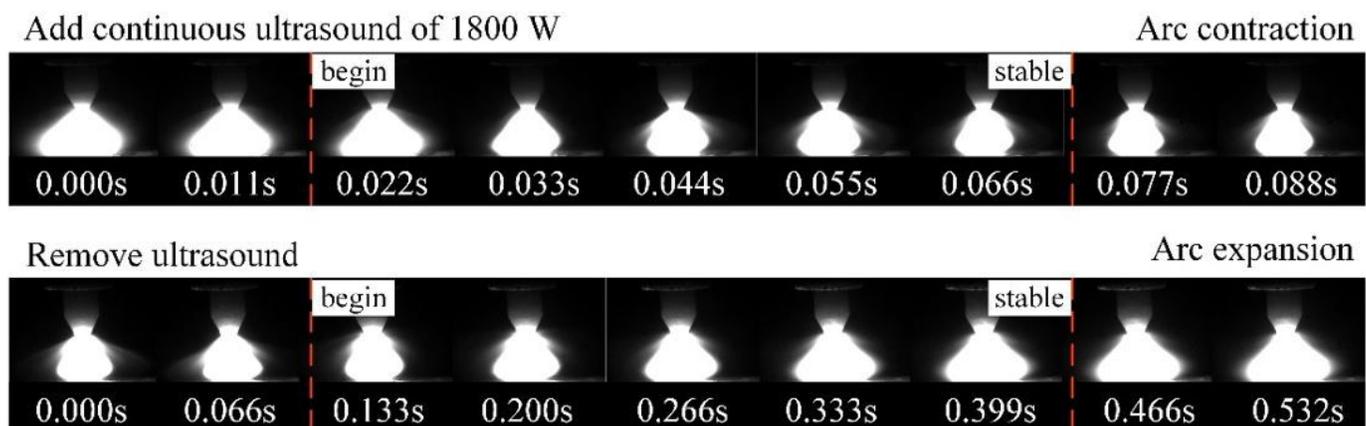


Figure 9

The speed of arc contraction and expansion