

Numerical Investigation of Residual Displacement of Rocking Self-Centering Columns Under Cyclic Loading

Yan Shi

Lanzhou University of Technology

zhengwu zhong (✉ zzw0730@163.com)

Lanzhou University of Technology <https://orcid.org/0000-0002-3662-4320>

Zhichao Zhang

Lanzhou University of Technology

Jianping Han

Lanzhou University of Technology

Hu Cheng

Jiangnan University

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Yan Shi^a, Zhengwu Zhong^{a,*1}, Zhichao Zhang^a, Jianping Han^a, Hu Cheng^{b,*}

^aSchool of Civil Engineering, Lanzhou University of Technology, Lanzhou730050,

China

^bSchool of Environment and Civil Engineering, Jiangnan University, Wuxi214122,

China

Corresponding author.

E-mail addresses: syky86@163.com(Y. Shi), zzw0730@163.com (Z. Zhong) , Zhangzhic0303@163.com (Z. Zhang), jphan1970@163.com(J. Han), hcheng@jiangnan.edu.cn(C. Hu).

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Yan Shi^a, Zhengwu Zhong^{a,*}, Zhichao Zhang^a, Jianping Han, Hu Cheng^{b,*}

*^aSchool of Civil Engineering, Lanzhou University of Technology, Lanzhou730050,
China*

*^bSchool of Environment and Civil Engineering, Jiangnan University, Wuxi214122,
China*

3 **Abstract**

4 Well-designed rocking self-centering (RSC) columns are capable of achieving small
5 residual displacement. However, few studies conducted the quantitative analysis for the
6 residual displacement of RSC columns. The residual displacement is the product of the
7 struggle between the self-centering (SC) capacity and the energy dissipation (ED)
8 capacity. In this study, a SC factor and an ED parameter were defined to reflect the SC
9 and ED capacity of the RSC column, respectively. The influence of eight common
10 design parameters on the SC factor and the ED parameter was explored using factorial
11 analysis. Parametric analysis was performed to investigate the tendency of the SC factor
12 and the ED parameter with the increase of maximum drift. According to the results of
13 the parametric analysis, the effect of the SC factor and the ED parameter on the
14 distribution of the residual drift was researched statistically. A simplified formula was
15 proposed to calculate the upper limit of the residual drift. What is more, a set of
16 predictive regression formulas was established to estimate the actual residual drift, these
17 regression formulas have an applicable condition that the ED parameter should be larger

18 than 0.75. When the ED parameter was less than 0.75, the residual drift is approximate
19 to zero.

20 **Keywords** Rocking self-centering column • Residual displacement • Cyclic
21 loading • Factorial analysis

22 **1. Introduction**

23 Past devastating earthquakes have demonstrated that the reinforced concrete (RC)
24 bridge structures are highly vulnerable to earthquakes with extensive damage
25 concentrated in plastic region of bridge pier (Han et al. 2009; Shi et al. 2020). It is likely
26 to cause large residual displacement as a result of serious damage. The bridge structure
27 with significant permanent displacement is hard to return back to the initial position,
28 which causes tremendous difficulties to the post-earthquake recovery and huge
29 economic losses (Kawashima et al. 1998). For example, about 100 RC bridge piers
30 were eventually demolished due to a residual drift ratio of 1.75% after the 1995 Kobe
31 earthquake in Japan (Kawashima et al. 1998). Therefore, the residual displacement is
32 regarded as a main index to evaluate the earthquake resilience and the self-centering
33 capacity of piers become an important design consideration (Uma et al. 2010; Palermo
34 and Mashal. 2012).

35 Based on accelerated bridge construction philosophy, the rocking self-centering
36 (RSC) column was proposed, and the post-tensioning has been considered to be an
37 efficient way to drastically reduce the residual displacement (Marsh et al. 2011). To data,
38 many experimental studies have been carried out to address the seismic behavior of
39 RSC columns (Hewes and Priestley. 2002; Palermo et al. 2007; Ou et al. 2010; Bu et al.

40 2016; Elgawady and Sha'lan. 2011; Guo et al. 2015; Han et al. 2019; Tong et al. 2019;
41 Cai et al. 2017; Roh and Reinhorn. 2010). Hewes and Priestley (2002) performed an
42 early cyclic test of the RSC column, the result shown that the segments of the pier
43 basically remained elastic and the residual drift was very small. However, the energy
44 dissipation (ED) capacity was extremely weak due to the lack of ED elements. To
45 enhance the ED capacity of RSC columns, various types of dissipaters were proposed
46 and the ED bar is the commonest ED device among these dissipaters. The results of
47 many cyclic tests shown that the hysteretic curve of the RSC column equipped with ED
48 elements was much fuller, and the ED capacity was improved as expected (Palermo et al.
49 2007; Ou et al. 2010; Bu et al. 2016; Elgawady and Sha'lan. 2011; Guo et al. 2015; Han
50 et al. 2019). Meanwhile, the added ED elements reduced the SC capacity of RSC
51 columns, leading to the problem of residual displacement could not be ignored if too
52 many dissipaters were used. Some researchers tried to use high performance materials
53 (e.g. shape memory alloy, fiber-reinforced polymer composite bar) to achieve a balance
54 between SC and ED capacity (Tong et al. 2019; Cai et al. 2017; Roh and Reinhorn.
55 2010). It can be concluded that there is a trade-off between the SC and ED capacity, the
56 residual displacement is the product of their mutual struggle.

57 The harm of residual displacement has been realized gradually, and residual
58 displacement has been regarded as an important consideration in seismic design.
59 According to earthquake damage investigation results, the Japan Road Association code
60 first proposed a reparability limit of 1% for RC columns (Japan Road Association,
61 2002). Some researches focusing on the residual displacement of RC columns have

62 been conducted, aiming to explore the influence factors and achieve the estimation of
63 residual displacement under earthquakes. It can be concluded that the residual drift is
64 determined by structural properties and characteristics of earthquake load both
65 (Liossatou and Fardis. 2016; Cheng et al. 2016; Liossatou and Fardis. 2015; Ji et al.
66 2018; Amiri and Bojorquez. 2019; Zhan and Jian. 2018; Quinde et al. 2019). However,
67 few studies related to the residual displacement estimation of RSC columns have been
68 reported. Li et al. (2020) selected residual drift as a performance index to conduct
69 seismic vulnerability analysis and losses assessment of an RSC bridge system. Ou et al.
70 (2007) developed a three-dimensional model of the RSC column equipped with internal
71 ED bars, the results of cyclic loading analyses suggested an optimum ED bar ratio of
72 0.5% around. Cai et al. (2019) performed cyclic analyses to investigate the influence of
73 post-tensioning force, gravity load, ED bar ratio and aspect ratio on the residual drift of
74 RSC columns. Liu et al (2018) carried out parametric analyses on residual displacement
75 under cyclic loading. Wang et al. (2019) proposed a simplified formula for UHPC
76 bridge columns with unbonded post-tensioning tendons to calculate the upper limit of
77 residual drift under cyclic loading. In conclusion, the residual drift of RSC columns
78 under cyclic loading mainly depends on structural properties, quantitative analysis of
79 residual drift is still limited in previous work.

80 The purpose of this study is exploring the distribution of residual drift of RSC
81 columns under cyclic loading and achieving its prediction. Two governing parameters
82 including a SC factor and an ED parameter were introduced to describe the SC capacity
83 and ED capacity of piers. The contribution of eight common design parameters to the

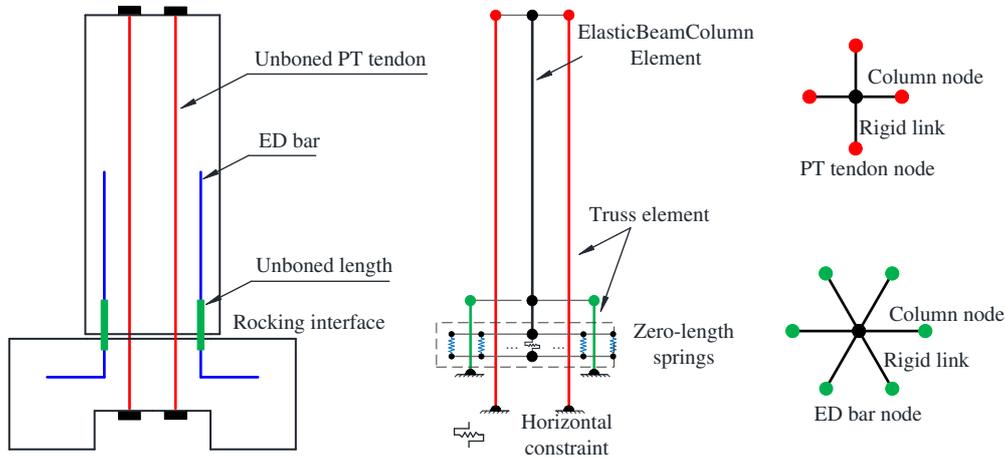
84 SC factor and ED parameter was compared. Then the effect of the SC factor and ED
85 parameter on the residual drift was investigated, a set of predictive formulas for the
86 residual drift was obtained from regressive analyses and an application of it was given.

87 **2. Simulation of RSC columns**

88 **2.1 Simulation method**

89 To capture the hysteretic behavior of the RSC columns, a numerical model is
90 established using OpenSees. Fig. 1 shows the schematic of the analytical model. The
91 displacement of the RSC columns is dominated by rigid rotation, the bending
92 deformation occurs before the column lifts up and its contribution is very small, so the
93 elastic beam-column elements can be used to model the column, this simplified
94 simulation strategy was also adopted in previous studies (Ahmdi and Kashani, 2020;
95 Marriott et al. 2009). A lumped mass is applied at the pier top to represent the gravity
96 load, and a horizontal constraint is set at the bottom to prevent the relative slide between
97 the column and the foundation. CorotTruss elements composed of
98 elastic-perfectly-plastic material are considered to model the force-displacement of the
99 unbonded post-tensioning (PT) tendons. The bottom nodes of the tendons are fixed, and
100 the top nodes are connected with the corresponding column node with rigid links. A
101 similar simulation method is adopted to model the unbonded segments of the energy
102 dissipation (ED) bars. Truss elements with Reinforcing Steel material are used to model
103 the ED bars, and the ultimate stress is set to 1.35 times as much as the yield stress f_y
104 (Priestley et al. 2007); the ratio of the tangent at initial strain hardening to the initial
105 elastic tangent can be set to 0.01-0.05 (Cai et al. 2019) (0.03 is selected in this study),

106 the ratio of strain corresponding to the initial strain hardening to the yield strain can be
 107 set to 3-5 (Cai et al. 2019) (3 is selected in this study), and the ultimate strain can be set
 108 to 0.1 (Kowalsky et al. 1995).



109

110

Fig. 1 Finite element model and cross-sections of existed test specimens

111 The total unbonded length of ED bars in numerical model, L_{ub} , consists of two
 112 parts. One is the designed unbonded length (L_0) which can prevent the early fracture of
 113 ED bars, the other is the equivalent unbonded length (L_{eu}) caused by the strain
 114 penetration. The L_{ub} can be expressed as:

115

$$L_{ub} = L_0 + L_{eu} \quad (1)$$

116

117 If $L_{eu}=0$, the value of L_{ub} is minimum, so the stress of ED bars is largest at the same
 118 lateral displacement. As a result, the strength of an RSC column will be overestimated.
 119 The value of L_{eu} is significant, but it is difficult to determine its value precisely because
 120 of the complexity of the strain penetration. For example, Mantawy et al. (2019)
 121 suggested to adopt an iterative method to determine the value of L_{ub} , the trial value of
 L_{ub} continued to increase until the correct bridge stiffness was calibrated.

122

Some formulas of L_{eu} can be found in the researches related to analytical pushover

123 method for RSC columns (Pampanin et al. 2001; Bu and Ou, 2013). According to the
 124 monolithic beam analogy, the stress of ED bars can be expressed as follows (Pampanin
 125 et al. 2001):

$$126 \quad \varepsilon_s = \frac{[(\Delta + 2/3l_{sp}\alpha\varepsilon_y)]}{(L_0 + 2l_{sp})} \approx \frac{\Delta}{(L_0 + 2l_{sp})} \quad (2)$$

127 where Δ is elongation of an ED bar, due to the opening of the joint; ε_y is yield strain
 128 of ED bars; α is ratio of elastic strain and yield strain in reinforcement; l_{sp} is strain
 129 penetration taken as $0.022f_yd_b$, f_y and d_b are the yield stress and diameter of ED bars,
 130 respectively. All units in MPa and mm. From Eq. (2), L_{eu} can be calculated as:

$$131 \quad L_{eu} = 2l_{sp} = 2 \times 0.022f_yd_b \quad (3)$$

132 In Bu's study, L_{eu} is calculated with Eq. (4) (Bu and Ou, 2013).

$$133 \quad L_{eu} = \begin{cases} 0 & , f_s > f_y \\ \frac{2.1 \times (f_s - f_y)}{(f_g)^{1.5}} d_b & , f_s > f_y \end{cases} \quad (4)$$

134 where f_s is stress of ED bars; f_g is compression strength of grout.

135 By trial calculation, it can be found that the calculated results obtained from Eq. (3)
 136 are much larger than the results of Eq. (4) generally. Therefore, Eq. (3) is used to
 137 determine the maximum value of L_{ub} . Though the precise value of L_{ub} is hard to
 138 determine, the range of L_{ub} can be estimated by Eq. (5), in the later analysis, the
 139 influence of L_{ub} on residual displacement will be discussed.

$$140 \quad \text{Min } L_{ub} = L_0 < L_{ub} < L_0 + 2 \times 0.022f_y d_b = \text{Max } L_{ub} \quad (5)$$

141 Several compression-only springs are used to model the opening and closing of the
 142 bottom rocking interface. Generally, the simulation result will become stable gradually

143 as the number of springs increases. These springs are distributed in a uniform way, the
 144 distance between two adjacent springs is equal and all springs have the same axial
 145 stiffness. The axial stiffness, k , can be calculated as (Li et al, 2020):

$$146 \quad k = \frac{2E_c A_g}{nH} \quad (6)$$

147 where $E_c = 4700\sqrt{f'_c}$ is the elastic modulus of the concrete, f'_c is the concrete
 148 compressive strength (Ahmdi and Kashani, 2020); A_g is the gross area of the column
 149 section; H is the column height; n is the number of zero-length springs.

150 2.2 Model validation

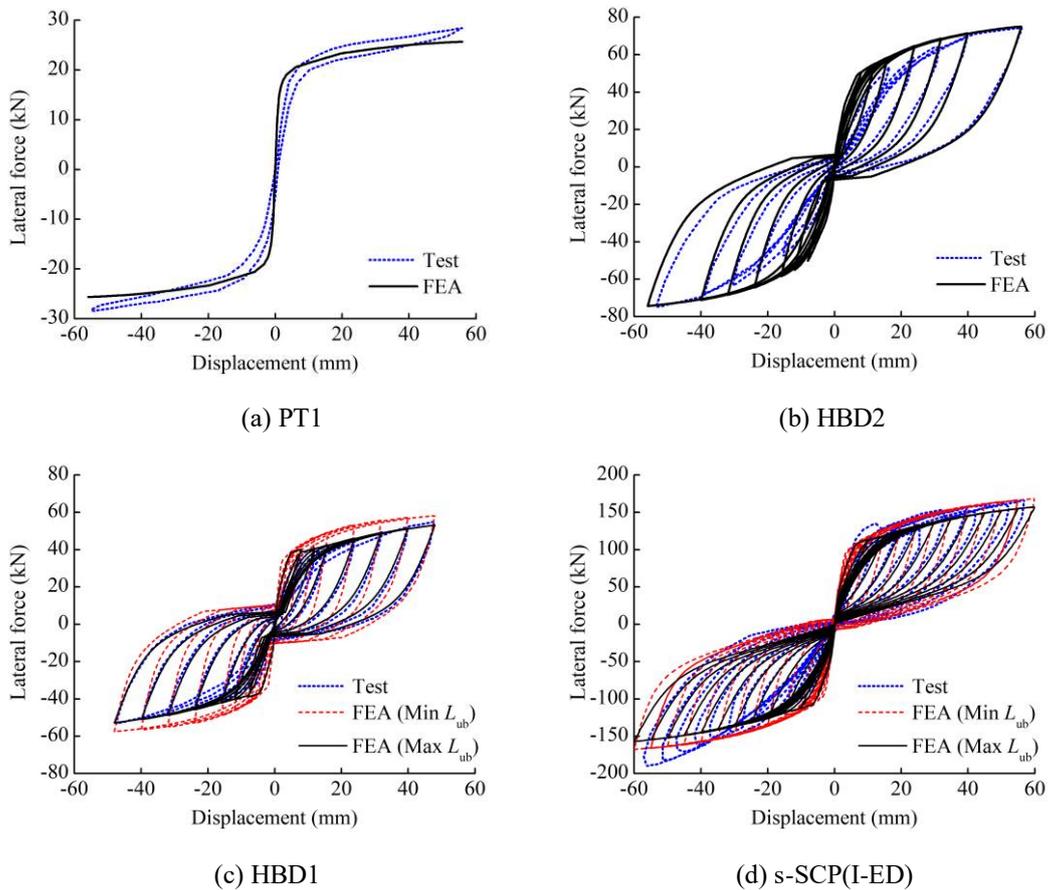
151 Table 1 Properties of selected specimen

Specimen	PT1	HBD2	HBD1	s-SCP(I-ED)
Geometry	350×350 mm	350×350 mm	350×350 mm	400×400 mm
Aspect ratio	4.57	4.57	4.57	3.78
Total axial load	200 kN	300k	200kN	533.05kN
Tendons	2×99 mm ²	4×99 mm ²	2×99 mm ²	4Φ15.2
	100 kN each	75 kN each	100 kN each	313.05 kN total
		4-HD20	4-D16	4-D20
Dissipation	None	12.5 mm diameter fuse	reinforcing steel	reinforcing steel
		50 mm fuse length	$L_0=50$ mm	$L_0=100$ mm
		$f_y=586$ MPa	$f_y=304$ MPa	$f_y=349$ MPa

152 In order to validate the simulation method, 4 RSC bridge pier specimens are
 153 selected (Palermo et al. 2007; Guo et al, 2012), as reported in Table 1. PT1 has no
 154 dissipation elements, it can be used to confirm the effectiveness of the modeling
 155 methods for all components in addition to ED bars. HBD2 chooses the reinforcing steel
 156 with a fuse length as the dissipation element. HBD1 and s-SCP(I-ED) dissipate energy
 157 by the internal reinforcing steel, the corresponding unbonded length is 50 mm and 100
 158 mm, respectively. More detailed information about these specimens can be found in

159 reference (Palermo et al. 2007; Guo et al, 2012).

160 As shown in Fig. 2, the numerical hysteretic curves are compared with the test
161 results. For specimen PT1 as shown in Fig. 2(a), the simulated initial stiffness is slightly
162 larger than the test result and the simulated strength was slightly lower. Besides,
163 because the elastic beam-column element is adopted to model the column, the simulated
164 hysteretic curve is unable to reflect the little energy dissipation during the cyclic loading.
165 On the whole, the FE result matches well with the test result, which suggests that the
166 simulation techniques except for ED bars are effective.



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169

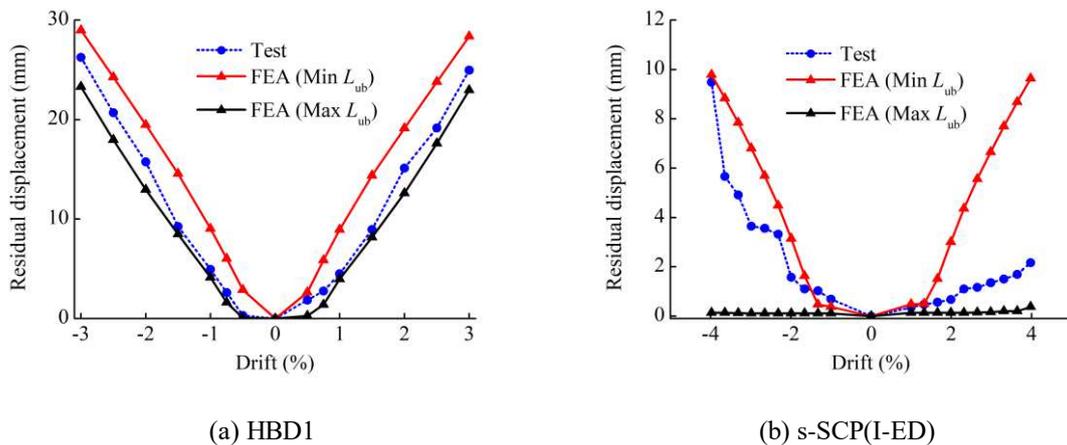
170

171

Fig. 2 Comparisons of the numerical hysteretic curve with the test results

172 Due to the reinforcing steel in specimen HBD2 has a fuse length of 50 mm, strain
173 will be concentrated on the fuse segment, so L_{ub} is set to 50 mm. The hysteretic curve

174 based on FEA is plotted in Fig. 2(b). As for specimens HBD1 and s-SCP(I-ED), detailed
 175 comparisons between test and simulation results are presented in Fig. 2(c) and (d). The
 176 red and black curves represent the simulation results corresponding to the minimum L_{ub}
 177 and the maximum L_{ub} , respectively. The lateral strength of the red curves is slightly
 178 larger than the black curves, it is because a smaller L_{ub} will generate a larger strain
 179 under the same joint opening, larger strain leads to larger dissipation force. As a result,
 180 the lateral strength is improved. Meanwhile, the residual displacement per loop of the
 181 red curves is also larger than the black curves, detailed comparisons are plotted in Fig. 3.
 182 On the one hand, this phenomenon can be explained from the perspective of larger
 183 dissipation force which weakens the self-centering capacity of the piers. On the other
 184 hand, the increase of L_{ub} will decrease the slope of unloading path significantly and thus
 185 diminish the residual displacement as shown in Fig. 2(c) and (d). The latter reason is
 186 more important, because the improvement of dissipation force is very limited.



187
 188 (a) HBD1 (b) s-SCP(I-ED)
 189 Fig. 3 Comparison of the numerical residual displacement with the test results

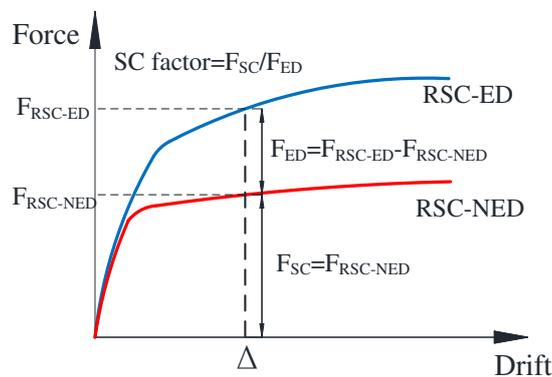
190 Based on the above analysis and Fig. 3, it can be concluded that the proposed
 191 simulation method is effective. However, there is uncertainty of L_{ub} in the modeling
 192 process, a conservative result of residual displacement will be obtained generally if the

193 strain penetration is not considered, and it is highly possible to underestimate the
 194 residual displacement if using Eq. (3) to calculate the equivalent unbonded length.

195 3. Governing design parameters for residual displacement

196 Two design parameters, the SC factor and ED parameter, are believed to have
 197 governing influence on the residual displacement.

198 3.1 Definition and calculation of SC factor



199

200

Fig. 4 Definition and calculation of SC factor

201 Several researchers have put forward different SC factor for evaluating the
 202 self-centering capacity of RSC columns. Hieber et al. (2005) proposed the re-centering
 203 ratio which is equal to the ratio between the total axial force (including the gravity force
 204 and initial prestressing force) and the yielding force of ED bars. The self-centering
 205 capacity of bridge columns at different drifts is usually different, while the re-centering
 206 ratio is a constant for an RSC column.

207 The contribution ratio λ_{SC} is another SC factor and it is typically adopted in the
 208 design of RSC systems (Palermo et al. 2007; Wang et al. 2019; Weng et al. 2010). λ_{SC}
 209 in its generic form represents the force or moment ratio between the self-centering
 210 contribution and the energy dissipation contribution, as shown in Eq. (7).

211
$$\lambda_{SC} = \frac{M_{\text{self-centering}}}{M_{\text{dissipation}}} = \frac{F_{\text{self-centering}}}{F_{\text{dissipation}}} \quad (7)$$

212 The self-centering and energy dissipation contribution can be derived from the
 213 monolithic beam analogy procedure (Pampanin et al. 2001). However, the iterative
 214 calculation process is still relatively complicated. What's more, λ_{SC} is obtained from
 215 theoretical calculation, while the residual displacement is determined by simulation. In
 216 order to reduce error, it is better that using simulation method to measure the
 217 self-centering performance index. For this reason, the SC factor λ_{SC} used in this study
 218 is defined as follows:

219
$$\lambda_{SC} = \frac{F_{SC}}{F_{ED}} \quad (8)$$

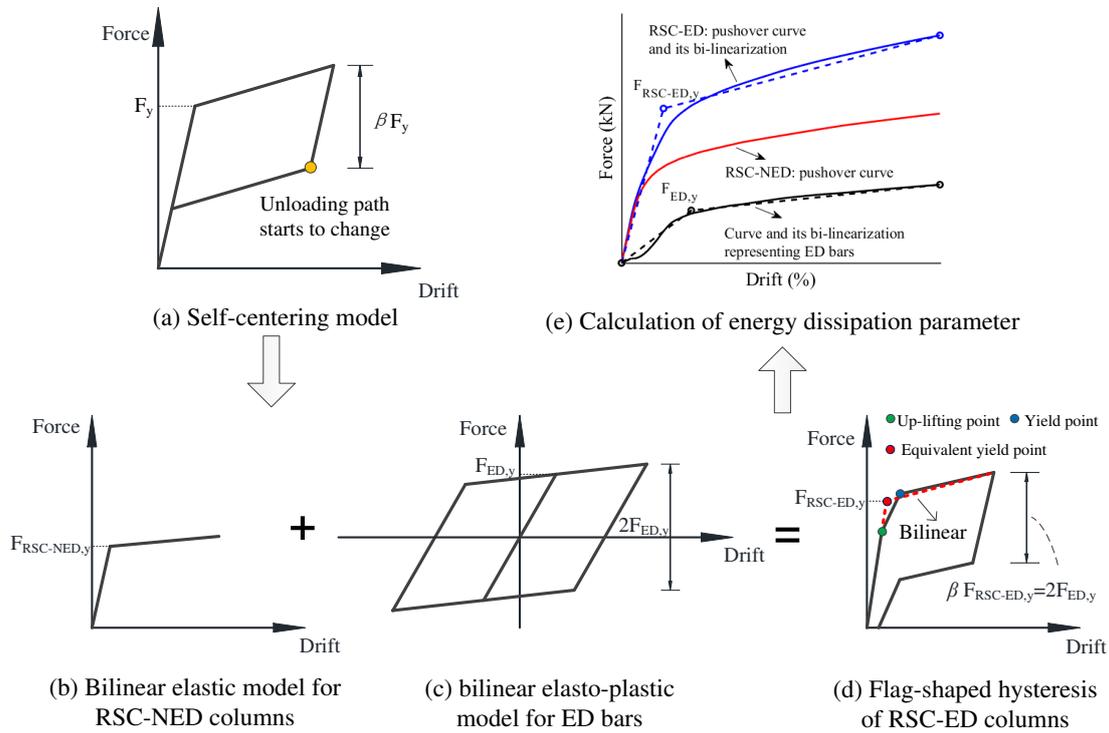
220 where F_{SC} is the self-centering contribution provided by gravity load and PT tendons,
 221 and F_{ED} is the energy dissipation contribution provided by ED bars. As shown in Fig. 4,
 222 the calculation of λ_{SC} requires the following two steps:

223 (1) Establish the numerical model of RSC-ED columns and conduct a pushover analysis,
 224 then the force-displacement curve can be obtained. The force F_{RSC-ED} includes the
 225 self-centering and energy dissipation contribution.

226 (2) Delete the ED bar elements from the existing numerical model of the RSC-ED
 227 column and perform a pushover analysis again, then the force-displacement curve which
 228 only contain the self-centering contribution is obtained. Therefore, the energy
 229 dissipation contribution F_{ED} can be derived as:

230
$$F_{ED} = F_{RSC-ED} - F_{RSC-NED} \quad (9)$$

231 **3.2 Definition and calculation of ED parameter**



232

233

Fig. 5 Definition and calculation of ED parameter

234

The second governing design parameter is ED parameter. The cyclic behavior of

235

RSC columns can be simplified into a flag-shaped hysteretic model as shown in Fig.

236

5(a). The ED parameter β is a significant parameter in this model, it not only reflects the

237

energy dissipation capacity of the model, but also controls the where the unloading path

238

starts to change. The smaller the ED parameter is, the earlier the unloading path changes,

239

leading to smaller residual displacement. Hence, it can be predicted that the ED

240

parameter has a non-ignorable influence on the residual displacement, while the recent

241

researches related to the residual displacement of RSC systems all did not consider it.

242

The self-centering model is so ideal that it is unable to capture the residual

243

displacement in fact. Implementing two rotational springs in parallel with appropriate

244

hysteretic models is another simplified simulation method. The RSC column without

245 ED bars is modelled by a bilinear elastic model, as shown in Fig.5 (b). The ED bar is
 246 simulated using a bilinear elasto-plastic model, as shown in Fig.5 (c). With the coaction
 247 of the two springs, the RSC column presents a trilinear skeleton curve to be exact, there
 248 is a stiffness reduction after the column is lifted up. Since the stiffness reduction is very
 249 slight, the skeleton curve can be approximate to a bilinear one.

250 To extract the ED parameter, an equivalent linearization method is used. The ED
 251 parameter can be calculated as:

$$252 \quad \beta = \frac{2F_{ED,y}}{F_{RSC-ED,y}} \quad (10)$$

253 where $F_{ED,y}$ is the yielding force of the bilinear elasto-plastic model; $F_{RSC-ED,y}$ is the
 254 effective yielding strength of the bridge column, as shown in Fig. 5(d).

255 Eq. (10) can be expressed approximately as:

$$256 \quad \beta \approx \frac{2F_{ED,y}}{F_{ED,y} + F_{RSC-NED,y}} = \frac{2}{1 + F_{RSC-NED,y} / F_{ED,y}} = \frac{2}{1 + \lambda_{SC,y}} \quad (11)$$

257 where $F_{RSC-NED,y}$ is the yielding force of the bilinear elastic model, $\lambda_{SC,y}$ is the SC
 258 factor that corresponds to the yield displacement. It can be found that the value of β is
 259 relatively stable, and it is smaller than 1 when the value of $\lambda_{SC,y}$ exceeds 1. As shown
 260 in Fig. 5(e), the calculation of β requires the following two steps:

261 (1) Establish the FE model of an RSC-ED column and perform a pushover analysis,
 262 then the obtained pushover curve is bilinearized according to the equal energy principle,
 263 the parameter $F_{RSC-ED,y}$ can be determined.

264 (2) Delete the ED bar elements from the FE model and carry out a pushover analysis
 265 again, then the force-displacement curve representing the energy dissipation

266 contribution can be plotted by subtraction. Conduct an equivalent linearization again
267 and the parameter $F_{ED,y}$ is obtained.

268 **4. Fractional factorial analysis**

269 In the actual construction of RSC columns, the key design parameters are
270 presented in the form of aspect ratio λ , concrete strength f_c , PT tendon ratio ρ_{PT} ,
271 axial-load ratio (η_G, η_{PT}) caused by gravity load P_G and PT force P_{PT} , ED bar ratio
272 ρ_{ED} , yield stress of ED bars f_y and unbonded length L_0 . It should be noted that the
273 non-dimensional parameters, the SC factor and ED parameter, can be regarded as the
274 comprehensive embodiment of these key design parameters. This part of study uses
275 fractional factorial analysis to discuss the effect of each parameter on the SC factor and
276 ED parameter at different drifts.

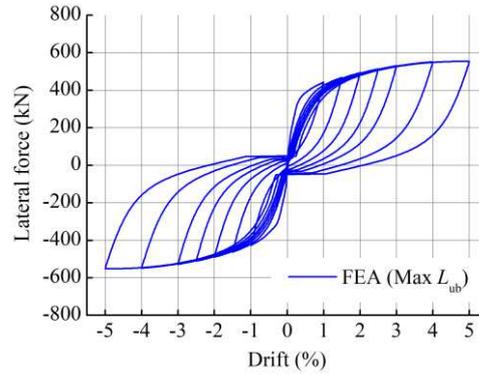
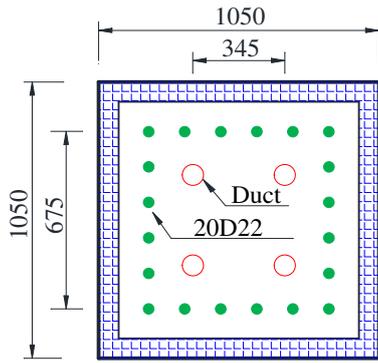
277 **4.1 Design parameters of reference specimen**

278 In the factorial analysis study, the reference specimen RS chooses the prototype of
279 specimen HBD1, the specimen HBD1 is 1/3 scaled, but the design parameters of
280 specimen RS are not strictly converted by a scale of 1:3 according to those of specimen
281 HBD1, as shown in Table 2. For example, in order to ensure the ED bars have enough
282 deformation capacity at larger loading drift, the value of L_0 of the specimen RS is set to
283 300 mm rather than 150 mm. The prototype pier of specimen HBD1 has a total mass of
284 180 t, but the gravity force was not applied in the test due to the limitation of the
285 experimental prestressing, the value of P_G of the specimen RS is 1800 kN. Meanwhile,
286 P_G will enhance the self-centering capacity of the specimen RS, which may lead to no
287 residual displacement. Therefore, the value of P_{PT} is set to 600 kN rather than 1800

288 kN.

289 Table 2 Comparison of the design parameters of specimens HBD1 and RS

Specimen	Width (mm)	λ	f_c (MPa)	ED bar	ρ_{ED} (%)	f_y (MPa)	L_0 (mm)	PT tendon	ρ_{PT} (%)	P_G (kN)	η_G	P_{PT} (kN)	η_{PT}
HBD1	350	4.57	54.1	4D16	0.66	304	50	2×99 mm ²	0.16	0	0	200	0.03
RS	1050	4.57	54.1	20D22	0.69	304	300	12D15.2	0.2	1800	0.03	600	0.01



290

(a) Cross-section

(b) hysteretic curve

291

292

Fig. 6 Cross-section and cyclic behavior of specimen RS (Unit: mm)

293

Fig. 6(a) shows the cross-section of the specimen RS, each duct holds 4 PT tendons,

294

and the diameter and tensile strength of each PT tendon are 15.2 mm and 1860 MPa,

295

respectively. The PT tendon ratio can be easily adjusted by changing the number of PT

296

tendons in each duct, the ED bar ratio can be changed by altering the diameter of ED

297

bars in the following study. The hysteretic curve of the specimen RS is plotted in Fig.

298

6(b). For specimen HBD1, the simulation result corresponding to the maximum value of

299

L_{ub} matches better with the test result, as shown in Fig. 2(c), so the maximum L_{ub} is

300

adopted in this part.

301

4.2 Two-level fractional design

302

The purpose of of this fractional factorial analysis is to evaluate the importance of

303

the key design parameters to the residual displacement of RSC columns. Table 3 shows

304

the key parameters and the two levels of each parameter. The ranges of the factors are

305 determined by the investigation of 19 RSC column specimens (Palermo et al. 2007; Ou
 306 et al. 2010; Tong et al. 2019; Bu et al. 2016; Marriott et al. 2009), the statistical results
 307 are also reported in Table 3. To prevent the PT tendon yields under cyclic loading, the
 308 value of P_d corresponding to its high level is set to 0.4, and the maximum loading drift
 309 is 4%.

310 Factorial analysis is used often when multiple factors exist in determining an
 311 output. However, the full factorial analysis requires a great number of runs if many
 312 factors are taken into account, which may become computationally expensive. In this
 313 study, the analysis includes eight factors and each factor has two levels, a complete
 314 factorial analysis needs 256 runs. In order to improve the efficiency, one-eighth factorial
 315 analysis is performed, which decreased the required runs to 2^{8-3} for a total of 32.

316 The approach Montgomery proposed (2008) is used to perform the fractional
 317 factorial analysis. The construction of a one- eighth factorial analysis consists of two
 318 parts. The first part is a basic design, which contains a complete 2^{8-3} fractional factorial
 319 combination (the first five columns in Table 4). The other part includes three generators
 320 (the last three columns in Table 4) which determines the factors that are not included in
 321 the basic design. – and + are the symbols of low level and high level, respectively. The
 322 levels of the last three factors are determined by using generating relations.

323 Table 3 Two levels of the considered factors

Level	λ	f_c	P_d	ρ_{PT}	η_G	L_0 (mm)	f_y (MPa)	ρ_{ED}
	(A)	(B)	(C)	(D)	(E)	(F=ABC)	(G=ABD)	(H=BCDE)
Range	4.42~5.29	32~65.9	0.12~0.51	0.13%~0.65%	0~0.1	50~400	300~600	0.26%~1.03%
- (low)	3.5	30	0.2	0.20%	0.02	150	300	0.46%
+ (high)	6	60	0.4	0.60%	0.1	450	600	1.12%

324 Note: P_d is the ratio between the initial stress of a PT tendon and its yield stress.

325 Table 4 2^{8-3} fractional factorial design

Case (Level)	Basic design					Generated from basic design		
	λ	f_c	P_d	ρ_{PT}	η_G	L_0	f_y	ρ_{ED}
	(A)	(B)	(C)	(D)	(E)	(F=ABC)	(G=ABD)	(H=BCDE)
1	-1	-1	-1	-1	-1	-1	-1	1
2	1	-1	-1	-1	-1	1	1	1
3	-1	1	-1	-1	-1	1	1	-1
4	1	1	-1	-1	-1	-1	-1	-1
5	-1	-1	1	-1	-1	1	-1	-1
6	1	-1	1	-1	-1	-1	1	-1
7	-1	1	1	-1	-1	-1	1	1
8	1	1	1	-1	-1	1	-1	1
9	-1	-1	-1	1	-1	-1	1	-1
10	1	-1	-1	1	-1	1	-1	-1
11	-1	1	-1	1	-1	1	-1	1
12	1	1	-1	1	-1	-1	1	1
13	-1	-1	1	1	-1	1	1	1
14	1	-1	1	1	-1	-1	-1	1
15	-1	1	1	1	-1	-1	-1	-1
16	1	1	1	1	-1	1	1	-1
17	-1	-1	-1	-1	1	-1	-1	-1
18	1	-1	-1	-1	1	1	1	-1
19	-1	1	-1	-1	1	1	1	1
20	1	1	-1	-1	1	-1	-1	1
21	-1	-1	1	-1	1	1	-1	1
22	1	-1	1	-1	1	-1	1	1
23	-1	1	1	-1	1	-1	1	-1
24	1	1	1	-1	1	1	-1	-1
25	-1	-1	-1	1	1	-1	1	1
26	1	-1	-1	1	1	1	-1	1
27	-1	1	-1	1	1	1	-1	-1
28	1	1	-1	1	1	-1	1	-1
29	-1	-1	1	1	1	1	1	-1
30	1	-1	1	1	1	-1	-1	-1
31	-1	1	1	1	1	-1	-1	1
32	1	1	1	1	1	1	1	1

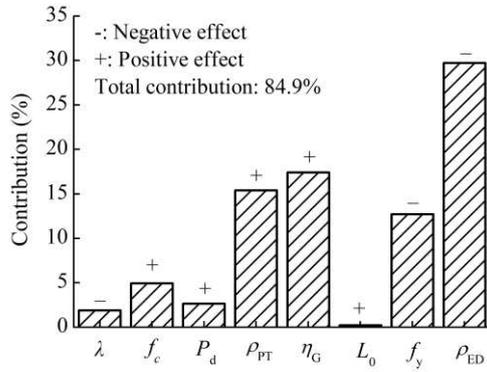
326 **4.3 Results of factorial analysis**

327 Based on the earthquake damage investigation results, the Japan Road Association
 328 (JRA) code proposed a residual drift limitation of 1% for RC columns to measure
 329 whether the columns could be repaired or not (Japan Road Association, 2002). If the

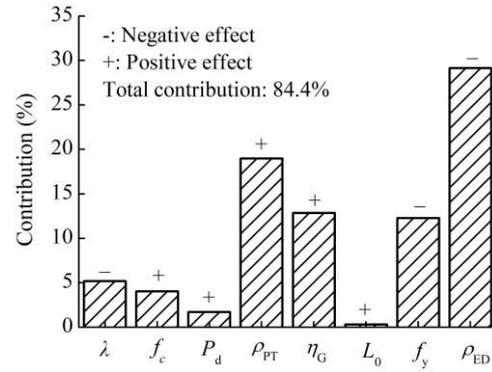
330 residual drift does not exceed 1%, the damaged column can be repaired generally. Due
 331 to the residual drift is always smaller than the peak drift, the SC factor and ED
 332 parameter at 1% drift are not concerned.

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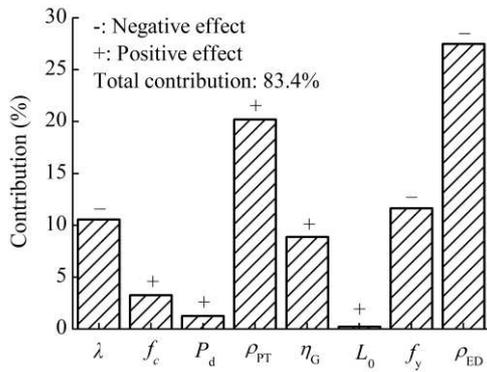
(a) 2% drift



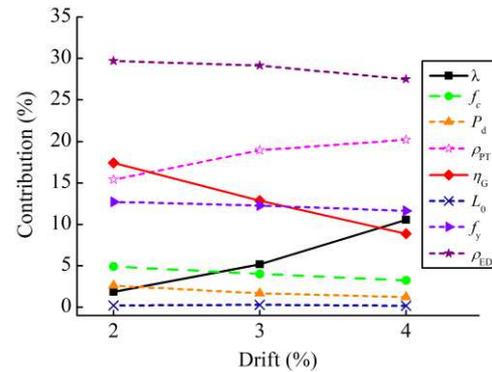
(b) 3% drift

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(c) 4% drift



(d) Change of contribution

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Fig. 7 Contribution of key parameters to SC factor under different drifts

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The effect of each key parameter on the SC factor at 2%, 3% and 4% drift is compared as shown in Fig. 7. Except for λ , f_y and ρ_{ED} , the else five parameters have positive influence on the SC factor. At the considered levels of the parameters, the most important parameters is ρ_{ED} , f_y , ρ_{TP} and η_G , the contribution of L_0 can be neglected. The change of contribution provided by each parameter is presented in Fig. 7(d), it can be observed that the change of the contribution provided by λ and η_G is the most notable. With the increase of drift, the contribution of λ increases from 1.9%

345 to 10.5%, while the contribution of η_G declines from 17.4% to 8.9%. This is because the
 346 larger aspect ratio and drift will aggravate the P- Δ effect. Meanwhile, the contribution of
 347 ρ_{TP} grows about 5%, which indicates the self-centering capacity is more dependent on
 348 ρ_{TP} at large drift. The total contribution is very stable and exceeds 83% no matter
 349 which drift is considered, no intense interaction between the parameters is observed.

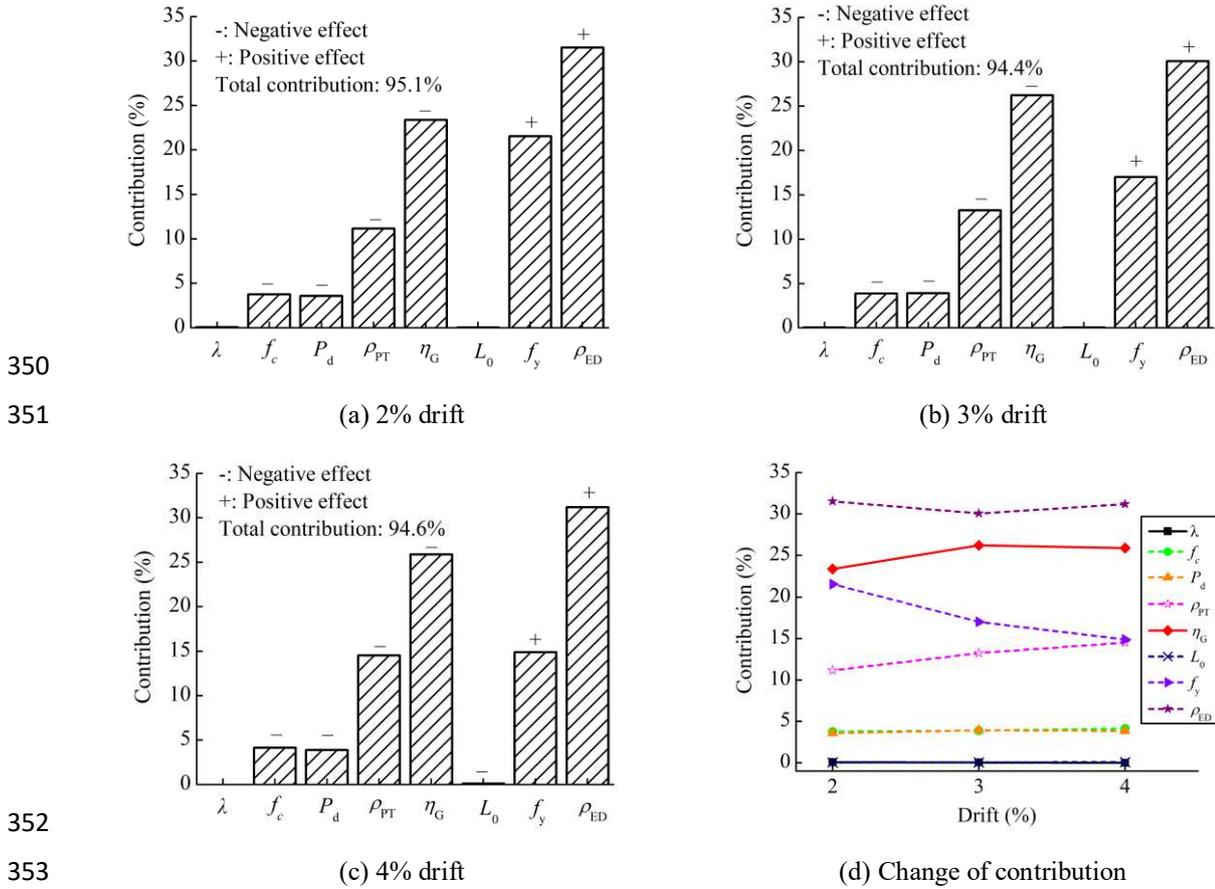


Fig. 8 Contribution of key parameters to ED parameter under different drifts

355 As shown in Fig. 8, the contribution of each factor to the ED parameter at 2%, 3%
 356 and 4% drift is compared. f_c , P_d , ρ_{TP} and η_G have a negative effect, f_y and
 357 ρ_{ED} have a positive effect, the effect of λ and L_0 is approximate to zero. The most
 358 significant parameters are ρ_{ED} , f_y , η_G and ρ_{TP} . As shown in Fig. 8(d), the
 359 contribution of these parameters excluding f_y basically remains the same, the

360 contribution of f_y decreases from 21.5% to 14.9% as the drift increases from 2% to
 361 4%. On the other hand, the total contribution at the three loading drifts all reaches 94%,
 362 it can be concluded that the ED parameter is dominated by the effect of single factor and
 363 the interaction between the factors is very slight. Here, the ED parameter β is fitted
 364 with a linear regression model which can be expressed as follows:

$$365 \quad \beta = a_0 + a_1 x_1 + a_2 x_2 + a_3 x_3 + a_4 x_4 + a_5 x_5 + a_6 x_6 \quad (12)$$

366 where x_1, x_2, x_3, x_4, x_5 and x_6 are the normalized parameters representing the effect
 367 of $f_c, P_d, \rho_{TP}, \eta_G, f_y$ and ρ_{ED} . For example, $x_1 = (\lambda - 45) / 15$. The normalized
 368 parameters range from -1 to 1 (corresponding to low and high levels). The obtained
 369 corresponding coefficients of the regression model are given in Table 5.

370 Table 5 Coefficient values of the regression model for β

Drift	Coefficients						
	a_0	a_1	a_2	a_3	a_4	a_5	a_6
2%	0.760	-0.062	-0.060	-0.106	-0.154	0.148	0.179
3%	0.749	-0.062	-0.062	-0.115	-0.161	0.130	0.173
4%	0.746	-0.063	-0.061	-0.118	-0.157	0.119	0.173

371 5. Formula to predict residual drift under cyclic loading

372 The purpose of this part is exploring the effect of the SC factor and ED parameter
 373 on the distribution of the residual drift, and predicting the residual drift under cyclic
 374 loading. Due to there are two directions during a full cycle, the residual drift D_{res} is
 375 defined as:

$$376 \quad D_{res} = \frac{D_{-res} + D_{+res}}{2} \quad (13)$$

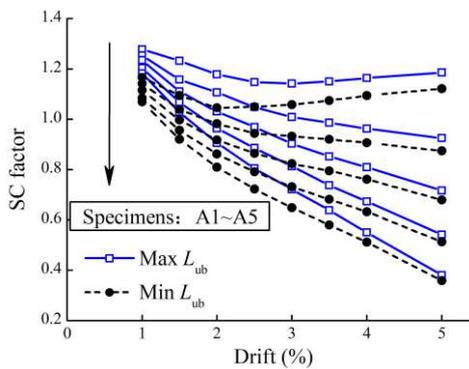
377 where D_{-res} and D_{+res} are the residual drift corresponding to the negative and positive
 378 loading directions, respectively.

379 **5.1 Parametric study**

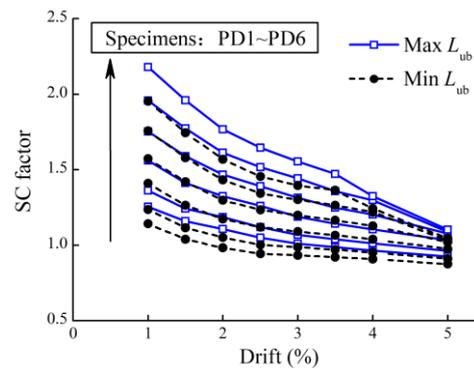
380 In order to obtain enough data to analyze the distribution of residual drift, a
 381 parametric study is first carried out. Table 6 shows the all the specimens used in the
 382 parametric study, the specimens are designed based on the specimen RS. Each specimen
 383 has a special denotation which corresponding to a value of the parameter. For example,
 384 for the aspect ratio λ , five specimens are designed and tagged with A1, A2, A3, A4 and
 385 A5. Among these tags, A1 corresponds to a value of 3.6.

386 Table 6 Denotation of specimens in parametric study

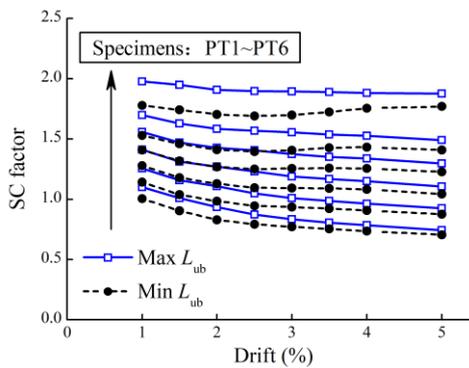
Parameters	Denotation	Parameter values for each specimen
λ	A1, A2, A3, A4, A5 (A1-A5)	3.6, 4.6, 5.5, 6.5, 7.4
P_d	PD1, PD2, PD3, PD4, PD5, PD6 (PD1-PD6)	0.15, 0.2, 0.3, 0.4, 0.5, 0.6
ρ_{PT}	PT1, PT2, PT3, PT4, PT5, PT6 (PT1-PT6)	0.13%, 0.2%, 0.26%, 0.33%, 0.4%, 0.53%
η_G	G1, G2, G3, G4, G5 (G1-G5)	0.03, 0.045, 0.06, 0.075, 0.091
L_0	L1, L2, L3, L4, L5 (L1-L5)	300 mm, 400 mm, 500 mm, 600 mm, 700 mm
f_y	F1, F2, F3, F4, F5 (F1-F5)	304 MPa, 350 MPa, 400 MPa, 450 MPa, 500 MPa
ρ_{ED}	E1, E2, E3, E4, E5, E6 (E1-E6)	0.46%, 0.69%, 0.89%, 1.12%, 1.46%, 2.28%



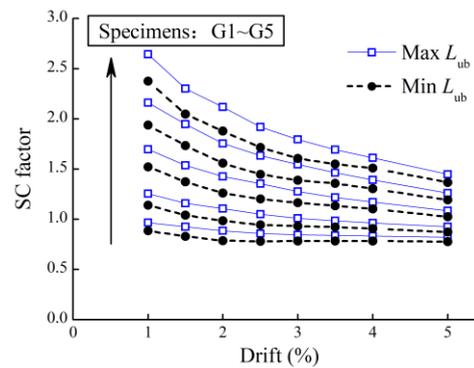
(a) Aspect ratio



(b) Ratio between initial stress and yield stress



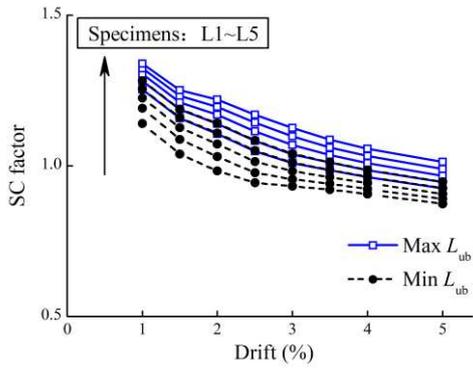
(c) PT tendon ratio



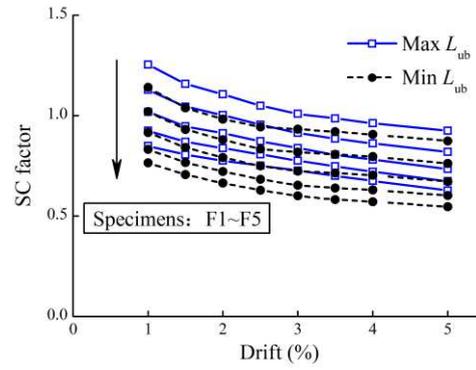
(d) Gravity axial load

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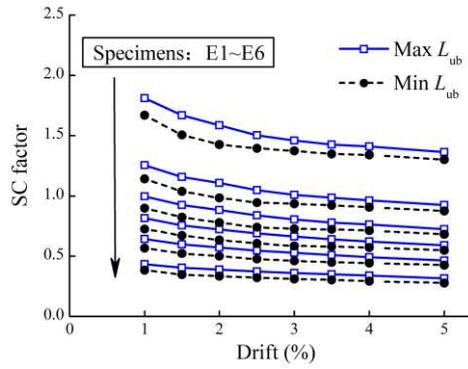
389
390



(e) Unbonded length of ED bars

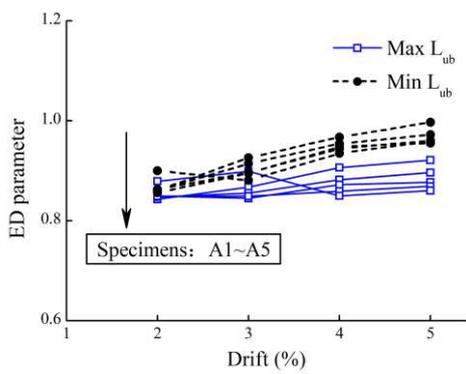


(f) Yield stress of ED bars

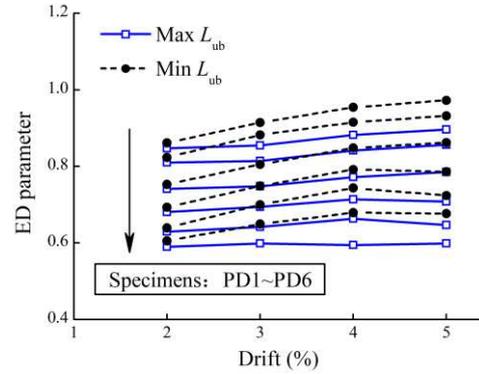


(g) ED bar ratio

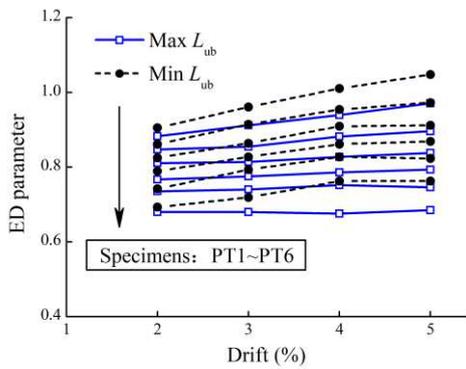
Fig. 9 Influence of each parameter on SC factor



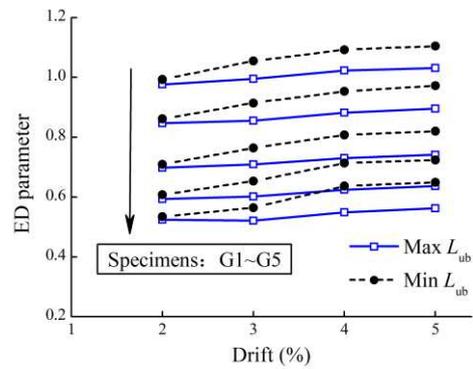
(a) Aspect ratio



(b) Ratio between initial stress and yield stress



(c) PT tendon ratio



(d) Gravity axial load

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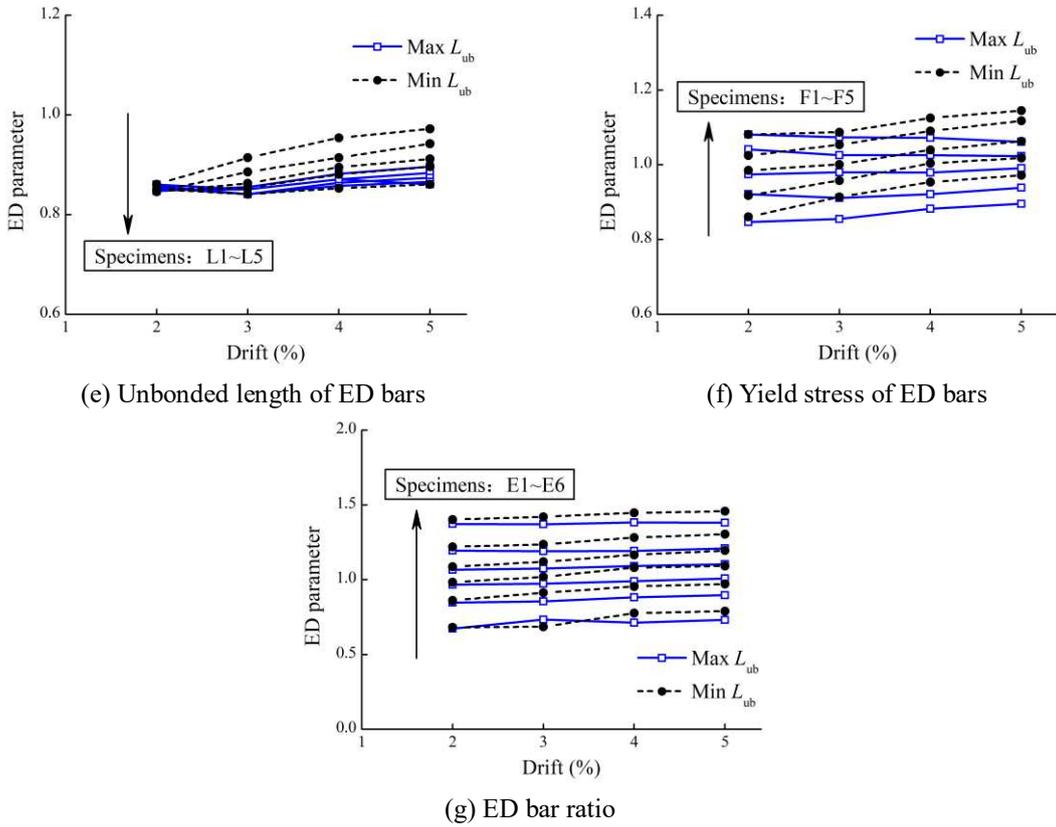


Fig. 10 Influence of each parameter on ED parameter

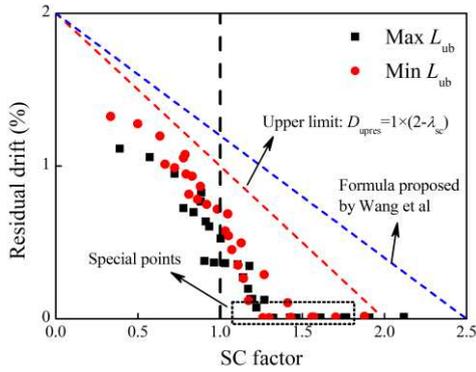
Fig. 9 shows the influence of each parameter on the SC factor, the uncertainty of L_{ub} in the simulation process is considered. It can be concluded that the value of the SC factor corresponding to minimum L_{ub} is always smaller than that corresponding to maximum L_{ub} , which indicates that the self-centering capacity of bridge columns will be underestimated if the strain penetration is not considered. The uncertainty of L_{ub} has little influence on the change tendency of the SC factor, the SC factor presents a downward trend as the drift increases.

As shown in Fig. 9(a), the five specimens (A1-A5) have a similar SC factor at 1% drift. With the increase of drift, the SC factor of the specimen with a larger aspect ratio descends more rapidly because of the P- Δ effect. Specimen A1 is different from other specimens, its SC factor has a slight growth when the drift exceeds a certain value.

416 Increasing P_d , ρ_{PT} , η_G and L_0 are all benefit to improve the self-centering force, so
417 their increase will enhance the SC factor as shown in Fig. 9(b), (c), (d) and (e). The
418 improvement effect of P_d and η_G on the SC factor is very similar and dependent on
419 the drift as shown in Fig. 9(b) and (d), a larger P_d and η_G can generate a larger SC
420 factor generally, but the self-centering capacity is not stable, which decreases sharply at
421 the drift increases. As shown in Fig.9 (c), it can be concluded that increasing the PT
422 tendon ratio is an effective method to strength the stability of the self-centering capacity.
423 Compared to P_d , ρ_{PT} and η_G , the effect of L_0 on the SC factor is very limited as
424 shown in Fig.9 (e). The value of L_0 increase from 300 mm to 700 mm, while the
425 increase of SC factor does not exceed 0.3. Increasing f_y or ρ_{ED} is helpful to improve
426 the energy dissipation capacity, so their increase will reduce the SC factor as shown in
427 Fig. 9(f) and (g). There is a greatest reduction of the SC factor when ρ_{ED} increases
428 from 0.46% to 0.69% as shown in Fig. 9(g).

429 Similarly, Fig. 10 shows the influence of each parameter on the ED parameter, it
430 can be observed that the ED parameter corresponding to the minimum L_{ub} is larger than
431 that corresponding to the maximum L_{ub} commonly. With the increase of drift, the ED
432 parameter shows a slight uptrend, it keeps stable on the whole and its largest growth
433 does not reach 0.2. As shown in Fig. 10(a), (b), (c), (d) and (e), increasing λ , P_d , ρ_{PT} ,
434 η_G and L_0 are able to reduce the ED parameter, especially for η_G , P_d and ρ_{PT} , their
435 reduction effect is more remarkable, and the effect of λ and L_0 is relatively limited.
436 Increasing f_y and ρ_{ED} are capable of improve the ED parameter as shown in Fig.
437 10(f) and (g).

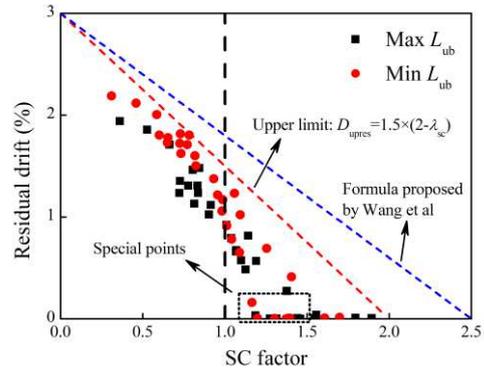
438 **5.2 Regression analysis**



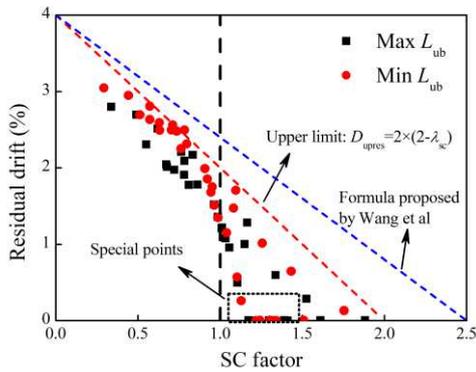
439

440

(a) 2% drift



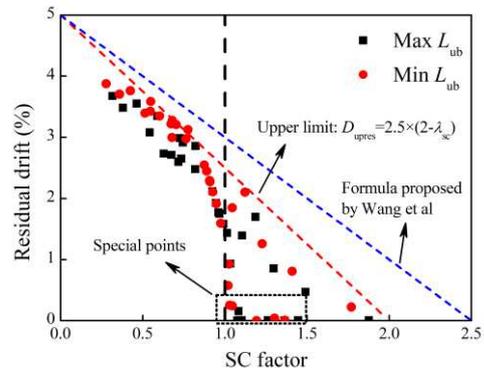
(b) 3% drift



441

442

(c) 4% drift



(d) 5% drift

443

Fig. 11 Effect of SC factor on residual drift distribution

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As shown in Fig.11, the data obtained from the parameter analysis are collected to

445

investigate the influence of the SC factor on the residual drift distribution. The black

446

points correspond to the maximum L_{ub} and the red points corresponds to the minimum

447

L_{ub} . The red points are located at the upper boundary of the black points. The upper

448

limit of the residual drift is dominated by two key coordinate points which are (2, 0) and

449

(0, D_{max}). Point (2, 0) indicates that the residual drift is equal to zero if the SC factor

450

reaches 2; point (0, D_{max}) indicates that the residual drift is equal to the maximum drift

451

if the SC factor is 0. The upper limit of residual drift D_{upres} at different drifts can be

452

expressed as Eq. (14). Wang et al. (2019) proposed a formula for the RSC UHPC bridge

453 column with a hollow section to calculate the upper limit of residual drift, as shown in
 454 Eq. (15). Eq. (14) is very similar to Eq. (15), the only difference is that Eq. (15) believes
 455 the residual drift is equal zero when the SC factor is 2.5. Therefore, Eq. (15) is more
 456 conservative as shown in Fig. 11. However, it does not mean that the concrete material
 457 or the section shape have great influence on the upper limit of residual drift. In (Wang et
 458 al. 2019), the SC factor defined as the moment contribution ratio is obtained by
 459 theoretical calculation, while the residual drift is obtained from the numerical results,
 460 which will amplify the error.

$$461 \quad D_{\text{upres}} = D_{\text{max}} \times (1 - 0.5\lambda_{\text{SC}}) \quad (14)$$

$$462 \quad D_{\text{upres}} = D_{\text{max}} \times (1 - 0.4\lambda_{\text{SC}}) \quad (15)$$

463 In addition, the residual drift exhibits a feature of linear distribution. However,
 464 there are some special points the SC factors of which exceed 1, while the corresponding
 465 residual drift is very small and approximate to zero. These special points show an
 466 entirely different pattern of distribution. In order to explain the phenomenon, the source
 467 of these special points is checked, finding most of them are obtained from the
 468 specimens PD1-PD6, PT1-PT6, and G1-G5. P_d , ρ_{PT} and η_G all have great negative
 469 effect on the ED parameter, so the influence of the ED parameter on the residual drift
 470 distribution is studied as shown in Fig. 12. When the ED parameter exceeds 0.75, the
 471 residual drift is very sensitive to it, especially within the range of 0.75 to 1.0, the
 472 residual drift grows rapidly as the ED parameter increases; when the ED parameter
 473 exceeds 1.0, the residual drift increases in a smooth way. Meanwhile, the distribution of
 474 residual drift is stratified because the residual drift depends heavily on the maximum

475 drift. On the other hand, it can be concluded that the residual drift is close to zero when
476 the ED parameter is less than 0.75, which is not related to the maximum drift.

477 As shown in Fig.13, the data in Fig.11 are collected and the points of which the ED
478 parameter is larger than 0.75 are removed. It can be found that the most of the special
479 points are filtered out, and the filtered data exhibit a more obvious linear distribution
480 characteristic. Regression analyses are performed for the filtered data, and the relation
481 between the residual drift at a certain drift and the SC factor is established as follows:

$$482 \quad D_{\text{res},2\%} = -1.4\lambda_{\text{SC}} + 1.936 \quad (16a)$$

$$483 \quad D_{\text{res},3\%} = -1.972\lambda_{\text{SC}} + 2.974 \quad (16b)$$

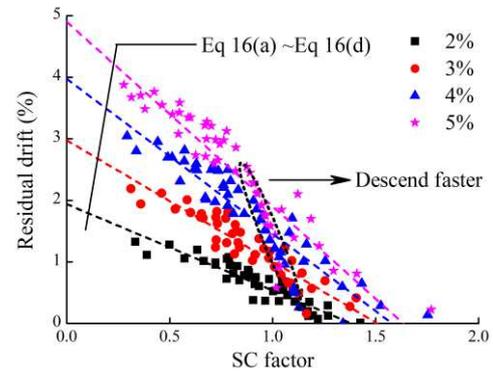
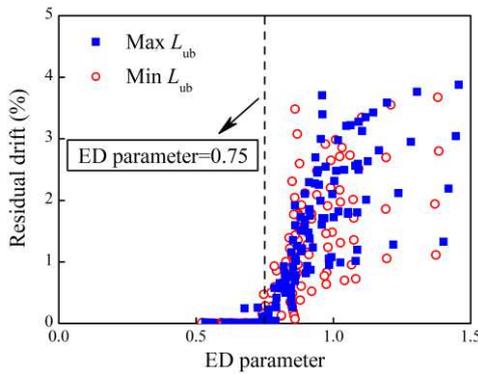
$$484 \quad D_{\text{res},4\%} = -2.515\lambda_{\text{SC}} + 3.973 \quad (16c)$$

$$485 \quad D_{\text{res},5\%} = -3\lambda_{\text{SC}} + 4.9 \quad (16d)$$

486 where $D_{\text{res},2\%}$, $D_{\text{res},3\%}$, $D_{\text{res},4\%}$, and $D_{\text{res},5\%}$ were the residual drifts at 2, 3, 4, and 5%
487 drift. It should be noted the set of formula can be used to estimate the residual drift
488 under cyclic loading on the premise that the ED parameter exceeds 0.75. If the
489 parameter is smaller than 0.75, the residual drift can be ignored. The correlation
490 coefficients of Eq. (16a), Eq. (16b), Eq. (16c), Eq. (16d) are 86.6%, 85.6%, 85.4%
491 and 84.8%, respectively.

492 Too large value of L_0 is an important reason leading to the discreteness of the
493 formulas. As shown in Fig.13, there are lots of points descend faster as the SC factor
494 increases, this is because too large value of L_0 will change the unloading path and
495 aggravates the pinching effect, meanwhile, the SC factor is not sensitive to L_0 . As a
496 result, the residual drift is reduced at the cost of a slight reduction in strength and energy

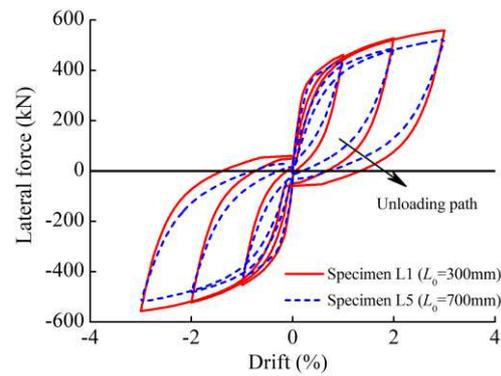
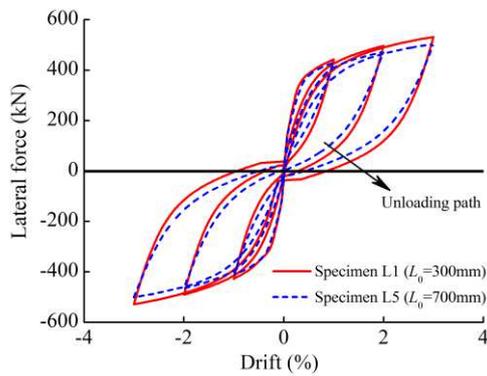
497 dissipation capacity. A Comparison of the hysteretic curves between specimen L1 and
 498 L5 are given as an example, as shown in Fig.14. In fact, a too long unbonded length will
 499 not be designed generally due to it may lead to the buckling of ED bars, so it is
 500 unnecessary to pay much attention on the effect of L_0 .



501

502 Fig. 12 Effect of ED parameter on residual drift distribution

Fig. 13 Regression analysis



503

(a) Maximum L_{ub}

(b) Minimum L_{ub}

504

505 Fig. 14 Comparison of hysteretic curves between specimen L1 and L5

506 Palermo et al. (2007) conducted a cyclic loading test on four RSC bridge pier
 507 specimens. These specimens were named PT1, HBD1, PT2 and HBD2, the only
 508 different between specimen PT1 (PT2) and HBD1 (HBD2) is the former lacks of ED
 509 bars. The SC factors and ED parameters of specimen HBD1 and HBD2 can be obtained
 510 from the test results. A comparison of the test results with the predictive residual drift is
 511 given as shown in Table 7.

512 Table 7 Comparison of the test results with predictive results

Specimens	Drift	SC factor	ED parameter	Residual drift (%)		
				Test	Upper limit	Predictive result
HBD1	2%	1	0.98	0.94	1	0.54
	3%	0.98	0.97	1.55	1.53	1.04
HBD2	2%	1.4	0.83	0.23	0.6	0

513 **6. Conclusion**

514 This paper uses numerical method to investigate and predict the residual
515 displacement of RSC columns under cyclic loading. The SC factor and ED parameter
516 are regarded as the important parameters to govern the residual displacement. The
517 contribution of eight design parameters at different drifts is discussed by factorial
518 analysis. The effect of the SC factor and ED parameter on the residual drift distribution
519 is analyzed statistically. During the process, the uncertainty of L_{ub} in numerical model is
520 considered. Finally, a set of predictive formulas is proposed by regression analyses.

521 Based on the analyses, the following conclusions can be drawn:

522 (1) Ignoring the strain penetration of ED bars will underestimate the self-centering
523 capacity of RSC columns, and conservative residual displacement will be obtained.

524 (2) The total contribution of the eight parameters to the SC factor and ED parameter are
525 stable and maintain at 84% and 95% around, respectively. No significant interaction
526 between these factors is observed. Due to the P- Δ effect, the contribution of the gravity
527 loading ratio to the SC factor will decrease rapidly as the drift increase, and the effect
528 of the aspect ratio will grow.

529 (3) The SC factor, ED parameter, and maximum drift dominate the distribution of
530 residual drift under cyclic loading. When the SC factor exceeds 2.0 or the ED parameter
531 is smaller than 0.75, the residual drift can be neglected. In other situations, the residual

532 drift can be estimated using the upper limit formula and the regression formula.

533 (4) The unbonded length of ED bars has little influence on the SC factor and the ED
534 parameter. However, if the unbonded length is too long, the residual displacement can
535 be diminished effectively because of the changed unloading path.

536 **Declarations**

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550 **Reference**

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