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Power Equipment Fault Information Acquisition System Based on Internet of Things

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Abstract: With the advent of the Internet of things era, many of the original power equipment and its fault information acquisition system have the problems of low efficiency, slow and inaccurate fault information collection speed, so the design of intelligent system is very important. The purpose of this study is to design the power equipment fault information acquisition system of the Internet of things, and analyze the collection speed and accuracy of the system. In this study, a power company in our city was taken as the experimental object to collect the fault information reported by the company, and put the new IOT fault information acquisition system into use in another company. After using for one month, the data collected by the power equipment fault information acquisition system of the Internet of things are compared with the original system, and the information collection amount, accuracy and acquisition speed are calculated. The research results show that the company's low-voltage user acquisition success rate has reached more than 99%, and the F1 value of the power equipment information acquisition system of the Internet of things is 96.4%, which is much higher than 86.3% and 75.7% of other systems. With the increase of time, the fault information collection efficiency can approach 99%. It shows that the power equipment information acquisition system of the Internet of things has higher accuracy and speed of information acquisition than the traditional system and other systems, and greatly improves the working efficiency of the system. The conclusion is that the function of this research system is better, the economic loss of the company is reduced, and the management is optimized. It makes contribution to the optimization and intelligent development of power equipment fault information acquisition system.

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1. Introduction

The fault of power equipment is usually dynamic and random. In order to ensure the normal operation of power equipment, it is necessary to detect the power equipment quickly and accurately. At the same time, the fault of power equipment must be predicted correctly and reasonably according to the detected information. Only this method can solve the existing hidden danger in time, avoid the continuous deterioration of power equipment status and reduce the accident rate. The characteristics of on-line monitoring are continuous monitoring and detection in operation, analysis and judgment of device status. In practical engineering, the application of state maintenance needs online monitoring. The appearance of state detection and diagnosis technology of power equipment is to adapt to the above development trend. By detecting the

operation of power equipment and analyzing the abnormal information of each equipment, we can obtain power as soon as possible. At the same time, the potential equipment failure is predicted.

The traditional power equipment fault information acquisition system has the problems of low efficiency, slow fault information collection speed, incorrect information collection and so on, which is difficult to deal with the problem of power equipment scale expansion in the network era. For power enterprises, the past acquisition system is very wasteful, and the maintenance of hardware and software system is also very difficult. If the fault information cannot be collected effectively and quickly, it will seriously affect the operation of power group.

In the research of power equipment fault information acquisition system, Maximov S proposed a new method of power system equipment average life assessment based on two parameter Weibull distribution. The method is suitable for complete and correct fault data. He uses the classical maximum likelihood estimation (MLE) to determine the distribution parameters. However, he proposed an estimation method based on asymptotic expansion, which overcomes the shortcomings of numerical or graphical techniques based on maximum likelihood estimation. By analyzing two right censored life data sets of three types of power equipment with different sample sizes, he proves that his method has higher accuracy than other estimators. His method is not stable [1]. Qiu J in order to analyze the fault trend of power equipment more accurately, he improved the nonparametric regression method based on hierarchical proportional hazard model (PHM), and established a failure rate model suitable for general power equipment. His model can maximize the use of equipment life cycle data as covariates, including power equipment manufacturers, in the hierarchical health status of equipment in the process, it is conducive to quantitative processing and classification of life cycle data. He uses more inspection events over a full cycle to predict potential risks and assess the health of the equipment. Then, he uses hierarchical nonparametric PHM method to establish a multi type recurrent event specific failure model for interval censored competitive risk problems. Finally, a transformer is taken as an example to illustrate the modeling process. The accuracy of his method is not high [2]. Nozadian M H B studied the reliability and mean time to failure (MTTF) of semiconductor switches in series and in parallel under different failure rates. According to the different values of the reliability of series parallel structures in case of failure, he comprehensively compares the reliability of series parallel structures under different failure rates. According to the fault type and switch structure, the switch reliability of redundant structure is higher than that of other structures. His method lacks argument and persuasion [3]. The fault data of impregnated paper under DC pulsating voltage was studied experimentally by Li J. He obtained the fault data of the oil impregnated paper specimen through the constant pressure stress test, and estimated the statistical distribution of the fault data using Weibull distribution. He used the exponential function (EF) and inverse power function to analyze the fault data of oil paper specimens obtained under pulsed DC voltage and DC and AC voltage alone. The performance of his method is evaluated by the fault data obtained from constant stress tests under different voltages. His method is not practical [4].

This study first introduces the overall structure of the system, and also describes the construction of fault information collection system based on the Internet of things, including the classification of power equipment status information, information acquisition methods and the establishment of induction layer. This study also describes the data acquisition requirements

analysis and the life cycle management of power equipment based on Internet of things technology. This study describes the formula of relative evaluation standard. In this study, two electric power companies in our city are taken as the experimental objects, and different fault information collection is carried out respectively. Through the experimental results, the operation health status of power equipment is predicted and analyzed, the fault information collection status of the Internet of things is analyzed, and the accuracy and efficiency of the information acquisition system are analyzed. Conclusion the function and efficiency of fault information collection system of surface Internet of things are better.

2. Power Equipment Fault Information Acquisition System and Internet of Things Technology

2.1 Overall System Architecture

In terms of architecture, the bottom layer of the system is composed of multiple hardware terminals. The hardware terminal is used to complete the information exchange between the system and the external environment. The upper layer of the system is the software system. The software system can analyze information and data from the lowest level and save data. The core module has general problems, and the testability and maintainability of the system are relatively low [5-6].

The system is very complex, including many modules, and the communication and data transmission between modules are more complex. All commercial processing functions of the system must be completed in the communication mode implementation class. This includes the management of communication tasks, the sending and receiving of communication data, and the analysis of communication protocols. When multitasking is executed simultaneously, the upstream and downstream communication management of multiple devices is performed at the same time: the array is used as a method to handle the simultaneous execution of multiple tasks in the communication processing class, and to record the current status of the devices in the system. Because of the internal integration of the system, the ability of the system to adapt to the changes of the external environment is relatively weak. After the communication mode is changed, the communication between modules needs to be reestablished. All program architectures need to be reused [7-8].

Access server is the core of the whole system. It is the communication center and business of the system to realize the integration and communication with all components, communication with hardware terminal, data processing and analysis, database storage and display driver. As shown in Figure 1, the data acquisition flow chart.

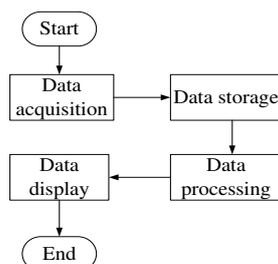


Figure 1 Flow chart of data acquisition

As can be seen from Figure 1, the system software adopts a distributed multi-layer structure,

including the demonstration layer (client), including the operator and commercial processing layer, as well as the commercial processing layer. The external interface is the core business processing part of the whole system, the application service layer is the technical support of the business service layer, and the data layer is responsible for the centralized storage of the whole system data, and responsible for the management of data optimization and data mining [9]

Data acquisition is to collect the current power consumption information of users in the practical application layer. At present, there are many problems in data acquisition, such as multiple data sources, large amount of data, rapid change, ensuring data reliability, and how to face repeated data [10].

2.2 Construction of Fault Information Collection System Based on Internet of Things

The perceptual layer is similar to human senses, and has the functions of recognizing, obtaining information and collecting necessary data information. In the existing Internet technology, two-dimensional code tag and reader, wireless RFID technology and reader, monitoring technology, global positioning system, various sensors, M2M terminal are more mature. First of all, the sensing layer obtains the data information of the tested equipment through various sensors and surveillance cameras, uses Bluetooth, RFID, two-dimensional code and other technologies for short-distance communication, and inputs the local information processing device. The important problems that need to be solved in the sensing layer are the list of data to be collected, the improvement of detection technology and the short-range wireless transmission communication.

(1) Classification of state information of power equipment

All kinds of information of substation equipment, such as sound, light, electricity, image, etc., can reflect the whole life cycle status of the equipment from all aspects, so the status information of substation equipment must contain a variety of data. According to the test data, observation records and other production processes of power system operators, it can be divided into three types: application information, operation information and maintenance test information [11-12].

1) Information before commissioning

The information before operation is usually collected by the technical department of the operation and maintenance management department of the power company. The infrastructure and material departments shall adjust and collect the units before startup, and hand them over to the production department after operation. In the production management system, the technical account of substation equipment and expansion project drawings are collected by the application management department. The related module is a production management system designed to save the information. Factory test report, handover test report and installation acceptance record can be used. The information management module of application layer production management system is used as the initial value of equipment status information, which is input by maintenance department [13].

2) Operation information

Application information mainly includes equipment inspection, maintenance, fault trigger, defect record, fixed real-time detection and mobile real-time detection data, as well as information related to severe working conditions. Through the inspection of the daily operation status of the equipment, the information of the equipment operation status and maintenance personnel can be collected, especially the production management system input to the

application layer according to the plan. Mobile real-time detection and fixed real-time detection data will be collected through the Internet of things system and input into the information management system.

3) Maintenance test information

Maintenance test information mainly includes periodic test report, diagnostic test report, special inspection record, defect elimination record and maintenance report. The maintenance and test unit is responsible for the collection, classification and input of production management information system. If the machine is returned to the factory for repair, it is necessary to obtain the maintenance report and relevant information from the manufacturer and input [14-15].

(2) Access to information

Patrol inspection of various types of voltage levels of substation equipment in power system, technical specifications of test items, servicing period, servicing items, etc. according to the legal provisions, the network system which mainly combines state protection objects with mobile real-time detection can form a collection method.

1) Inspection

According to the operation status of substation equipment, the management department shall carry out daily inspection and various equipment inspection. The inspection content is determined by the characteristics of the equipment and the characteristics to be collected. With the inspection characteristics of various equipment, it is convenient for daily management. The characteristics of the daily inspection also need to develop a cycle. In addition to daily inspection, other special inspections can be carried out according to the technical documents of different equipment. In addition to daily inspection, special inspection and inspection should be carried out at specific time and weather such as typhoon season inspection, strong wind and cold weather inspection. All types of inspections require electronic documentation for recording and input into the application layer [16-17].

2) Experiment

The power failure test of various equipment is an important information source of machine status information, which can be divided into regular examination and diagnostic examination. Type tests carried out at regular intervals. Adjust the cycle according to the status and maintenance judgment of the machine obtained by the application layer. Diagnostic tests are only carried out when the equipment is abnormal or suspected to be abnormal [18].

3) Fixed live detection (online monitoring)

Stable real-time detection refers to the method of continuous or regular detection by using sensors set in or near the equipment body during normal operation of substation [19].

(3) Establishment of induction layer

Sensor layer information can be divided into professional patrol, mobile site detection and fixed site detection. Professional patrol is patrolled by operation and maintenance personnel and reported to hand held terminal and uploaded to PMS. The mobile real-time detection data will be transmitted to the hand held device through the portable detection device through Bluetooth. The fixed real-time detection can be directly uploaded through the online monitoring module of substation and transmission equipment.

2.3 Data Acquisition Demand Analysis

The main function of the system is to realize the complete collection of power consumption

data of all customers, including real-time collection of voltage, current, power and other data. The collection of users is classified as follows. The purpose of power consumption information collection system is to enable all users to collect power consumption information in real time. Users here include large, medium and small special transformer users, low-voltage single-phase users, three-phase users, and public distribution transformer evaluation [20-21].

Data collection can be divided into automatic collection and manual collection. During the collection task, the main data collected by the terminal are: voltage data, current data, meter reading data, load data and other related data.

The collected data mainly include the following contents: basic information includes current instrument data, total effective power, total invalid power, current / day freeze. Maximum demand: the maximum demand of effective / invalid power, generation time and current value. Current and voltage value: current curve data, voltage curve data, load curve data. Power data: data curve of measurement point, effective power and invalid power [22-23].

(1) Automatic acquisition task: Constitute an automatic collection task, according to the data collection table to read data, curve data, statistical data and other related records in a specific period.

(2) Collection quality analysis: By comparing the daily collection tasks, analyze the success rate of collection, and judge whether the automatic data collection is normal.

(3) Data call test: Data calls can obtain specific interrupt or remote graph data by manually obtaining data collection.

2.4 On Line Monitoring Technology of Circuit Breaker Category

(1) Mechanical part monitoring.

Monitoring includes switching time, coil waveform, contact travel and speed, and vibration waveform. The grid which can collect the displacement signal is set in the operation part of the circuit breaker. The speed displacement is converted into electrical signal through the relative movement of the grid and the circuit breaker, and the displacement, speed and time of the circuit breaker action are obtained through data processing. Then the displacement and opening and closing velocity can be calculated.

(2) Control part monitoring.

Monitor the action time of the auxiliary contact and the action state of the control unit.

(3) Electrical monitoring.

The switch action of circuit breaker is usually realized by electromagnet. When the control current flows through the coil of the electromagnet, the electromagnet will send out electromagnetic force and lead the core into the circuit device. The current flowing in the switch coil contains a lot of transmission information that can be detected. Usually, the current monitoring sensor uses Hall sensor, which synchronizes the relative time of fault with the current waveform to judge the fault symptoms.

2.5 Life Cycle Management of Power Equipment Based on Internet of things Technology

(1) In the initial stage of construction, the construction cost of power equipment increases, but as an auxiliary equipment, the Internet of things technology needs certain material support, so the construction cost in the early stage is bound to increase. However, under the premise of large-scale popularization and application of digital substation and intelligent substation, this part

of cost is borne by part of construction machinery cost, which has little impact on initial cost [24].

(2) The operation level and service life of power supply equipment are greatly improved. In this paper, from the perspective of the Internet of things to monitor and maintain the state of power machinery, describes the role of Internet technology on the Internet of things. Its core is to improve the operation level of the machine and shorten the outage maintenance time [25].

(3) The cost is very serious. With the development of Internet technology, online condition monitoring and reasonable condition based maintenance plan, labor consumption and reliability of working environment are greatly reduced. On the other hand, the reduction of machine maintenance cost is also related to the improvement of power supply reliability and quality. In this way, the power industry has brought benefits, social benefits and economic benefits have also been improved.

2.6 Relative Evaluation Criteria

When the measured value of the monitoring parameter exceeds the specified threshold range or the specified limit value, the action state of the unit will change, and the abnormality may occur. In case of abnormal conditions, the machine does not necessarily fail. In addition, due to the change of the operation conditions of the unit, the monitored parameter values may change. On the contrary, when the monitoring data is within the normal action threshold, the unit also has abnormal state. Therefore, other evaluation criteria can be imported. Relative evaluation criteria. Relative evaluation benchmark refers to that for the same monitoring quantity of the same unit, the normal value in a certain period is taken as the reference value or health value, and the working condition of the unit is evaluated and analyzed by comparing the actual value with the reference value.

(1) Determination of evaluation benchmark value

According to the statistical theory, if the sample condition is large, the average value of the sample can be regarded as the theoretical average value. Therefore, in the case of large accumulation of unit data, the average value of characteristic quantity can be solved as the benchmark value of soundness evaluation

$$\bar{X} = \frac{(x_1 + x_2 + \dots + x_n)}{n} \quad (1)$$

(2) Determination of evaluation and early warning interval

The structure of turbine unit is more complex, and the random error of reference value is composed of many factors such as variation and random interference. However, random errors usually have the characteristics of statistical distribution, and generally follow the normal distribution. Therefore, the combination of the leyit criteria can lead to the evaluation of warning thresholds

$$X_c = \bar{X} \pm 3\sigma \quad (2)$$

σ is the standard deviation.

$$\sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2} \quad (3)$$

For each characteristic quantity of the unit, its reference value and early warning area can

be constructed into a health sample by operating performance data. During normal operation of the device, it can be seen from the statistical rule that the probability of the measured point data within the normal sample interval is 99.73%. When the unit measurement point data exceeds the healthy area of the sample, the probability of abnormal machine is 99.73%. Therefore, from the perspective of statistical theory, this method can be used to construct the health baseline and early warning area of equipment.

2.7 Principal Component Analysis

Principal component analysis (PCA), also known as principal component analysis (PCA) or principal component analysis (PCA), is a very popular statistical data analysis method to find as few orthogonal vectors as possible to represent the data information characteristics of multivariate data.

PCA tries to regroup the original variables into a new group of independent comprehensive variables. At the same time, according to the actual needs, a few less comprehensive variables can be taken out to replace the original variables, and the combination can reflect the information of the original variables as much as possible. It is a common method to deal with dimension reduction mathematically. The general method is to transform the linear orthogonal transformation into uncorrelated new orthogonal variables, and use the variance of each group to distinguish. That is, the larger the variance of Y_1 (the first selected linear combination), the more information Y_1 contains. If Y_1 is the largest variance of all linear combinations, then Y_1 is the first principal component.

The operation steps of PCA are as follows

(1) Get the raw data.

(2) Subtract the mean. For PCA to work well, first calculate the average value of each dimension, and then subtract the mean value of each dimension from each sample to get a difference, thus a new data set can be obtained.

(3) The covariance matrix is calculated. Covariance operation is performed on the data set obtained in the second step.

(4) The eigenvalues and eigenvectors are calculated. The covariance matrix obtained in the third step. It must be a square matrix, so the eigenvalues and eigenvectors of the matrix can be obtained by using the knowledge of linear algebra.

(5) Select several main components to construct the new space. In fact, the feature vector corresponding to the maximum eigenvalue is printed as the principal component of the data set, which contains a large amount of information.

(6) Reconstruct the data.

3. Experimental Design of Power Equipment Information Acquisition System of IOT

3.1 Experimental Data

In this study, two power companies in our city are selected as the experimental research objects, and the data collected by the power equipment fault information collection system of the two companies before are compared. Then, one of them is taken as the experimental group, and the traditional fault information collection system of power equipment is replaced by the intelligent system of Internet of things. After one year's use, the data collection amount, accuracy

and speed of the two companies are analyzed.

3.2 Experimental Steps

First of all, the design framework of fault information collection system based on the overall structure sets the experimental parameters to provide data for the experiment. Select the company, let the company's employees upload power equipment fault information at the same time, record the information collection speed in the system, and perform data analysis. The former design of fault information collection for power equipment is compared with the system, and the experimental results are obtained. According to the above experimental contents and results, the experimental conclusion is drawn.

3.3 Experimental Background and Materials

Many developed countries in the west developed online monitoring technology developed relatively early, the comprehensive application of computer technology and network technology has improved the monitoring level of power equipment. The research of various power equipment monitoring and diagnosis technologies, as well as the application of Internet of things and cloud computing, promote the development of power equipment monitoring and early warning system in western countries. The typical systems include aim system in Canada, PM (predictive maintenance) system developed by ENTEC company in the United States, mechanical condition monitoring system developed by Mitsubishi Heavy Industry, the largest military enterprise in Japan, substation maintenance management system developed by Ivo transmission service company in Finland, and main man developed by Holland Maintenance management system and cmms-iams (intelligent control maintenance management integrated system) developed in Europe and America in 1990s. The application of these software systems promotes the development of fault diagnosis of power equipment.

3.4 Power Calculation of Power Equipment

In ship DC power system, the output angular speed of diesel engine is only connected with the rotor of rectifier generator coaxially, that is to say, it provides prime power and only receives electromagnetic torque of rectifier generator, that is, it only cares about the speed and torque of diesel engine. Therefore, the internal characteristics of the diesel engine are ignored and simplified, and a diesel engine model with certain accuracy suitable for marine DC power system is constructed. In diesel engine, the mathematical relationship between effective power, output torque and average effective pressure and speed is as follows:

$$N_e = \frac{2p_e V_l n}{60\tau} = \frac{p_e V_l n}{30\tau} = K_1 p_e n \quad (4)$$

$$M_1 = \frac{60}{2\pi} \times \frac{N_e}{n} = 9.55 \frac{N_e}{n} = K_2 p_e \quad (5)$$

Where: N_e is the effective power of the diesel engine; n is the speed of the diesel engine;

τ is the stroke coefficient; p_e is the average effective pressure; V_l is the working volume of

10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

From table 1 and Table 2, it can be seen that with the increase of confidence level of wind power output confidence interval, the unit operation cost is on the rise, and the economy of unit combination scheme becomes worse. With the improvement of confidence level of wind power output confidence interval, the number of start-up units of traditional robust unit commitment model increases, the robustness of unit commitment scheme is enhanced, and the ability to cope with wind power fluctuations is improved.

With the change of the confidence interval of wind power output, the economy and robustness of the unit commitment scheme based on the traditional robust unit commitment model show a trend of ebb and flow. When the economy is good, the robustness of unit commitment scheme becomes worse, and the ability to deal with wind power fluctuation is weakened; when the robustness is good, the economy becomes worse. Therefore, there must be an optimal wind power output confidence interval, which makes the robustness and economy of the proposed unit commitment scheme reach the best compromise. However, the traditional robust unit commitment model considering wind power integration usually relies on experience or subjective intention to select the confidence interval of wind power output, which is lack of theoretical basis and the rationality of the proposed unit commitment scheme is also deficient.

4.2 Main Fault Analysis of Electric Equipment Engine

The generator is usually composed of end cover, stator, rotor, brush device, lead-out box, bearing and other components. The stator is composed of frame, main coil, commutation core, commutation coil, compensation winding, connecting wire and lead wire. The rotor is composed of rotor core, rotor winding, commutator, fan and shaft. The stator and rotor are connected and assembled by bearing and end cover, forming the main functional parts of the generator. As shown in Table 3, the main fault types of power equipment.

Table 3. Types of generator faults

| Fault type | Fault category |
|------------------------|------------------------------------|
| Electrical failure | Stator winding short circuit |
| | Broken stator wire |
| | Stator hydro junction failure |
| Mechanical failure | Rotor unbalance |
| | Air gap eccentricity |
| | Shafting misalignment |
| Cooling system failure | Leakage of stator winding |
| | Local blockage of ventilation duct |

Fault diagnosis parameter information

(1) On line monitoring information - Vibration Monitoring

In this method, the vibration sensor is used to monitor the vibration of the motor bearing or frame. Because the vibration frequency of different faults is different, the vibration frequency can be compared with the known fault frequency to find the fault location and fault nature. The limitation of vibration monitoring is: for motors, the installation position of sensors is very few, on the other hand, the vibration frequency is very easy to be interfered by the outside, and the vibration intensity range is wide. In the complex external environment, there are many

influencing factors, so it is difficult to accurately judge the corresponding fault; in addition, the fault type and vibration frequency are many to many It is difficult to distinguish the relationship.

(2) Electrical test information

Discharge monitoring includes end discharge, internal discharge of motor insulation and slot discharge. When the discharge monitoring exceeds the warning value, the equipment maintenance shall be carried out. The axial magnetic flux leakage and shaft voltage monitoring will cause the increase of axial magnetic flux leakage flux and shaft voltage in case of fault, so the fault can be judged. Temperature monitoring is to detect the temperature of stator, bearing and other parts by temperature sensor to identify the fault. Due to the limitation of the position and number of sensors, it is difficult to reflect the actual heating position of the fault, so it is difficult to realize fault location.

4.3 Prediction and Analysis of Operation Health Status of Power Equipment

In the experiment, the x-direction vibration data of the guide bearing group is selected. However, due to the high sampling frequency of the measuring points, a part of the data is intercepted in order to verify the model method. In the experiment, 2500 groups of data were selected and grouped according to 10 data. The average value of each data set was taken as the new measurement point data, and a total of 250 groups of data were calculated. Figure 2 shows the time sequence display of measurement point data after recombination.

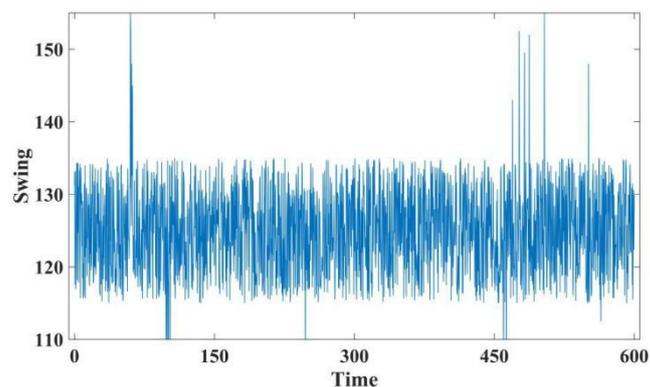


Figure 2. Sample data of measuring points after grouping

250 groups of data were divided into two parts. The first group of 200 groups of data was used as training data, the last 20 groups of data were used as validation data, and ARIMA model was used as control model. Figure 3 shows the results of forecasting data using ARIMA model and hybrid prediction model proposed in this section.

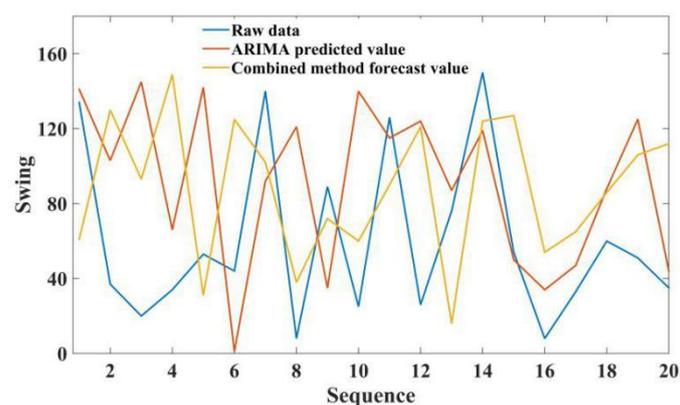


Figure 3. Model prediction results

Figure 2 and Figure 3 show that ARIMA prediction results are better than ARIMA based hybrid and SVR prediction models. According to the combination forecast, the residual error is small, which indicates that the prediction result of the model is excellent. Therefore, the equipment is predicted by the model parameters related to vibration, and then analyzed by asking the pendulum area, so as to achieve the goal of evaluating the indirect health status of the equipment.

4.4 Analysis of Power Equipment Fault Information Collection in the Internet of Things

As shown in Table 4, all kinds of user data acquisition.

Table 4. Data collection of various users

| Category | Households(ten thousand) | Acquisition success rate | Application ratio |
|---|--------------------------|--------------------------|-------------------|
| Low voltage data acquisition | 2084 | >99% | 98% |
| Public transformer data acquisition | 37.65 | >99.5% | 98% |
| Data acquisition of special transformer | 19.84 | >99.5% | 98% |

As shown in Table 4, as long as it is a local company, based on the acquisition, application and maintenance research, optimize the parent station strategy, improve the diversification of communication channels and network modes, gradually convert the old equipment, upgrade the communication module, and basic file management, fault collection, correct location, closed-loop processing and other solutions. At present, the company's success rate of collecting low-voltage users has reached more than 99%, especially the collection success rate of public transformers has reached 99.5%, and the recovery success rate of remote control power supply has reached more than 90%. The automatic collection of more than 20 million sets of electric energy meters has been realized, and the labor force of 50000 people has been saved; the instructions for power outage and power restoration of 14424100 times have been issued normally.

4.5 Accuracy Analysis of Power Equipment Fault Information Acquisition System of Internet of Things

Firstly, the construction of bidirectional cyclic neural network structure based on LSTM is realized by tensorflow. The initial network parameters are randomly given by tensorflow according to the set loss function and network optimization algorithm, and the learning rate $R / = 0.05$ is set. The following experimental process is used for the experiment. The model is basically stable after 8000 repetitions. The relationship between the accuracy of test set data and verification set data and the number of iterations is shown in Figure 4.

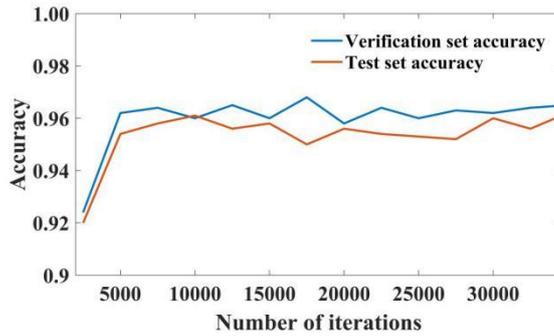


Figure 4 The relationship between the accuracy of the system and the number of iterations

As shown in Figure 4, if the number of iterations increases, the accuracy of both verification and test sets will be stable at about 96%. The accuracy of verification group is slightly higher than that of test group. The surf IOT system works efficiently.

In order to further verify the accuracy of the fault information collection system, SVM are selected as control models in the experiment. The purpose of the three algorithms is to achieve the accuracy of four kinds of labels, that is, four kinds of analysis results. High risk, low risk, inefficiency, destruction, recall rate and F1. The experimental classification results such as scores are shown in Table 5.

Table 5. Experimental classification results

| Algorithm | Classification | Accuracy | Recall | F1 value |
|--------------|----------------|----------|--------|----------|
| KNN | high-risk | 78.2% | 81.6% | 75.7% |
| | Low risk | 64.8% | 63.6% | |
| | invalid | 79.0% | 82.7% | |
| | crack | 78.6% | 82.9% | |
| SVM | high-risk | 86.6% | 87.8% | 86.3% |
| | Low risk | 89.2% | 88.6% | |
| | invalid | 86.8% | 90.4% | |
| | crack | 79.8% | 80.5% | |
| IOT approach | high-risk | 98.0% | 97.3% | 96.4% |
| | Low risk | 94.9% | 96.6% | |
| | invalid | 97.9% | 95.2% | |
| | crack | 95.4% | 92.8% | |

The experimental results in Table 5 show that the bidirectional current neural network based on this white paper has higher accuracy than SVM and KNN models, which verifies the applicability of the current neural network structure in the field of fault diagnosis. When dealing with sequence fault data, the processing ability of deep learning network structure is better than that of traditional shallow network structure.

4.6 Efficiency Analysis of Power Fault Information Acquisition System of Internet of Things

The efficiency of the former fault information collection system is compared with that of the object-based Internet environment. The comparison results are shown in Figure 5.

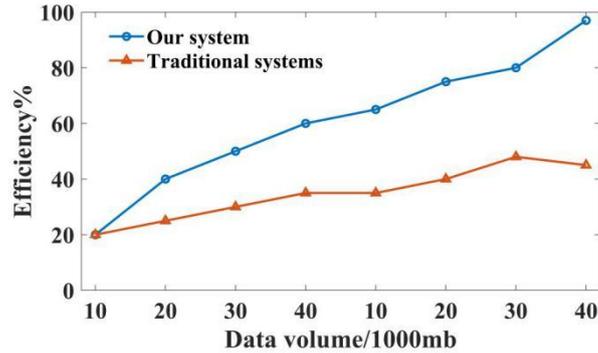


Figure 5 Efficiency comparison of two acquisition systems

As can be seen from Figure 5, the power equipment fault information collection system based on the Internet of things improves the judgment performance of fault information and the efficiency of fault information collection. With the increase of time, the efficiency of fault information collection is different from that in the past, which can be close to 99%. Compared with the system, this design is more reasonable and valuable.

The power equipment fault information collection system based on the Internet of things has fast collection speed. Compared with the previous system, it can collect fault information faster and ensure the correctness of information collection. The power equipment fault information collection system based on the Internet of things has efficient information collection efficiency and high-speed information collection speed, which can realize multiple fault information collection and processing, and lay a solid foundation for the future information collection system design.

5. Conclusion

This research is based on the equipment fault information collection system of the Internet of things, and mainly studies the fault information collection method based on the Internet of things technology. Equipment fault data is generally time series data. In the analysis of equipment failure, the data before and after fault and before and after fault are analyzed. The abnormal state of equipment is associated with the data before and after the fault. Therefore, by analyzing the characteristics of the fault data and the equipment before and after the fault, a bi-directional recurrent neural network model based on LSTM is constructed. This is more accurate than the previous machine learning diagnosis method.

With the advent of the Internet of things era, power equipment is gradually connected to the network, and its intelligent fault detection function provides greater help for the power industry. The traditional power equipment fault information collection system has the problems of poor efficiency, slow fault information collection speed and incorrect information collection, which is difficult to cope with the network era of power equipment scale expansion. For power companies, the traditional collection system is not only a waste of money, but also difficult to achieve hardware and software system maintenance. The method designed in this paper can not only improve the efficiency and speed of collection, but also can compare and collect fault information. The overall operation state of the power unit is improved accurately.

Power companies can reduce the economic losses of enterprises through real-time data collection, accurate analysis, on-line monitoring of abnormal problems, active learning, processing equipment failure, detection of electricity theft and other abnormal conditions. The

application of the system not only improves the application ability and profitability of users, but also improves the intelligent management and high-quality service level of power companies. It is an important means to catch up with the construction of intelligent grid. In order to ensure the effectiveness of information collection, the control strength of the collection system can be adjusted when the hardware system is designed by circuit reset module. Compared with the previous system design, it can be analyzed that the system designed in this investigation has good fault information collection function and information collection. To provide strong support for the expansion of China's power industry.

Due to the limitation of time, only the generator is selected to realize the fault diagnosis function, and the fault monitoring and early warning of other equipment such as transformer, capacitive equipment, lightning arrester, power cable and so on can be further designed and implemented, and a comprehensive fault monitoring and early warning system can be further completed. Different devices are suitable for different diagnosis algorithms. Further research and test should be carried out on the diagnosis algorithms. In addition, the functions of the system should be further improved according to the actual situation. The equipment monitoring module should be further improved. In addition to browsing the parameter information and inputting data, the next goal should be to realize the automatic data collection and uploading to the server.

List of Abbreviations

IOT: Internet of Things

MLE: maximum likelihood estimation

PHM: Peptide Histidine-Methionine

MTTF: Mean Time to Failures

EF: Extremely Fine

DC: Direct Current

AC: Alternating Current

Availability of data and materials

Not applicable' for that section.

Declarations

Consent for publication: Approved.

Competing interests

There is no potential competitive advantage in our paper. All the authors have reviewed the manuscript and agreed to submit it to your magazine. We confirm that the contents of the manuscript have not been published or submitted for publication elsewhere.

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Author's contributions

All authors take part in the discussion of the work described in this paper.

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Figure:

Fig 1 Flow chart of data acquisition

Fig 2 Sample data of measuring points after grouping

Fig 3 Model prediction results

Fig 4 The relationship between the accuracy of the system and the number of iterations

Figures

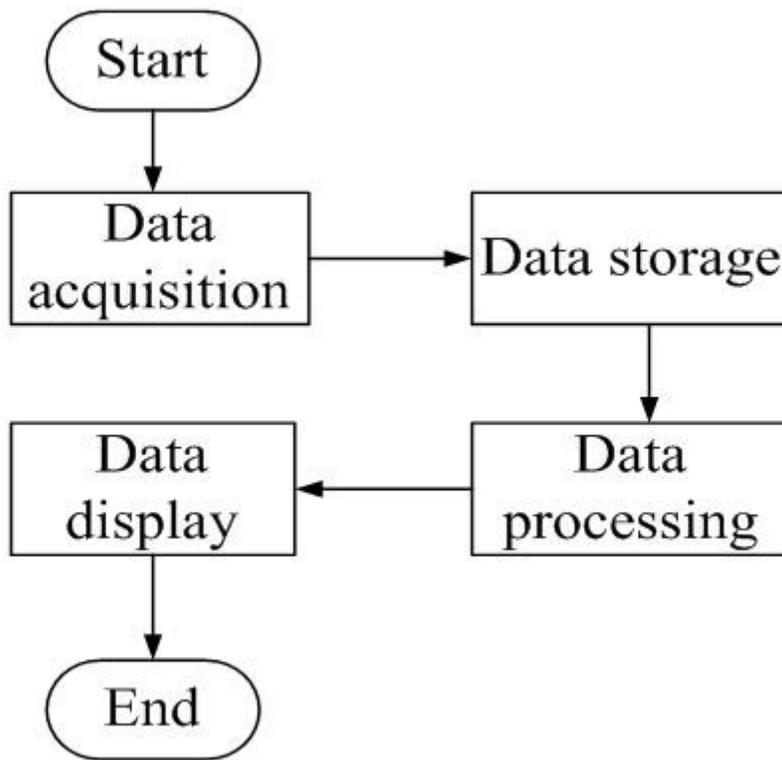


Figure 1

Flow chart of data acquisition

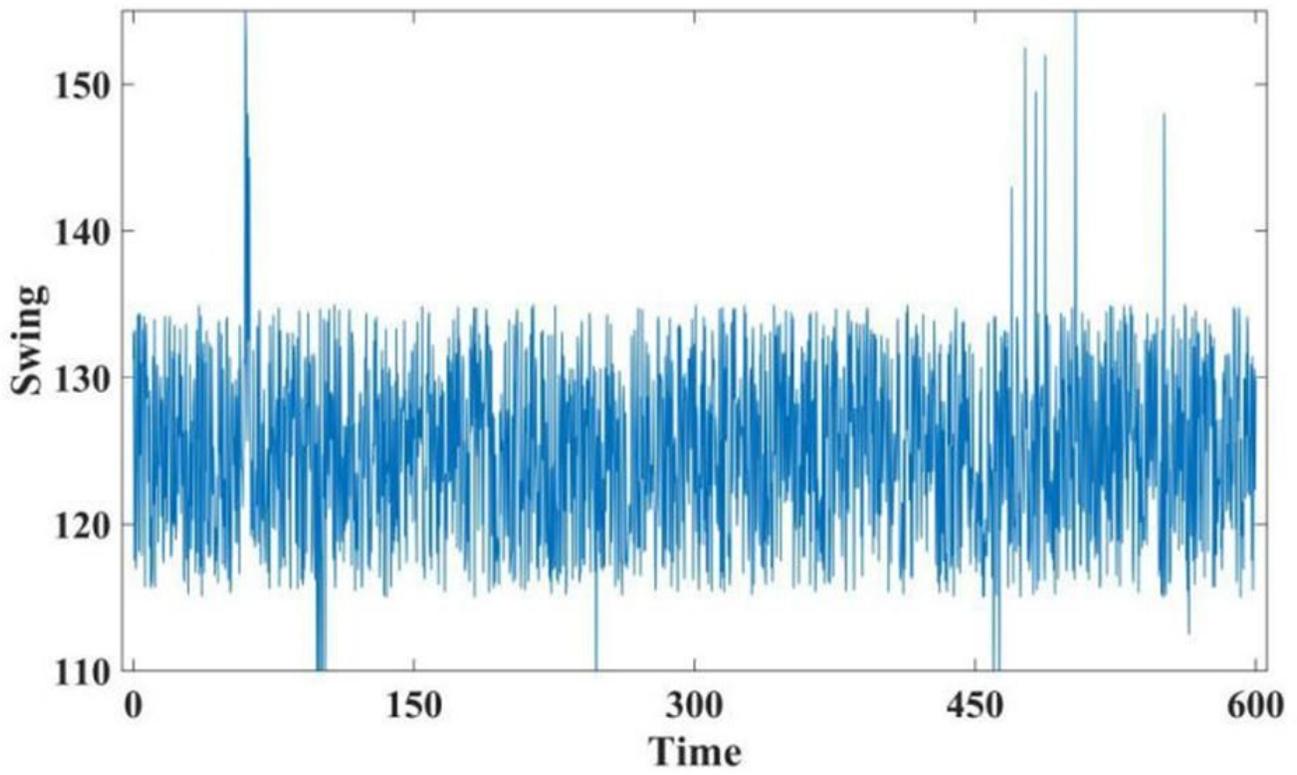


Figure 2

Sample data of measuring points after grouping

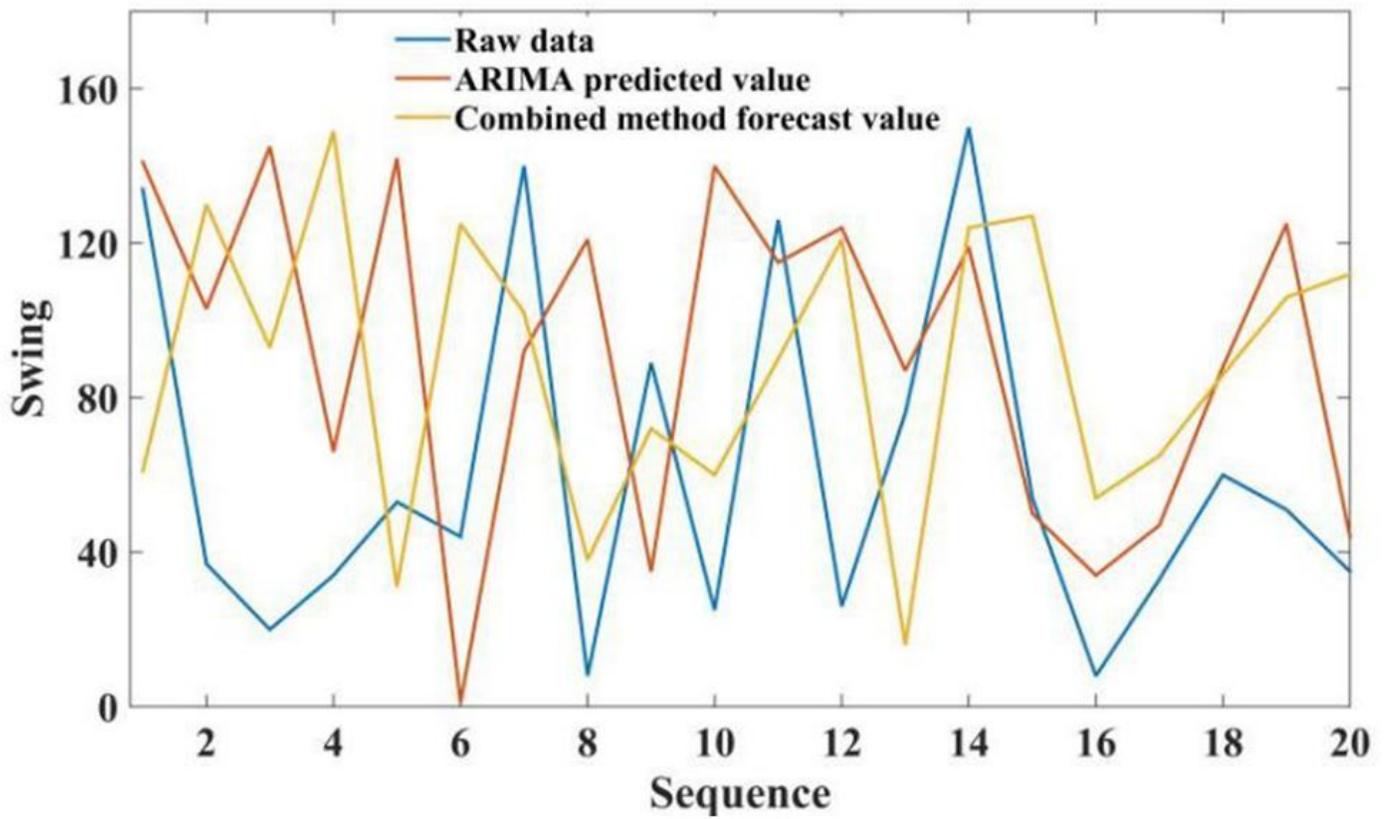


Figure 3

Model prediction results

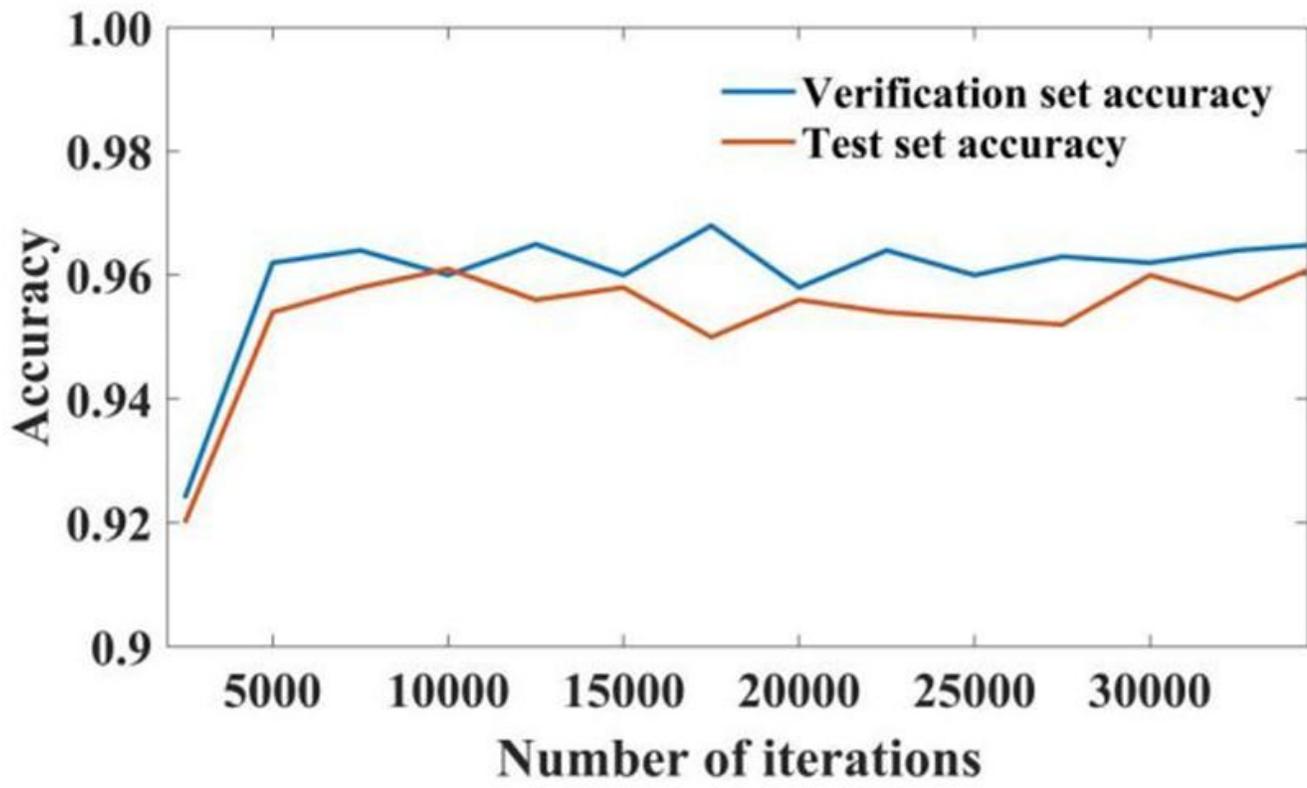


Figure 4

The relationship between the accuracy of the system and the number of iterations

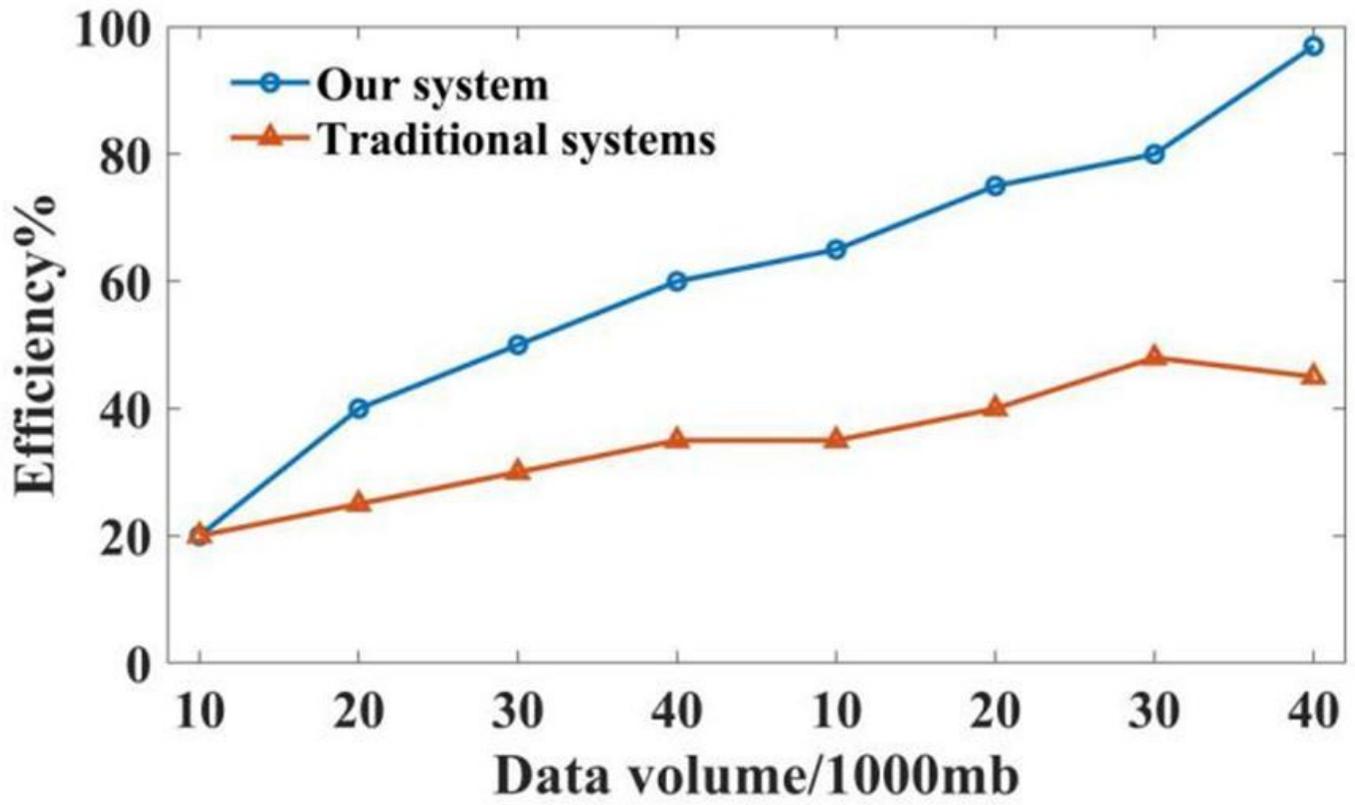


Figure 5

Efficiency comparison of two acquisition systems