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Mathematical modelling and optimal cost-effective control of COVID-19 transmission dynamics.

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Abstract

The novel coronavirus disease (COVID-19) caused by a new strain of severe acute respiratory syndrome coronavirus 2 (SARS-CoV-2) remains the current global health challenge. In this paper, an epidemic model based on system of ordinary differential equations is formulated by taking into account the transmission routes from symptomatic, asymptomatic and hospitalized individuals. The model is fitted to the corresponding cumulative number of hospitalized individuals (active cases) reported by the Nigeria Centre for Disease Control (NCDC), and parameterized using the least squares method. The basic reproduction number which measures the potential spread of COVID-19 in the population is computed using the next generation operator method. Further, Lyapunov function is constructed to investigate the stability of the model around a disease-free equilibrium point. It is shown that the model has a globally asymptotically stable disease-free equilibrium if the basic reproduction number of the novel coronavirus transmission is less than one. Sensitivities of the model to changes in parameters are explored. It is revealed further that the basic reproduction number can be brought to a value less than one in Nigeria, if the current effective transmission rate of the disease can be reduced by 50%. Otherwise, the number of active cases may get up to 2.5% of the total estimated population. In addition, two time-dependent control variables, namely preventive and management measures, are considered to mitigate the damaging effects of the disease using Pontryagin's maximum principle. The most cost-effective control measure is determined through cost-effectiveness analysis. Numerical simulations of the overall system are implemented in MatLab[®] for demonstration of the theoretical results.

Keywords: COVID-19, model fitting, global stability, optimal control, cost effectiveness, numerical simulations.

1 Introduction

It is no longer news that the current global threat to human existence is the novel coronavirus disease (COVID-19), which is caused by a new strain of severe acute respiratory syn-

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drome coronavirus 2 (SARS-CoV-2). The disease was first reported to the World Health Organization (WHO) in late December, 2019 in Wuhan, Hubei Province, China [1, 2]. COVID-19 has been declared as a pandemic (global epidemic) affecting over 200 countries and territories around the world. The disease is responsible for the current global socio-economic disruptions affecting lives and livelihoods. As of 15 July 2020, there have been 13,690,115 confirmed cases of COVID-19, including 5,071,482 active cases and 587,235 deaths worldwide [3].

Dry cough, fever and fatigue (tiredness) are the most common symptoms of the novel coronavirus disease. However, other symptoms include shivering (chills), pains, sore throat, difficulty in breathing, headache, skin rashes, runny nose, taste loss, diarrhea and fingers or toes dislocation [2, 4]. COVID-19 primarily spreads when an infected person expels respiratory droplets via coughing or sneezing. Some reports have shown that infected person with no symptoms can also transmit the virus [5, 6, 7]. There is no specific cure yet for COVID-19 due to its novelty. However, efforts are in place to develop vaccines and antivirals to cure the disease. Existing management of cases is targeted at relieving symptoms of the disease while the immune system of infected person fights the virus. It should be mentioned that older people and persons with underlying health conditions such as lung disease, asthma, cancer, diabetes, liver disease and other immunocompromised conditions are at higher risk of having complications from COVID-19 [4]. The novel coronavirus disease can be prevented by adhering to measures, including regular hand washing or use of alcohol-based sanitiser, maintaining social distancing, avoiding crowded places, use of face masks, and use of hand gloves with personal protective clothing by healthcare workers while giving care to COVID-19 patients [2, 4].

On the 27th of February 2020, one person with immediate travel history was diagnosed of COVID-19 in Lagos State. This marked the first confirmed case of the novel coronavirus to be reported in Nigeria [8]. As of 15 July 2020, the cumulative number of confirmed cases has risen to 34,259 as reported by the Nigeria Centre for Disease Control (NCDC). Of the confirmed cases, 13,999 individuals have recovered while 760 deaths were recorded, bringing the total number of currently infected cases being managed at isolation centres or health facilities (active cases) to 19,500. It is important to note that all 36 states including the Federal Capital Territory of the country have reported cases of COVID-19, with Kogi and Cross River States having the least, 5 confirmed cases each, and Lagos State recording the highest number with 12,941 confirmed cases as at 15th July, 2020 [8].

Mathematical modelling continues to play significant role in demystifying complex systems whose behaviors or properties can be observed. Most recently, a number of models fitted to real data of COVID-19 transmission have been developed to identify factors driving the disease at different population levels [9, 10, 11, 12, 13, 14, 15, 16, 17, 18]. For examples, in [9], the authors analysed COVID-19 spread dynamics with environmental influence using the reported cases in Ghana. A mathematical model for assessing the impacts of non-pharmaceutical interventions on the transmission dynamics of the novel coronavirus pandemic in Nigeria was presented in [11] by using the available cumulative COVID-19 mortality data. Jia and Coworkers [12] presented a dynamical model of COVID-19 by taking into account the impact of policy intervention and meteorological factors based on officially published data from China. In another development, Srivastav *et al.* [16] applied optimal control theory to analyse a mathematical model for COVID-19 model using real

data from Italy and Spain.

In this work, an epidemic model for COVID-19 with transmission routes from symptomatic infectious humans, asymptomatic infectious humans and hospitalized individuals is parameterized and analyzed based on the cumulative number of active cases reported in Nigeria. Moreover, optimal control theory is applied to the epidemiology of COVID-19 transmission in order to assess the optimal levels of time-dependent prevention and management measures that will significantly minimize the number of infectious humans in the population.

2 Model formulation

In this section, an epidemic model which focuses only on the dynamics of COVID-19 outbreak in the absence of demographic effects (natural births and deaths) is considered (see, e.g. [19, 20]). Thus, the host population is stratified into seven mutually exclusive epidemiological classes: susceptible class $S(t)$ (those who are prone to contract COVID-19 infection), exposed class $E(t)$ (those who have been infected, but are not infectious), symptomatic infectious class $I(t)$ (those who exhibit COVID-19 symptoms and are capable of spreading the disease), asymptomatic infectious class $A(t)$ (those who are not symptomatic, but are infectious), hospitalized class $H(t)$ (infectious individuals who are admitted to healthcare facility due to virus infection (active cases)), recovery class $R(t)$ (those who have been recovered from the disease), and death class $D(t)$ (those who have died as a result of COVID-19 infection).

It is pertinent to mention that over 800 healthcare workers have tested positive for COVID-19 in Nigeria due to inadequate protective equipment [21]. This necessitates the transmission route from hospitalized class as appeared in [20]. Figure 1 shows a flowchart depicting the transmission dynamics of COVID-19 in the total host population size N , which is given by $N = S(t) + E(t) + I(t) + A(t) + H(t) + R(t) + D(t)$. Consequently, the following system of nonlinear differential equations is obtained.

Figure 1: A flowchart of COVID-19 model with $\lambda = \beta S(I + \varepsilon_1 A + \varepsilon_2 H)/N - D$.

$$\begin{aligned}
\frac{dS}{dt} &= -\frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} \\
\frac{dE}{dt} &= \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} - \alpha E \\
\frac{dI}{dt} &= l_1 \alpha E - (h_1 + r_1 + \delta_1) I \\
\frac{dA}{dt} &= (1 - l_1) \alpha E - (h_2 + r_2) A \\
\frac{dH}{dt} &= h_1 I + h_2 A - (\gamma + \delta_2) H \\
\frac{dR}{dt} &= r_1 I + r_2 A + \gamma H \\
\frac{dD}{dt} &= \delta_1 I + \delta_2 H.
\end{aligned} \tag{1}$$

Table 1 provides the detailed descriptions of the parameters of the COVID-19 model (1).

Table 1. The parameters of the COVID-19 model (1).

Parameter	Description
β	Effective transmission coefficient
ε_1	Modification parameter for a reduced transmission from asymptomatic humans
ε_2	Modification parameter for a more reduced transmission from hospitalized class
α	Rate of disease progression from exposed class
l_1	Proportion of exposed with symptoms after the incubation period
$1 - l_1$	Proportion of exposed without symptoms after the incubation period
h_1	Hospitalization rate for symptomatic class
h_2	Hospitalization rate for asymptomatic class after confirmation
r_1	Recovery rate for symptomatic class
r_2	Recovery rate for asymptomatic class
γ	Recovery rate for hospitalized class
δ_1	Disease-induced mortality rate for symptomatic class
δ_2	Disease-induced mortality rate for hospitalized class

3 Theoretical analysis of the model

It should be mentioned that the parameters of the formulated model (1) are non-negative since the model describes disease outbreak in human population. Therefore, it suffices to state that solutions of the model (1) are non-negative.

3.1 Basic reproduction number

The potential spread of disease outbreak in a population can be determined by finding an epidemiological threshold known as the basic reproduction number. In the context of the novel coronavirus, the basic reproduction number, denoted by $\mathfrak{R}_0$, can be defined as the average number of secondary cases produced by one COVID-19 infected person during the course of infectiousness in a wholly susceptible population. To obtain $\mathfrak{R}_0$ for the COVID-19 model (1), the next generation operator technique is employed following the notations in [22]. Matrices F and V evaluated at the disease-free equilibrium $(N, 0, 0, 0, 0, 0, 0)$ are given, respectively, by

$$F = \begin{pmatrix} 0 & \beta & \beta\varepsilon_1 & \beta\varepsilon_2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

and

$$V = \begin{pmatrix} \alpha & 0 & 0 & 0 \\ -l_1\alpha & h_1 + r_1 + \delta_1 & 0 & 0 \\ -(1-l_1)\alpha & 0 & h_2 + r_2 & 0 \\ 0 & -h_1 & -h_2 & \gamma + \delta_2 \end{pmatrix}.$$

The spectral radius of FV^{-1} , given by $\mathfrak{R}_0 = \rho(FV^{-1})$, is obtained as

$$\mathfrak{R}_0 = \frac{\beta l_1}{k_1} + \frac{\beta \varepsilon_1 (1 - l_1)}{k_2} + \frac{\beta \varepsilon_2 (l_1 h_1 k_2 + (1 - l_1) h_2 k_1)}{k_1 k_2 k_3}, \quad (2)$$

where, $k_1 = h_1 + r_1 + \delta_1$, $k_2 = h_2 + r_2$ and $k_3 = \gamma + \delta_2$.

Thus, the following local stability result is claimed in the sense of [22].

Theorem 1. *The disease-free equilibrium (DFE) of the COVID-19 model (1) is locally asymptotically stable if the basic reproduction number, $\mathfrak{R}_0 < 1$, and unstable if $\mathfrak{R}_0 > 1$.*

The implication of Theorem 1 from epidemiological viewpoint is that a small number of infected individuals present in a population will not cause an outbreak as long as $\mathfrak{R}_0 < 1$. It must be emphasized that this result depends on the initial sizes of infected individuals in the population. Hence, to rule out this dependency, a global stability result becomes necessary.

3.2 Global asymptotic stability of DFE

The global asymptotic stability of the COVID-19 free equilibrium, given by $(N, 0, 0, 0, 0, 0, 0)$, is explored as follows.

Theorem 2. *The disease-free equilibrium (DFE) of the COVID-19 model (1) is globally asymptotically stable if $\mathfrak{R}_0 \leq 1$.*

Proof. The following carefully constructed linear Lyapunov function is used (see, e.g. [23, 24]).

$$\mathfrak{F} = f_1 E + f_2 I + f_3 A + f_4 H, \quad (3)$$

where, $f_1 = [l_1 k_2 k_3 + \varepsilon_1 (1 - l_1) k_1 k_3 + \varepsilon_2 (l_1 h_1 k_2 + (1 - l_1) h_2 k_1)] / k_1 k_2 k_3$, $f_2 = [k_3 + \varepsilon_2 h_1] / k_1 k_3$, $f_3 = [\varepsilon_1 k_3 + \varepsilon_2 h_2] / k_2 k_3$ and $f_4 = \varepsilon_2 / k_3$.

The time derivative of (3) along the solution path of the COVID-19 model (1) is given by

$$\begin{aligned}
\dot{\mathfrak{F}} &= f_1 \dot{E} + f_2 \dot{I} + f_3 \dot{A} + f_4 \dot{H}, \\
&= f_1 \left(\frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} - \alpha E \right) + f_2 (l_1 \alpha E - k_1 I) + f_3 ((1 - l_1) \alpha E - k_2 A) \\
&\quad + f_4 (h_1 I + h_2 A - k_3 H), \\
&= f_1 \left(\frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} \right) - I - \varepsilon_1 A - \varepsilon_2 H, \\
&\leq f_1 \beta (I + \varepsilon_1 A + \varepsilon_2 H) - (I + \varepsilon_1 A + \varepsilon_2 H); \quad (\text{since } S \leq N - D), \\
&= (I + \varepsilon_1 A + \varepsilon_2 H) (f_1 \beta - 1), \\
&= (I + \varepsilon_1 A + \varepsilon_2 H) \left(\frac{\beta l_1}{k_1} + \frac{\beta \varepsilon_1 (1 - l_1)}{k_2} + \frac{\beta \varepsilon_2 (l_1 h_1 k_2 + (1 - l_1) h_2 k_1)}{k_1 k_2 k_3} - 1 \right), \\
&= (I + \varepsilon_1 A + \varepsilon_2 H) (\mathfrak{R}_0 - 1).
\end{aligned} \tag{4}$$

It follows that $\dot{\mathfrak{F}} \leq 0$ if $\mathfrak{R}_0 < 1$ with equality, $\dot{\mathfrak{F}} = 0$, if and only if $E = 0$, $I = 0$, $A = 0$ and $H = 0$. Therefore, it can be concluded from the LaSalle's Invariance Principle [25] that the DFE is globally asymptotically stable whenever $\mathfrak{R}_0 \leq 1$. $\square$

The implication of Theorem 2 from the epidemiological viewpoint is that COVID-19 can be effectively controlled in the population if $\mathfrak{R}_0 < 1$ regardless of the initial sizes of the infected individuals. This theoretical result will be graphically illustrated later.

4 Parameter estimation and model fitting

This section is devoted to the estimation of parameters of the COVID-19 model (1) based on the reported data of cases in Nigeria [8]. In particular, the formulated model is parameterized to assess the burden of COVID-19 in terms of the number of individuals currently infected (active cases) in Nigeria. In this study, the values for parameters such as effective transmission coefficient (β), modification parameter (ε_2), and hospitalization rates (h_1 and h_2) are estimated, while the values of other parameters are chosen from the well established literature as appeared in Table 2. The estimation of parameters is carried out using the least squares method implemented in Excel Solver [26] with a view to minimizing summation of squared errors given by $\sum (Y(t, p) - X_{real})^2$ subject to the COVID-19 model (1), where X_{real} is the real reported data, and $Y(t, p)$ represents the solution of the model corresponding to the number of active cases over time t with the set of estimated parameters, denoted by p .

Moreover, initial conditions for the exposed humans, symptomatic and asymptomatic infectious individuals are estimated to account for the possibility that the actual number

of cases is most likely much higher than reported in Nigeria as in other parts of the world, due to limited testing and the possible presence of COVID-19 infected individuals with no symptoms [27]. In order to accommodate the foregoing possibility, the estimations of parameters and initial conditions for the model fitting are allowed to commence from 10th March, 2020, exactly a day after the second COVID-19 confirmed case was reported by NCDC [8], so that $H(0) = 2$. Keeping in mind that the total population of Nigeria is estimated at $N = 200$ million people [28], and that no report of recovery and deaths due to the disease was made as at 10th March, 2020 (i.e. $R(0) = D(0) = 0$), then it is easy to determine the initial susceptible population as $S(0) = N - (E(0) + A(0) + I(0) + H(0) + R(0) + D(0))$.

Table 2. Values of parameters and initial conditions.

Parameter	Value	Source
β	0.38974	Fitted
ε_1	0.5 day ⁻¹	[10]
ε_2	0.24278	Fitted
α	$\frac{1}{5.2}$ day ⁻¹	[29]
l_1	0.5	[10]
h_1	0.33604	Fitted
h_2	0.19466	Fitted
$r_1 = r_2$	$\frac{1}{7}$ day ⁻¹	[11, 30]
γ	$\frac{1}{15}$ day ⁻¹	[10, 15]
$\delta_1 = \delta_2$	0.015 day ⁻¹	[16, 31]

The model is fitted to the real data along with the following initial conditions: $E(0) = 880$, $A(0) = 330$, $I(0) = 190$, so that $S(0) = 199,998,600$. The model fitting with reported active cases is depicted in Figure 2. Consequently, the value of the basic reproduction number using the parameter values in Table 2 is $\mathfrak{R}_0 = 1.412$, which still exceeds the novel coronavirus pandemic threshold of one.

4.1 Sensitivity of the model to parameters

It is important to explore how sensitive the COVID-19 model (1) is to changes in each of its parameters in order to suggest intervention strategies that will help in bringing down the infection trajectory. In other words, carrying out sensitivity analysis will help in providing insights into what should be done or avoided to prevent the outbreak of the novel coronavirus [32]. Thus, as defined in [33], a relative change in the basic reproduction number, $\mathfrak{R}_0$, when each parameter changes is measured using the following

$$\Upsilon_p^{\mathfrak{R}_0} = \frac{\partial \mathfrak{R}_0}{\partial p} \times \frac{p}{\mathfrak{R}_0},$$

where, $\Upsilon_p^{\mathfrak{R}_0}$ is the sensitivity index of a differentiable $\mathfrak{R}_0$ with respect to any parameter, p . Consequently, the sensitivity indexes for the model (1) are graphically shown in Figure 3. It can be observed that of all the positive indices, the effective transmission coefficient, β , is the highest, and therefore the most sensitive parameter. This means that an increase (or a decrease) of the value of β will increase (or decrease) $\mathfrak{R}_0$ by 100%. However, of all

Figure 2: Fitting of the COVID-19 model (1) with the available cumulative number of active cases from 10th March to 15th July, 2020.

the negative indices shown in Figure 3, the recovery rate for the hospitalized class (active cases), denoted by γ , is the most sensitive parameter. This means that an increase (or a decrease) of the value of γ will decrease (or increase) $\mathfrak{R}_0$ by 42.1%.

In addition, contour plots of $\mathfrak{R}_0$ as a function of other parameters are shown in Figure 4 to demonstrate how changes in these parameters affect the basic reproduction number, $\mathfrak{R}_0$. Figure 4(a) shows a decrease in $\mathfrak{R}_0$ with increasing recovery rates for both symptomatic and asymptomatic individuals. This spontaneous recovery from infection is due to the body's innate immune response which is capable of inhibiting virus replication, promoting virus clearance, and triggering a prolonged adaptive immune response against reinfection [34]. Moreover, it can be confirmed, as shown in Figure 4(b), that the basic reproduction number can be brought lower than the threshold of one if efforts are geared towards lowering the transmission rate while simultaneously improving on the management of active cases.

In Figure 5(a), the effects of effective transmission coefficient at different values are illustrated. It is projected that the cumulative number of active cases in Nigeria, given the current infection trajectory with $\beta = 0.38974$, may get up to 5×10^6 (equivalently, 2.5% of the total estimated population) unless drastic measures are taken to bring the basic reproduction number below one. As shown in Figure 5(b), the cumulative number of active cases reduces with increasing value of recovery rate for hospitalized individuals from $\gamma = 1/15 \text{ day}^{-1}$ to $1/5 \text{ day}^{-1}$. In particular, if it takes 5 days or less to effectively manage infected individuals, the risk of infection transmission from the hospitalized class

Figure 3: COVID-19 model sensitivities to its associated parameters.

(a)

(b)

Figure 4: 2-D contour plots of the basic reproduction number $\mathfrak{R}_0$.

Figure 5: Projections with varying effects of parameters: (a) Effective transmission coefficient at values of $\beta = [0.42 (\mathfrak{R}_0 = 1.521 > 1), 0.38974 (\mathfrak{R}_0 = 1.412 > 1), 0.36 (\mathfrak{R}_0 = 1.304 > 1)$ and $0.19487 (\mathfrak{R}_0 = 0.706 < 1)]$. (b) Recovery rate for hospitalized individuals at values of $\gamma = [0.06667 (\mathfrak{R}_0 = 1.412 > 1), 0.1 (\mathfrak{R}_0 = 1.2 > 1), \text{ and } 0.2 (\mathfrak{R}_0 = 0.959 < 1)]$.

will reduce significantly. This indicates that the longer it takes to effectively manage COVID-19 patient, the heavier the burden of the disease on the healthcare facility and the population at large. In agreement with the global stability result (Theorem 2), Figure 6 illustrates the convergence to the COVID-19-free equilibrium irrespective of the initial sizes of the infectious individuals in the population.

5 Optimal control model and analysis

In the light of the sensitivity analysis result, optimal control theory is applied to the COVID-19 model (1), as applied to other infectious diseases models (e.g. [33, 35, 36, 37, 38, 39]) in order to mitigate the spread of COVID-19 in the population optimally. This is done by introducing two time-dependent control variables $u_1(t)$ and $u_2(t)$, which are described in details as follows.

- (i). $u_1(t)$ denotes the preventive strategy targeted at inhibiting the virus transmission from symptomatic, asymptomatic and hospitalized humans. This can be achieved through public health advocacy for social distancing, good personal hygiene, wearing face masks in public places, and provision of protective gear for healthcare workers. Noting that $u_1(t) = 1$ implies the strategy is effective for protection against infection, while $u_1(t) = 0$ implies strategy failure.
- (ii). $u_2(t)$ represents control variable to step up the management of hospitalized individuals with a view to ensuring prompt recovery and preventing deaths due to complications. This can be achieved through prompt provision of supplemental oxygen or me-

(a)

(b)

(c)

Figure 6: Convergence of solution trajectories for (a) symptomatic humans, (b) asymptomatic humans and (c) hospitalized humans at different initial sizes in line with Theorem 2. Parameter values used are as given in Table 2 except for $\beta = 0.19487$ and $\varepsilon = 0.12$, so that $\mathfrak{R}_0 = 0.522 < 1$.

chanical ventilation for hospitalized individuals with severe COVID-19. If $u_2(t) = 1$, then the control is effective in managing the disease, while $u_2(t) = 0$ means the absence of control.

Consequently, the optimal control model with the two aforementioned time-dependent variables is given by the following differential equations

$$\begin{aligned}
\frac{dS}{dt} &= -(1 - u_1(t)) \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} \\
\frac{dE}{dt} &= (1 - u_1(t)) \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} - \alpha E \\
\frac{dI}{dt} &= l_1 \alpha E - (h_1 + r_1 + \delta_1) I \\
\frac{dA}{dt} &= (1 - l_1) \alpha E - (h_2 + r_2) A \\
\frac{dH}{dt} &= h_1 I + h_2 A - (\gamma + u_2(t) + \delta_2) H \\
\frac{dR}{dt} &= r_1 I + r_2 A + (\gamma + u_2(t)) H \\
\frac{dD}{dt} &= \delta_1 I + \delta_2 H.
\end{aligned} \tag{5}$$

The aim of introducing the two control variables is to seek the optimal solution required to minimize the numbers of symptomatic, asymptomatic and hospitalized individuals responsible for spreading the novel coronavirus in the population at minimum cost. Hence, the objective functional for this control problem is given by

$$\mathfrak{J}(u_1, u_2) = \min_{0 \leq u_1, u_2 \leq 1} \int_0^{T_f} \left(w_1 I + w_2 A + w_3 H + \frac{1}{2} [w_4 u_1^2(t) + w_5 u_2^2(t)] \right) dt, \tag{6}$$

where, constants w_i , $i = 1, 2, \dots, 5$ are positive weights required to balance the corresponding terms in the objective functional. Following other literature on COVID-19 control problems [9, 16, 17, 40, 41], quadratic costs on the controls are chosen, where $1/2 w_4 u_1^2(t)$ is the total cost of implementing the preventive measure, and $1/2 w_5 u_2^2(t)$ is the total cost of managing active cases over the time interval $[0, T_f]$.

Precisely, the optimal control double $u^* = (u_1^*, u_2^*)$ is sought such that

$$\mathfrak{J}(u_1^*, u_2^*) = \min \{ \mathfrak{J}(u_1, u_2) : u_1, u_2 \in \mathcal{U} \}, \tag{7}$$

where, $\mathcal{U}$ is the non-empty control set defined by

$\mathcal{U} = \{ (u_1, u_2) : (u_1(t), u_2(t)) \text{ are measurable with } 0 \leq u_1, u_2 \leq 1 \text{ for } t \in [0, T_f] \}$. Thus, to determine the necessary conditions that the optimal control double (u_1^*, u_2^*) must satisfy, Pontryagin's maximum principle [42], which transforms the control problem (7) subject

to the model (5) into a problem of minimizing pointwise a Hamiltonian $\mathcal{H}$, is used. This Hamiltonian is given by

$$\begin{aligned}
\mathcal{H} = & w_1 I + w_2 A + w_3 H + \frac{1}{2}[w_4 u_1^2(t) + w_5 u_2^2(t)] \\
& + \lambda_1 \left[-(1 - u_1(t)) \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} \right] \\
& + \lambda_2 \left[(1 - u_1(t)) \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)}{N - D} - \alpha E \right] \\
& + \lambda_3 [l_1 \alpha E - (h_1 + r_1 + \delta_1) I] + \lambda_4 [(1 - l_1) \alpha E - (h_2 + r_2) A] \\
& + \lambda_5 [h_1 I + h_2 A - (\gamma + u_2(t) + \delta_2) H] \\
& + \lambda_6 [r_1 I + r_2 A + (\gamma + u_2(t)) H] + \lambda_7 [\delta_1 I + \delta_2 H],
\end{aligned} \tag{8}$$

where, λ_i , $i = 1, 2, 3, \dots, 7$, represent the adjoint variables associated with the state variables of the model (5). The standard existence result for minimizing control problem as appeared in [43, 44] is adapted as follows.

Theorem 3. *Given that (u_1^*, u_2^*) minimizes the objective functional (6) subject to the corresponding state system (5), then the adjoint variables λ_i , $i = 1, 2, 3, \dots, 7$, satisfy the following system*

$$\begin{aligned}
\frac{d\lambda_1}{dt} &= \frac{\beta(1 - u_1(t))(I + \varepsilon_1 A + \varepsilon_2 H)[\lambda_2 - \lambda_1]}{N - D} \\
\frac{d\lambda_2}{dt} &= \alpha(\lambda_2 - l_1 \lambda_3 - (1 - l_1) \lambda_4) \\
\frac{d\lambda_3}{dt} &= \frac{\beta S(1 - u_1(t))[\lambda_2 - \lambda_1]}{N - D} + \delta_1(\lambda_3 - \lambda_7) + h_1(\lambda_3 - \lambda_5) + r_1(\lambda_3 - \lambda_6) - w_1 \\
\frac{d\lambda_4}{dt} &= \frac{\varepsilon_1 \beta S(1 - u_1(t))[\lambda_2 - \lambda_1]}{N - D} + h_2(\lambda_4 - \lambda_5) + r_2(\lambda_4 - \lambda_6) - w_2 \\
\frac{d\lambda_5}{dt} &= \frac{\varepsilon_2 \beta S(1 - u_1(t))[\lambda_2 - \lambda_1]}{N - D} + \delta_2(\lambda_5 - \lambda_7) + (\gamma + u_2(t))(\lambda_5 - \lambda_6) - w_3 \\
\frac{d\lambda_6}{dt} &= 0 \\
\frac{d\lambda_7}{dt} &= \frac{\beta(1 - u_1(t))S(I + \varepsilon_1 A + \varepsilon_2 H)[\lambda_1 - \lambda_2]}{(N - D)^2}
\end{aligned} \tag{9}$$

with the terminal (transversality) conditions

$$\lambda_i(T_f) = 0, \quad i=1,2,3,\dots,7. \tag{10}$$

Further, the optimal control double (u_1^*, u_2^*) is given as follows

$$\begin{aligned} u_1^* &= \max \left\{ 0, \min \left\{ 1, \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)[\lambda_2 - \lambda_1]}{w_4(N - D)} \right\} \right\}, \\ u_2^* &= \max \left\{ 0, \min \left\{ 1, \frac{H[\lambda_5 - \lambda_6]}{w_5} \right\} \right\}. \end{aligned} \quad (11)$$

Proof. The existence of the optimal control double (u_1, u_2) is based on the *a priori* boundedness of the state variables of model (5), convexity and boundedness of the Lagrangian of the control problem. The system of ordinary differential equations (9) governing the adjoint variables is derived by differentiating the Hamiltonian $\mathcal{H}$. Further, the control characterizations in (11) are derived by solving, on the interior of the control set $\mathcal{U}$, the partial differentials of the Hamiltonian $\mathcal{H}$ with respect to each of the controls u_1 and u_2 . Hence, by standard arguments involving control bounds, it follows that

$$u_1^* = \begin{cases} 0 & \text{if } \tau_1^* \leq 0, \\ \tau_1^* & \text{if } 0 < \tau_1^* < 1, \\ 1 & \text{if } \tau_1^* \geq 1, \end{cases}$$

and

$$u_2^* = \begin{cases} 0 & \text{if } \tau_2^* \leq 0, \\ \tau_2^* & \text{if } 0 < \tau_2^* < 1, \\ 1 & \text{if } \tau_2^* \geq 1, \end{cases}$$

where,

$$\tau_1^* = \frac{\beta S(I + \varepsilon_1 A + \varepsilon_2 H)[\lambda_2 - \lambda_1]}{w_4(N - D)}$$

and

$$\tau_2^* = \frac{H[\lambda_5 - \lambda_6]}{w_5}.$$

This ends the proof. $\square$

5.1 Simulations of the control problem

Forward and backward Runge-Kutta method of order four implemented in MATLAB is used to solve the resulting optimality system which consists of systems (5) and (9) with the characterizations (11) within the time interval of $[0, 100]$ days. The weight constants are chosen as $w_1 = 1$, $w_2 = 1$, $w_3 = 1$, $w_4 = 50$ and $w_5 = 100$. Details of the numerical procedure are contained in [45].

Figure 7 demonstrates how single preventive measure, $u_1(t)$, affects the spread of the novel coronavirus in the population. As shown in Figure 7(a), to minimize the objective functional (6), the optimal control $u_1(t)$ is maintained at maximum level of 100% for about 93 days before relaxing to the minimum in final time. As expected, the sizes of COVID-19 infectious individuals are reduced when control is in place. Further, in Figure 8(a)-(b), the effects of single management control, $u_2(t)$, are shown in minimizing the number of virus infection in the population, but not as much as when only preventive strategy is

(a)

(b)

(c)

(d)

Figure 7: Control profile ($u_1(t)$) and its effects on the COVID-19 dynamics.

(a)

(b)

(c)

(d)

Figure 8: Control profile ($u_2(t)$) and its effects on the COVID-19 dynamics.

(a)

(b)

(c)

(d)

Figure 9: Combined effects of optimal controls $u_1(t)$, $u_2(t)$ on the COVID-19 dynamics.

applied. More importantly, Figure 9 shows the significance of combining the two optimal controls in bringing down the total number of infectious humans to zero. It is observed that optimal solution is attained when preventive measure is strictly adhered to at maximum level of 100% for 45 days, while the management control of the hospitalized individuals is at maximum level of 100% for 32 days. It can be seen that combination of the two controls is significantly more effective in curbing the spread of the virus than when each control is singly applied.

5.2 Cost-effectiveness analysis

It is important to determine the most cost-effective optimal control measure among the single and combined implementation of the two given control measures in order to optimally mitigate the spread of COVID-19 at the lowest cost possible. Hence, cost-effectiveness analysis is explored using the incremental cost effectiveness ratio (ICER) [9, 24, 46, 47, 48]. To avoid dissipation of available limited resources, ICER is used to compare any two competing measures for controlling the spread of disease or related problems. The ICER formula is given by

$$\text{ICER} = \frac{\text{Change in total costs between control measures}}{\text{Change in total number of infection averted by control measures}}. \quad (12)$$

The total cost for each of the single implementation and combined effort of the control measures is derivable from the objective functional 6, while the infection averted is obtained by calculating the difference between infectious individuals without and with control measures. Let C_1 , C_2 and C_{12} represent single implementation of the preventive measure $u_1(t)$, single implementation of the management control $u_2(t)$ and combined effort of the two measures, respectively. In what follows, Table 4 summarizes the ICER for each and combination of the control variables $u_1(t)$ and $u_2(t)$ in an increasing order of the total infection averted.

Table 4. ICER in the order of COVID-19 cases averted by control measures.

Control measures	Total infection averted	Total costs	ICER
C_1	3.5062×10^6	4.7351×10^4	0.0135
C_2	3.7311×10^6	8.2886×10^4	0.1580
C_{12}	3.8848×10^6	5.0064×10^4	-0.2136

Using (12), the ICER for C_1 , C_2 and C_{12} shown in Table 4 are calculated, respectively, as follows.

$$\text{ICER}(C_1) = \frac{4.7351 \times 10^4}{3.5062 \times 10^6} = 0.0135,$$

$$\text{ICER}(C_2) = \frac{(8.2886 - 4.7351) \times 10^4}{(3.7311 - 3.5062) \times 10^6} = 0.1580,$$

$$\text{ICER}(C_{12}) = \frac{(5.0064 - 8.2886) \times 10^4}{(3.8848 - 3.7311) \times 10^6} = -0.2136.$$

Comparing C_1 and C_2 , it is seen that $\text{ICER}(C_1)$ is less than $\text{ICER}(C_2)$. This means that C_2 is more costly and less effective than C_1 . In other words, C_1 dominates C_2 . Thus, single implementation of management control is removed from the list. As a consequence, C_1 and C_{12} are assessed in Table 5 using similar procedure.

Table 5. Comparison between C_1 and C_{12} .

Control measures	Total infection averted	Total costs	ICER
C_1	3.5062×10^6	4.7351×10^4	0.0135
C_{12}	3.8848×10^6	5.0064×10^4	0.0072

It is revealed in Table 5 that C_1 is dominated by C_{12} since $\text{ICER}(C_1)$ is greater than $\text{ICER}(C_{12})$. This implies that C_{12} is less costly and more effective than C_1 . Hence, single implementation of preventive measure is excluded from the list. This shows that combined effort of the two control measures is the most cost-effective intervention capable of diminishing the burden of the novel coronavirus optimally in the host population.

6 Conclusion

This study presented a mathematical analysis of transmission dynamics of the novel coronavirus (COVID-19) pandemic by subdividing the host population into susceptible, exposed, symptomatic infectious, asymptomatic infectious, hospitalized, recovered and dead classes. The nonlinear model has been developed by considering transmission routes from symptomatic infectious humans, asymptomatic infectious humans and hospitalized individuals. The theoretical analysis carried out, based on Lyapunov stability, showed that the model has a globally asymptotically stable disease-free equilibrium if the basic reproduction number of the novel coronavirus transmission is less than one. This is an indication that COVID-19 outbreak can be effectively controlled in the population irrespective of the number of the infectious individuals initially introduced into the completely susceptible population.

In particular, the formulated model was fitted to the reported data of cumulative number of hospitalized individuals (active cases) due to COVID-19 in Nigeria, and estimates for parameters such as, effective transmission coefficients (β), modification parameter for the transmission of virus infection from active cases (ε_2), hospitalization rates for both symptomatic and asymptomatic individuals (h_1 and h_2) were determined using the least squares method. Sensitivity analysis of the fitted model was performed to find the parameters that drive the spread of the virus infection mostly in the population. It was revealed that β is the most sensitive parameter, followed by ε_2 and the recovery rate for active cases denoted by γ . Further insights into the projection of the disease transmission indicated that the cumulative number of active cases in Nigeria, given the current infection trajectory, may get up to 2.5% of the total estimated population of 200 million, unless drastic measures are taken to bring the basic reproduction number below one. It was shown by simulations that the basic reproduction number can be brought to a value less than one in Nigeria, if the current effective transmission rate of the disease can be reduced by 50%.

Moreover, the model was extended to include time-dependent optimal control variables (preventive and management measures) to examine their impacts in minimizing the burden of COVID-19 in the population using Pontryagin's maximum principle. The optimal preventive measure was shown to be better than management control in reducing the burden of the disease, but the combined effort of the two controls has significant effect in reducing the number of infectious individuals in the population. This result is further supported by carrying out the cost-effectiveness analysis, and it is therefore established that the combined implementation of the two control measures is the most cost-effective when compared with the single implementation of each control measure.

In view of the above, it can be concluded that low transmission rate with high recovery rate are required to effectively overcome the spread of the novel coronavirus in the host population. To achieve this optimally, it is recommended that adherence to the combination of preventive and management control measures should be strict. These measures include continued public advocacy for social distancing, good personal hygiene, wearing face masks in public places, provision of protective gear for healthcare workers caring for people with COVID-19 infection. If strict adherence is practiced, transmission routes from symptomatic, asymptomatic and hospitalized individuals will be effectively hindered, and availability of supplemental oxygen or mechanical ventilation for hospitalized individuals with severe COVID-19. In addition, given the ongoing community spread of the virus in Nigeria and almost all the countries of world, the need to scale up the testing capacity cannot be overemphasized.

Conflict of Interests

The authors declare no conflict of interest.

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Figures

Figure 1

A flowchart of COVID-19 model with $\lambda = \beta S(I + \varepsilon_1 A + \varepsilon_2 H)/N - D$.

Figure 2

Fitting of the COVID-19 model (1) with the available cumulative number of active cases from 10th March to 15th July, 2020.

Figure 3

COVID-19 model sensitivities to its associated parameters.

Figure 4

2-D contour plots of the basic reproduction number R_0 .

(a)

(b)

Figure 5

Projections with varying effects of parameters: (a) Effective transmission coefficient at values of $\beta = [0.42 (R_0 = 1.521 > 1), 0.38974 (R_0 = 1.412 > 1), 0.36 (R_0 = 1.304 > 1) \text{ and } 0.19487 (R_0 = 0.706 < 1)]$. (b) Recovery rate for hospitalized individuals at values of $\gamma = [0.06667 (R_0 = 1.412 > 1), 0.1 (R_0 = 1.2 > 1), \text{ and } 0.2 (R_0 = 0.959 < 1)]$.

(a)

(b)

(c)

Figure 6

Convergence of solution trajectories for (a) symptomatic humans, (b) asymptomatic humans and (c) hospitalized humans at different initial sizes in line with Theorem 2. Parameter values used are as given in Table 2 except for $\beta = 0.19487$ and $\varepsilon = 0.12$, so that $R_0 = 0.522 < 1$.

(a)

(b)

(c)

(d)

Figure 7

Control profile ($u_1(t)$) and its effects on the COVID-19 dynamics.

(a)

(b)

(c)

(d)

Figure 8

Control profile ($u_2(t)$) and its effects on the COVID-19 dynamics.

(a)

(b)

(c)

(d)

Figure 9

Combined effects of optimal controls $u_1(t)$, $u_2(t)$ on the COVID-19 dynamics.