

Estimation of Relative Source Locations From Seismic Amplitude: Application to Earthquakes and Tremors at Meakandake Volcano, Eastern Hokkaido, Japan

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1 **Estimation of relative source locations from seismic amplitude:**
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3 **eastern Hokkaido, Japan**

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6 **Abstract**

7 Although seismic amplitudes can be used to estimate event locations for volcanic tremors and other
8 seismic events with unclear phase arrival times, the precision of such estimates is strongly affected by
9 site amplification factors. Therefore, reduction of the influence of site amplification will allow more
10 precise estimation of event locations by this method. Here, we propose a new method to estimate
11 relative event locations using seismic amplitudes. We use the amplitude ratio between two seismic
12 events at a given station to cancel out the effect of the site amplification factor at that station. By
13 assuming that the difference between the hypocentral distances of these events is much smaller than
14 their hypocentral distances themselves, we derive a system of linear equations for the differences in
15 relative event locations. This formulation is similar to that of a master event location method that uses
16 differences in phase arrival times. We applied our new method to earthquakes and tremors at
17 Meakandake volcano, eastern Hokkaido, Japan. Comparison of the hypocentral distributions of
18 volcano-tectonic earthquakes obtained thereby with those obtained from phase arrival times confirmed
19 the validity of our new method. Moreover, our method clearly identified source migration among three
20 source regions in the tremor on 16 November 2008, consistent with previous interpretations of other
21 geophysical observations in our study area. Our method will thus be useful for detailed analyses of
22 seismic events whose onset times are ambiguous.

23 **Keywords**

24 Relative source location, Seismic amplitude, Volcano-tectonic earthquakes, Volcanic tremors, Tremor
25 migration, Meakandake volcano

26 **Introduction**

27 Estimating the location of seismic events is a fundamental step in seismological analyses. Phase arrival
28 times are routinely used to locate earthquake hypocenters (e.g., Hirata and Matsu'ura 1987; Klein 2002).
29 Several other techniques have been applied, some of which have dealt successfully with ambiguous arrival
30 times. Seismic array observations (e.g., Rost and Thomas 2002) enable us to estimate wave propagation
31 direction and apparent velocity by using waveform similarity (e.g., Capon 1969; Neidell and Taner 1971;
32 Goldstein and Archuleta 1987), which can be used to estimate a waveform's point of origin. When
33 waveforms are not similar among stations, but seismogram envelopes are, differences in phase arrival
34 times among stations can be estimated from seismogram envelope correlations, and source locations can
35 be estimated from these arrival-time differences; this is known as the envelope correlation method (Obara
36 2002).

37 Seismic amplitude can also be used to estimate seismic event locations. The amplitude source location
38 (ASL) method (e.g., Battaglia and Aki 2003; Battaglia et al. 2005; Kumagai et al. 2010) uses amplitude
39 spatial decay for this purpose. Because the ASL method does not rely on phase arrival times, it is
40 applicable to seismic events with unclear onset times, such as tremors. The ASL method has been
41 applied to tremors and earthquakes within volcanoes (Battaglia 2003; Kumagai et al. 2011; Ogiso and
42 Yomogida 2012; Kumagai et al. 2013a; Ogiso et al. 2015; Kurokawa et al. 2016; Ichihara and Matsumoto
43 2017; Walsh et al. 2017; Ichimura et al. 2018; Kumagai et al. 2019), pyroclastic flows (Yamasato 1997;
44 Jolly et al. 2002), lahars or debris flows (Kumagai et al. 2009; Ogiso and Yomogida 2015; Doi and Maeda
45 2020), and snow avalanches (Pérez-Guillén et al. 2019). The ASL method has also revealed the source
46 process of a large subduction zone earthquake (Kumagai et al. 2013b), the detailed distribution of shallow
47 low-frequency earthquakes near a trench axis (Tamaribuchi et al. 2019). Because the ASL method uses
48 observed seismic amplitudes, the appropriate correction of site amplification effects is important for the
49 accuracy of event locations determined by this method (Kumagai et al. 2013a).

50 In addition to estimating absolute source locations, as discussed above, estimates of relative source
51 location have been used to derive precise location distributions. The underlying concept for this techniques
52 is the removal of common factors that affect location precisions. A joint hypocenter determination
53 technique (e.g., Douglas 1967) includes site correction terms in a system of equations designed to
54 simultaneously estimate relative event locations and site correction terms. A master event location
55 method (Aoki 1974; Ito 1985; Frémont and Malone 1987) attributes differences between phase arrival

56 times of a reference event and other events to differences in their relative locations. When seismic
57 events occur in close proximity to one another, the errors arising from wave propagation path can
58 be canceled out by accounting for arrival-time differences. A double-difference earthquake location
59 algorithm (Waldhauser and Ellsworth 2000) is a novel approach to source-location estimation that uses
60 the differences of observed and theoretical arrival times between event pairs to minimize the influence
61 of an unmodeled heterogeneous velocity structure without any reference events. These techniques for
62 estimating relative source locations have revealed more detailed spatial characteristics of seismicities
63 than those by absolute location estimation methods.

64 Here, we propose a new method to estimate relative source locations that uses seismic amplitudes and
65 takes advantage of aspects of both the ASL method and the relative location methods. Our method uses
66 amplitude ratios between reference and other events at several stations to cancel out the effects of site
67 amplification. By assuming that subevents occur near a reference event, we derive a system of linear
68 equations for differences in relative location. We then estimate relative locations by solving the equations
69 with a standard least-squares method. In this paper, we first explain the formulation of our new method
70 and then apply it to volcano-tectonic (VT) earthquakes and tremors at Meakandake volcano, eastern
71 Hokkaido, Japan. To test the validity of our method, we then compare the hypocentral distribution
72 of VT earthquakes derived by our new method with those derived by two methods that determine
73 hypocenters from phase arrival times. Next, we demonstrate that the migration of the tremor locations
74 that we identified with our new method is clearer than that in the previous study (Ogiso and Yomogida
75 2012), and discuss the relationship between tremor source regions and other geophysical observations.

76 **Theoretical background**

77 In this section, we briefly review the ASL method and then present the theory that underpins our new
78 method of determining relative source locations from seismic amplitudes.

79 **ASL method**

80 When body waves propagate, the observed seismic amplitude $A_i(f)$ at a certain frequency f at the i th
81 station can be represented as

$$A_i(f) = A_0(f) \frac{\exp(-B(f)r_i)}{r_i} S_i(f), \quad (1)$$

82 where $A_0(f)$ is the source radiation amplitude, r_i the hypocentral distance between the source and the
 83 i th station, and $S_i(f)$ the site amplification factor at the i th station. $B(f)$ is defined as

$$B(f) = \frac{\pi f}{Q\beta}, \quad (2)$$

84 where Q is the intrinsic attenuation factor and β the velocity of the medium, or the average S-wave
 85 velocity in general. If we assume the source location for a certain event, we can calculate the source
 86 radiation amplitude $A_0(f)$ as

$$A_0(f) = \frac{1}{N} \sum_{i=1}^N \frac{A_i(f)}{S_i(f)} r_i \exp(B(f)r_i), \quad (3)$$

87 where N is the number of observations. Using equations (1) and (3), we calculate the normalized residual
 88 R as

$$R = \frac{\sum_{i=1}^N \{A_i(f)/S_i(f) - A_0(f) \exp(-B(f)r_i)/r_i\}^2}{\sum_{i=1}^N \{A_i(f)/S_i(f)\}^2}. \quad (4)$$

89 In application of the ASL method, a grid search is usually conducted to find the location where R reaches
 90 its minimum value. Because the heterogeneous radiation pattern of the source is not modeled in equation
 91 (1), and because distortion of the radiation pattern becomes more obvious in higher frequency ranges
 92 (e.g., Takemura et al. 2009; Kobayashi et al. 2015), seismic amplitudes at high frequencies (usually higher
 93 than 5 Hz) are suitable for the ASL method.

94 **Estimation of relative source locations from seismic amplitudes**

95 As shown by equation (3), the site amplification factor $S_i(f)$ has a large influence on source locations
 96 estimated by the ASL method. The coda normalization method (e.g., Phillips and Aki 1986; Takemoto
 97 et al. 2012) is widely used to estimate site amplification factors. Calibration of site amplification factors
 98 with seismic events for which locations are well-constrained (Ichihara and Matsumoto 2017; Walsh
 99 et al. 2017; Kumagai et al. 2019) is preferable when estimating source locations. Nevertheless, some
 100 uncertainties are unavoidable when estimating site amplification factors. In this study, we propose the
 101 use of amplitude ratios to cancel out uncertainties in site amplification factors.

102 From equation (1), the amplitude ratio between two events, the j th and k th events, at the i th station is

$$\frac{A_i^j(f)}{A_i^k(f)} = \frac{A_0^j(f) \exp(-B(f)r_{ij}) r_{ik}}{A_0^k(f) \exp(-B(f)r_{ik}) r_{ij}}, \quad (5)$$

103 where $A_i^j(f)$ and $A_i^k(f)$ are the observed amplitudes of the j th and k th events at the i th station, $A_0^j(f)$
 104 and $A_0^k(f)$ are the source radiation amplitudes of the j th and k th events, respectively, and r_{ij} and r_{ik}

105 are the hypocentral distances from the i th station to the j th and k th events, respectively. We define the
 106 difference of the hypocentral distances of the j th and k th events Δr_{jk} as

$$\Delta r_{jk} = r_{ik} - r_{ij}, \quad (6)$$

107 and, substituting equation (6) into (5) gives

$$\frac{A_i^j(f)}{A_i^k(f)} = \frac{A_0^j(f)}{A_0^k(f)} \frac{1}{\exp(-B(f)\Delta r_{jk})} \left(1 + \frac{\Delta r_{jk}}{r_{ij}}\right). \quad (7)$$

108 Here we assume that the sources of the j th and k th events are near each other so that Δr_{jk} becomes
 109 much smaller than the hypocentral distances r_{ij} and r_{ik} . Taking the natural logarithm of both sides of
 110 equation (7) and approximating $\ln(1 + \Delta r_{jk}/r_{ij})$ as $\Delta r_{jk}/r_{ij}$, equation (7) becomes

$$\ln \frac{A_i^j(f)}{A_i^k(f)} \approx \ln \frac{A_0^j(f)}{A_0^k(f)} + B(f)\Delta r_{jk} + \frac{\Delta r_{jk}}{r_{ij}}. \quad (8)$$

111 Similar to the formulation of Aoki (1974) for a master event location method using differences of phase
 112 arrival times, we can approximate Δr_{jk} to be

$$\Delta r_{jk} \approx \mathbf{n}_i^j \cdot \Delta \mathbf{x}_k, \quad (9)$$

113 where \mathbf{n}_i^j is the unit vector representing the takeoff angle and azimuth from the j th event to the i th
 114 station, and $\Delta \mathbf{x}_k$ is the location vector of the k th event relative to the j th event. After substituting
 115 equation (9) into (8), we rewrite equation (8) into the following matrix form for standard least-square
 116 inversion:

$$\mathbf{d} = \mathbf{G}\mathbf{m}, \quad (10)$$

117 where \mathbf{d} represents the data vector consisting of $\ln(A_i^j/A_i^k)$, \mathbf{m} is the model vector consisting of $\ln(A_0^j/A_0^k)$
 118 and $\Delta \mathbf{x}_k$, and \mathbf{G} is the kernel consisting of the coefficients of the model vector in the right-hand side of
 119 equation (8). We can solve equation (10) by a standard least-squares method if we have more than four
 120 observations for each event. Our formulation is essentially the same as that of the master event location
 121 method using differences of phase arrival times (Aoki 1974), except we use seismic amplitudes rather
 122 than arrival times.

123 The corresponding model covariance matrix \mathbf{S}_m is

$$\mathbf{S}_m = (\mathbf{G}^T \mathbf{S}_d^{-1} \mathbf{G})^{-1}, \quad (11)$$

124 where \mathbf{S}_d is the data covariance matrix. In the following analysis, we first calculate the variance of data
 125 residuals using all events except the reference event. Assuming that errors in the data are independent

126 each other, we construct a diagonal data covariance matrix with the variance of data residuals to obtain
127 \mathbf{S}_m by equation (11). Because we adopt a common value for variance for all data, the estimation errors
128 of relative source locations derived by equation (11) become the same for all events.

129 Ichihara and Matsumoto (2017) estimated relative locations of volcanic tremor events using seismic
130 amplitude ratios. They calculated amplitude ratios among several stations to eliminate the source
131 radiation amplitude term ($A_0(f)$ in equation 1) and conducted a grid search to find optimal tremor
132 source locations. It appears that the approach of Ichihara and Matsumoto (2017) estimates relative source
133 locations, because the site amplification terms and intrinsic attenuation factor they used were adjusted
134 to the reference source location. Nevertheless, their principle formulation follows the original ASL
135 method. In contrast, we attribute the amplitude ratio between two events at each station to the relative
136 difference between their locations. Our approach relies on the assumption that the difference between
137 the hypocentral distance of a reference event and a subevent is much smaller than their hypocentral
138 distances, which is not required in the formulation of Ichihara and Matsumoto (2017). Our formulation
139 thus has two advantages over theirs. First, we avoid uncertainties in estimating site amplification factors.
140 Second, our fundamental formulation (equation 8) has a simple linear form, so that we can estimate not
141 only relative source locations, but also the errors on those estimations by using a standard least-squares
142 method.

143 **Data and analysis**

144 Meakandake volcano (eastern Hokkaido, northern Japan; Fig. 1a) has three active craters: Naka-
145 machineshiri, Pon-machineshiri, and Mt. Akanfuji. The eruptive history of Meakandake (Japan Me-
146 teorological Agency 2013) shows that its most recent eruption was a phreatic eruption in November 2008
147 at the 96-1 crater, on the southeastern edge of the Pon-machineshiri crater (Ishimaru et al. 2009). Many
148 earthquakes and tremors were observed before and during the 2008 eruptive period (Ogiso and Yomogida
149 2012; Japan Meteorological Agency 2013). In this study, we used seismograms of VT earthquakes and
150 volcanic tremors recorded during the 2008 activity at Meakandake by five stations (Fig. 1a) operated by
151 the Sapporo Regional Volcano Observation and Warning Center (RVOWC) of the Japan Meteorological
152 Agency. Vertical-component short-period (natural period 1 s) seismometers were deployed at stations
153 V.PMNS and V.NSYM, and three-component short-period (1 s) seismometers were deployed at the other
154 three stations. Each seismogram was digitized at a sampling rate of 0.01 s.

155 In this study, we used 1-D velocity and attenuation structure of S-waves shown in Fig. 1b. The velocity
156 structure was derived by trial-and-error approach at Sapporo RVOWC, which has been used there for
157 routine hypocenter determinations since August 2017 (Okuyama, 2020, personal communication). The
158 attenuation structure we used is that of Kumagai et al. (2019), which they used in their application of
159 the ASL method at Nevado del Ruiz volcano (Colombia). We conducted a ray shooting in a spherical
160 coordinate (e.g., Aki and Richards 1980, Chapter 13) to derive \mathbf{n}_i^j in equation (9).

161 To validate the source locations of the VT earthquakes determined by our new method by comparing
162 them with those determined from phase arrival times, we selected 45 earthquake events that occurred
163 near the 96-1 crater between 1 and 10 November 2008 for which the Sapporo RVOWC had determined
164 hypocenters from phase arrival times. We manually picked up the arrival times of P-waves at all five
165 stations and those of S-waves at stations V.MEAB and V.MNDK (Fig. 2). Note that because the phase
166 arrivals for these earthquakes were clearly evident on all of the seismograms, any event location method
167 using phase arrival times would be suitable for further analysis of this seismic activity. We calculated
168 source locations by three methods: (a) absolute hypocenter estimation from phase arrival times with
169 the HYPOMH algorithm (Hirata and Matsu'ura 1987), (b) master event location estimation (Aoki 1974)
170 using differences of P-wave arrival times, and (c) our new method of estimating relative source locations
171 from seismic amplitudes. The reference event we used for the latter two methods was an earthquake at
172 21:30 (Japan Standard Time; JST) on 7 November 2008 (latitude 43.3829°, longitude 144.0093°, depth
173 -0.40 km). This reference location was originally determined from the phase arrival times and the
174 HYPOMH algorithm. We selected this reference event because its epicenter was at the centroid of all
175 of the hypocenters derived from the phase arrival times. The P-wave velocity structure we used for the
176 HYPOMH algorithm and master event method was $\sqrt{3}$ times larger than S-wave velocity structure shown
177 in Fig. 1b. For our method of relative source location, we applied a 5–10 Hz bandpass filter to the data
178 of each seismogram, and calculated the root-mean-square (RMS) amplitude of the vertical component
179 within a time window extending for 10 s after the P-wave arrival (Fig. 2). We set frequency f in equation
180 (2) to 7.5 Hz.

181 For comparison of the calculated volcanic tremor locations, we selected tremors that occurred on 16 and
182 17 November 2008. Ogiso and Yomogida (2012) applied the ASL method to these events and identified
183 segmentation in their source regions. The duration time of 15 November tremor was about 30 min (Ogiso
184 and Yomogida 2012). Following the approach of Ogiso and Yomogida (2012), we divided the first 18

185 min of the tremor into three phases (Fig. 3a) and estimated source locations for each phase. During
186 17 and 18 November, small-amplitude, long-duration tremors were observed intermittently (Ogiso and
187 Yomogida 2012, Fig. 18). Because amplitude ratios among stations did not change significantly during
188 these intermittent tremors (Ogiso and Yomogida 2012, Fig. 21), we estimated tremor locations from
189 11:00 to 12:00 (JST) on 17 November (Fig. 3b). Because the velocity and attenuation structures we
190 used (Fig. 1b) differed from the simple structures used by Ogiso and Yomogida (2012), we analyzed the
191 locations of these tremors by both the ASL method and our new relative source location method. The
192 process we used to prepare amplitude data was similar to that used for analysis of volcanic earthquakes,
193 apart from the length of the time window. After applying a 5–10 Hz bandpass filter, we calculated the
194 time series of RMS amplitudes from the vertical-component seismogram at each station within a 30-s time
195 window that we shifted by 15 s for each calculation. We then used these time series of RMS amplitudes
196 for both the ASL and our relative source location methods. For the ASL method, we used the same
197 amplification factors as those estimated by Ogiso and Yomogida (2012) using the coda normalization
198 method, and performed a grid search with 0.001° increments of latitude and longitude and a 0.1 km depth
199 increment. For our relative source location method, we set the reference location at latitude 43.378°,
200 longitude 144.005° and 0.1 km depth, which was the tremor location from 01:05:05 to 01:05:35 (JST) on
201 16 November, as estimated by the ASL method in this study.

202 **Results and discussions**

203 **VT earthquakes**

204 Comparison of the hypocenter distributions of VT earthquakes estimated by the three considered source-
205 location methods (Fig. 4) shows that the focal region derived from phase arrival times extends about 0.5
206 km horizontally and 1.2 km vertically (Fig. 4a), and that derived by our relative source location method
207 extends about 0.7 km horizontally and 1.0 km vertically (Fig. 4c). The focal region derived by the master
208 event method on the basis of differences of P-wave arrival times (Fig. 4b) had the smallest extent among
209 three results: about 0.2 km horizontally and 0.6 km vertically. We note that the absolute source locations
210 by the master event method and our relative source location method (Figs. 4b and 4c) depended on the
211 location of the selected reference event.

212 The choice of attenuation structure affected the extent of the focal region for our relative source location
213 method. Equation (8) indicates that an observed amplitude ratio can be decomposed into the ratio of

214 the source radiation amplitude and the difference in relative source location. Variable B in equation (8)
215 (i.e., the intrinsic attenuation factor in the region of the reference event) determines the contribution of
216 the difference between relative locations to the observed amplitude ratio. If Q is large, the contribution
217 of the difference between relative locations becomes small and the distribution of relative source locations
218 widens. In contrast, the relative source locations converge toward zero with a small value of Q . Ideally,
219 the attenuation structure around the target focal region should be evaluated independently by some other
220 method, such as simultaneous inversion of the source, attenuation and site amplification terms (e.g., Oth
221 et al. 2011; Nakano et al. 2015). Use of a detailed 3-D heterogeneous attenuation structure around a
222 source region (e.g., Matsumoto et al. 2009) would greatly improve the precision of our source location
223 method.

224 The depth distributions of source locations differ slightly among the three results. The source-depth
225 distribution derived from phase arrival times seems to have a mean of about 0.25 km (Fig. 4a). That
226 derived by the master event method shows most of the sources to be concentrated at about 0 km depth
227 (Fig. 4b). In contrast, the source-depth distribution derived by our relative source location method
228 (Fig. 4c) shows two clusters: the one at about at 0 km and the other at -0.5 km depth. Comparison
229 of this depth distribution to that of the relative source locations derived by the master event method
230 suggests that the shallow source locations derived by our new location method (around -0.5 km depth;
231 Fig. 4c) may not be actual ones. This apparent depth segmentation may be due to two different focal
232 mechanisms. Because the onsets of P- and S-waves for these events were clearly evident in seismograms,
233 their radiation patterns should not be isotropic. If the focal mechanisms of the two events were similar to
234 each other, their spatial distributions of seismic amplitude should also be similar, so the amplitude ratios
235 of the two events well reflect the differences between their source radiation amplitudes and their relative
236 source locations (i.e., equation 5). For events with different focal mechanisms, the amplitude ratios
237 would be dependent on the azimuth of each station. Under such circumstances, equation (5) no longer
238 holds and the results obtained by our new relative source location method may be erroneous. Distortion
239 or reduction of radiation patterns due to multiple scattering of seismic waves (Takemura et al. 2009;
240 Kobayashi et al. 2015) has important ramifications for the ability of our method to stably locate seismic
241 events with different focal mechanisms, as is also the case for the ASL method (Morioka et al. 2017). If
242 the focal mechanisms among events are similar to each other, the relative source locations estimated by
243 seismic amplitude ratios will be equally as reliable as the absolute source locations estimated from phase

244 arrival times, regardless of the scattering properties of the medium.

245 **Tremors of 16 and 17 November**

246 We now compare the distribution of source locations of volcanic tremors estimated by our method with
247 that estimated by the ASL method. We assumed that the tremors on 16 and 17 November had no clear
248 azimuthal dependency in their spatial distributions of seismic amplitudes. Tremors, which have relatively
249 continuous signals, should be less affected by differences in focal mechanism than the dominant P- and
250 S-wave arrivals of VT earthquakes.

251 There is a clear southwest to northeast horizontal trend of source locations in all four results (Fig. 5), but
252 their horizontal extents differ. The horizontal extent of source locations obtained using the ASL method
253 are from 1.0 km (Fig. 5c) to 1.5 km (Fig. 5a) whereas those obtained using our new method are from 0.8
254 km (Fig. 5d) to 1.0 km (Fig. 5b); thus, our method located the tremor sources in more compact regions.
255 Ogiso and Yomogida (2012) found that the tremor locations on 16 November migrated among phases 1,
256 2, and 3, and that the spatial distribution of phase 3 of the 16 November tremor overlapped those of the
257 following intermittent long-duration tremors on 17 to 18 November. The tremor locations we estimated
258 by the ASL method (Figs. 5a and 5c) show similar characteristics as those of Ogiso and Yomogida (2012,
259 Figs. 15 and 20). They interpreted the location differences of the tremor on 16 November represented
260 downward migration of the tremor source during phases 1 and 2, and that the source region of phase 3
261 connected the source regions of phases 1 and 2 with those of the following intermittent tremors.

262 The relative source locations estimated by our new method (Figs. 5b and 5d) show similar overall
263 characteristics to those estimated by the ASL method (Figs. 5a and 5c), but the detail of the spatial
264 relationships of source regions for the three phases of tremor on 16 November differ as follows (Figs. 5a
265 and 5b). Our method showed the source region of the phase 1 tremor to be more tightly concentrated
266 on the western flank of Mt. Akanfuji, with those of phases 2 and 3 a little farther to the northeast of
267 the phase 1 source region, but not extending as far to the northeast as those estimated by the ASL
268 method. In particular, the source region of the phases 2 and 3 overlapped each other. The source region
269 of the tremor of 17 November estimated by our new method was the east of the source regions of the
270 tremor of 16 November, and there was no overlap of the source regions of the events on those two days.
271 This difference between the spatial relationships of the source regions of tremors estimated by the ASL
272 method and our new method may partly reflect to the uncertainty of the site amplification correction
273 in the ASL method. If the site amplification factor at one station differed greatly from its true value,

274 the source radiation amplitude (equation 3) would also differ from its true value, and the ASL method
275 would then estimate an incorrect source location. If there were many observations (stations), an error in
276 site amplification factor at a single station would be suppressed because equation (3) uses the average of
277 site-corrected amplitudes at all stations. However, the smaller the number of observations (we used only
278 five stations), the larger the influence of each observation on the location estimated by the ASL method.
279 In contrast, our relative source location method minimizes the effect of such errors in site amplification
280 corrections for estimation of source locations. The difference between the source locations derived by
281 the ASL and those derived by our new method demonstrate the ability of our method to cancel out the
282 uncertainties of site amplification factors when there are few stations.

283 Takahashi et al. (2018) found a region of low resistivity located beneath the northwest flank of Mt. Akan-
284 fuji from audio-frequency magnetotelluric observations, which corresponds to the source regions we iden-
285 tified for three tremor phases on 16 November (Fig. 5b). On the basis of broadband seismic observations,
286 Aoyama and Oshima (2015) retrieved the change of tilt that they attributed to the opening of a vertical
287 crack in the volcanic edifice. To explain the change of tilt, Takahashi et al. (2018) proposed a model
288 in which upward heat convection caused the rapid flow of heat into the low resistivity zone. Migration
289 of the source location, as estimated by the ASL method for the tremor of 16 November, appears to be
290 inconsistent with the model of Takahashi et al. (2018): the descent of the source location between phases
291 1 and 2 conflicts with the upward heat transfer of their model. In contrast, the relative locations in this
292 study by applying our new method are consistent with their model: the source region of the phase 1 is
293 consistent the activation of volcanic fluids in the low resistivity zone, and the ascent of source locations
294 between phases 2 and 3 is consistent to the rapid transfer of heat from depth.

295 The locations of the sources of the intermittent tremors (on 17 November) remains controversial. The
296 locations we estimated by the ASL method (Fig. 5c) indicate that the source region of the intermittent
297 tremors partially overlaps that of the phase 3 of the tremor on 16 November (Fig. 5a), whereas our new
298 relative source location method separates the source regions of the two tremors (Figs. 5b and 5d). Based
299 on the source locations estimated by our method, there may have some mechanism by which the two
300 source regions were linked, although no geophysical evidence to support this link has yet come to light.
301 Future improvements in geophysical observation networks around active volcanic craters and greater
302 precision in the location of tremor sources will likely help us to understand the cause of such separations
303 of source regions.

304 **Conclusions**

305 We have presented a new method to estimate relative source locations from seismic amplitudes. The
306 method is similar to the conventional master event method except that it uses event amplitude ratios
307 instead of phase arrival times. Our method avoids the uncertainties inherent in the estimation of site
308 amplification factors by using amplitude ratios between two events at a common station. We assume
309 that for two events near to each other, the observed amplitude ratios can be attributed to the ratio of
310 source radiation amplitude and the difference of relative source location in the form of standard least-
311 squares inversion. As a result, we can use to estimate not only relative source locations but also their
312 errors. The relative source locations of VT earthquakes estimated by our new method showed that
313 using seismic amplitude ratios enabled us to derive a hypocentral distribution similar to that determined
314 by the conventional absolute source location method using phase arrival times. We applied our new
315 method to estimate relative source locations for volcanic tremors recorded at Meakandake volcano on
316 16 and 17 November 2008, and identified clear segmentation of source clusters and migration of tremor
317 source locations. The observed migration is consistent with other geophysical observations, such as the
318 resistivity structure and changes in tilt determined from broadband seismic data. Our new method of
319 source location from event amplitude data will be useful for detailed analyses of seismic events whose
320 onset times are ambiguous.

321 **Declarations**

322 **Ethics approval and consent to participate**

323 Not applicable.

324 **Consent for publication**

325 Not applicable.

326 **List of abbreviations**

327 ASL: Amplitude Source Location

328 VT: volcano-tectonic

329 RMS: root-mean-square

330 RVOWC: Regional Volcano Observation and Warning Center

331 JST: Japan Standard Time

332 **Availability of data and materials**

333 The waveform data we analyzed are available from the corresponding author on request. The source
334 codes used in this study can be downloaded from <https://github.com/mogiso/AmplitudeSourceLocation>.

335 **Competing interests**

336 The authors declare that they have no competing interests.

337 **Funding**

338 Not applicable.

339 **Authors' contribution**

340 MO estimated source locations and drafted the manuscript. KY formulated the equations and discussed
341 the results with MO. Both authors read and approved the final manuscript.

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346 velocity structure and helpful discussions about hypocenter distributions. All figures were drawn with
347 the Generic Mapping Tools version 5 (Wessel et al. 2013).

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484 **Figure legends**

485 **Figure 1:** (a) Regional location map (below) and topographic map (above) of Meakandake volcano
486 showing the locations of the five seismic stations (inverted triangles) used in this study. Topographic
487 contour interval is 50 m. (b) One-dimensional S-wave velocity (left) and attenuation (right) structures
488 used in this study. The origin of the depth is mean sea level.

489 **Figure 2:** Waveforms recorded at five stations for a VT earthquake that occurred at 21:30 on 7 November
490 2008. Vertical and N-S components are shown in black and red, respectively. Gray solid and dashed lines
491 denote P- and S-wave arrival times, respectively. The black double-headed arrows indicate the time
492 windows used to calculate RMS amplitudes.

493 **Figure 3:** Vertical component of tremor waveforms recorded at station V.MEAB on (a) 16 November
494 and (b) 17 November 2008. We estimated tremor locations for the waveforms shown in red in (b). Note
495 that both waveforms were decimated without anti-aliasing filtering to reduce the file size of the figure.

496 **Figure 4:** Plan and vertical cross-sectional views of the hypocenter distributions of VT earthquakes from
497 1 to 10 November 2008 derived from (a) phase arrival times and the HYPOMH algorithm, (b) the master
498 event method using differences of P-wave arrival times, and (c) our relative source location method. In
499 panels (b) and (c), estimated location errors are shown in the lower corners. In the plan views, inverted
500 triangles denotes seismic stations, and elevation contours are at 50 m intervals.

501 **Figure 5:** Locations of the tremors of (a, b) 16 and (c, d) 17 November as estimated by (a, c) the ASL
502 method and (b, d) our new location method. In (a) and (b), the red, green, and blue stars indicated source
503 locations for the three phases indicated by the same colors in Fig. 3a.

Figures

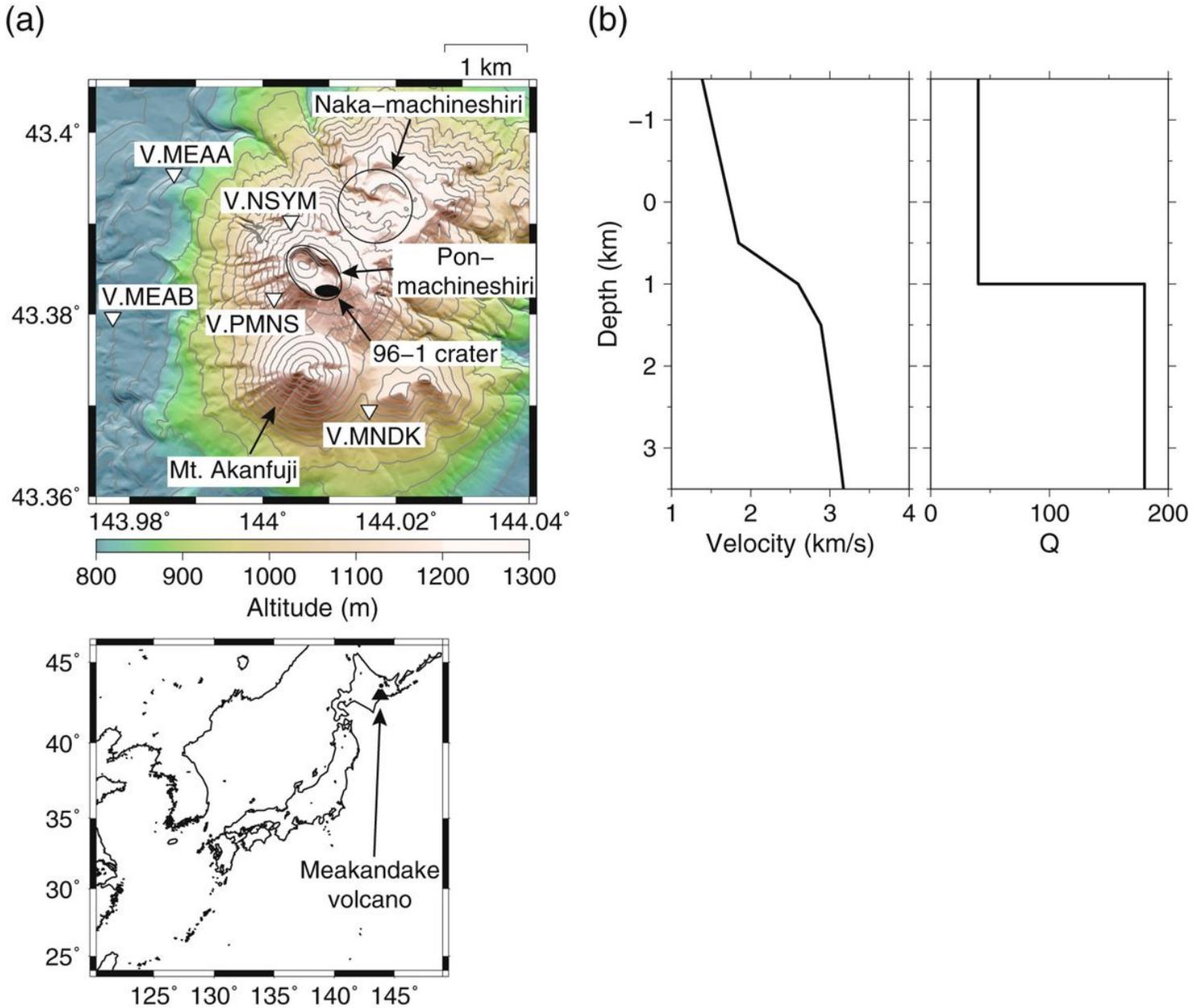


Figure 1

(a) Regional location map (below) and topographic map (above) of Meakandake volcano showing the locations of the five seismic stations (inverted triangles) used in this study. Topographic contour interval is 50 m. (b) One-dimensional S-wave velocity (left) and attenuation (right) structures used in this study. The origin of the depth is mean sea level.

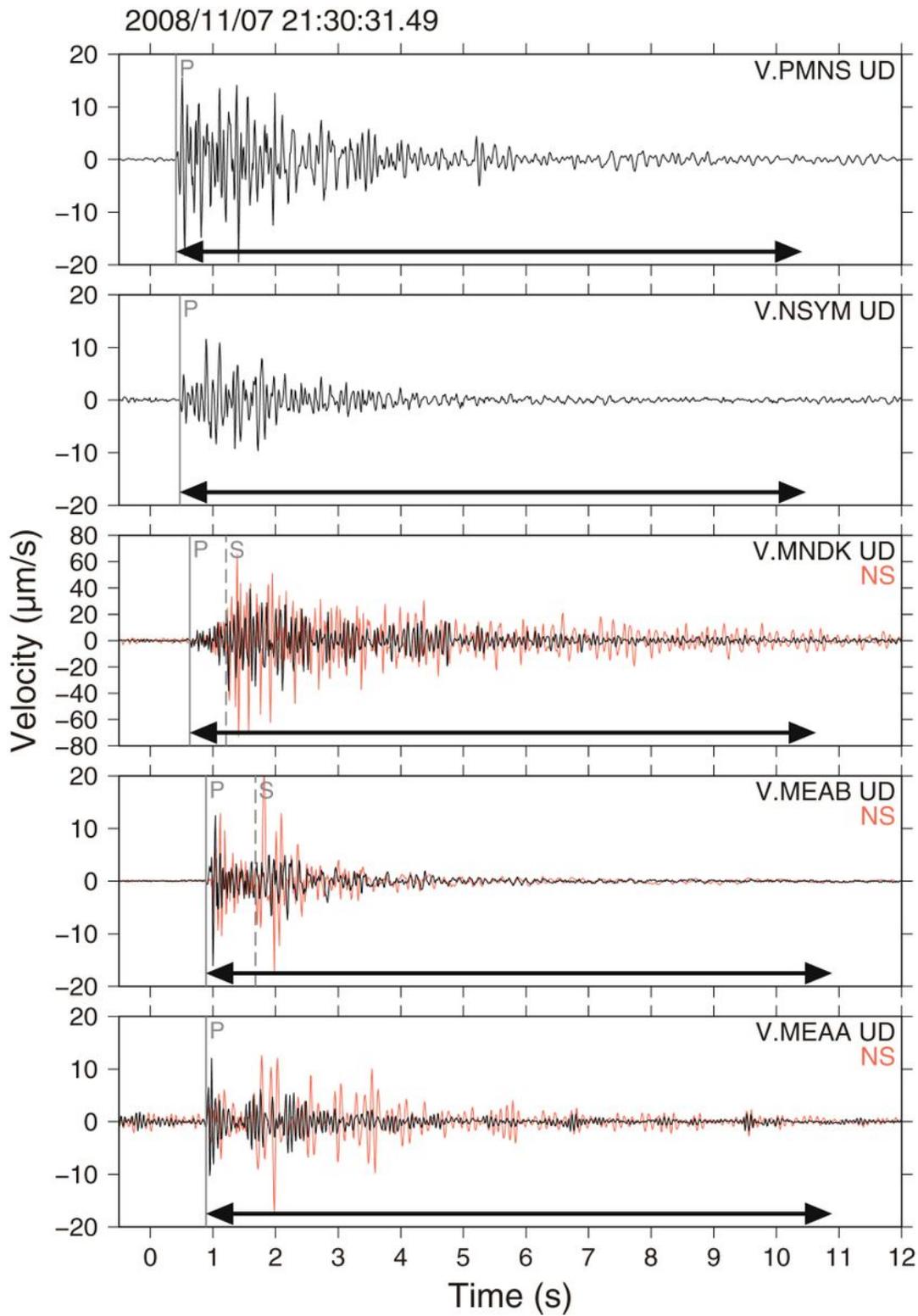


Figure 2

Waveforms recorded at five stations for a VT earthquake that occurred at 21:30 on 7 November 2008. Vertical and N-S components are shown in black and red, respectively. Gray solid and dashed lines denote P- and S-wave arrival times, respectively. The black double-headed arrows indicate the time windows used to calculate RMS amplitudes.

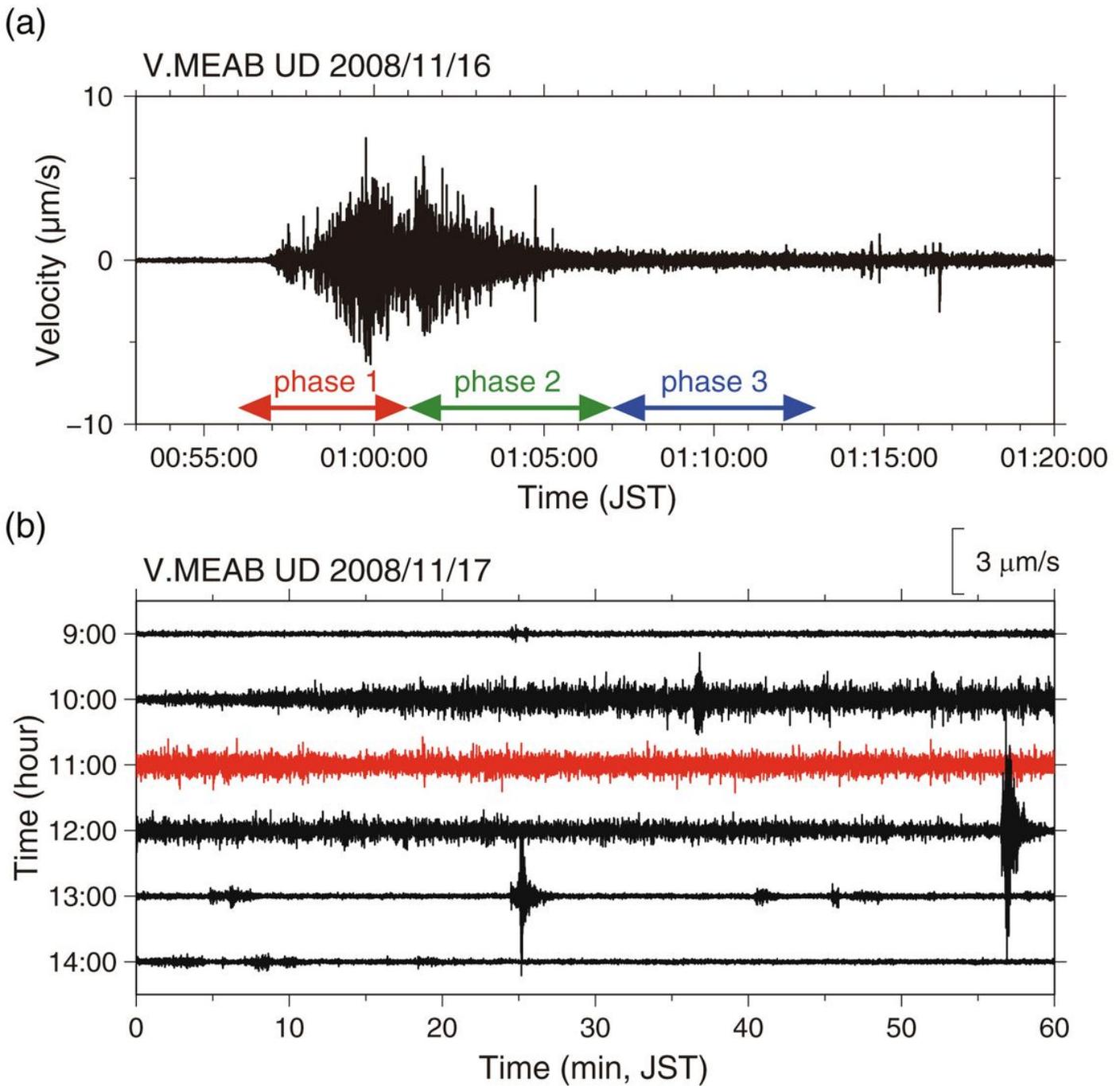


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Vertical component of tremor waveforms recorded at station V.MEAB on (a) 16 November and (b) 17 November 2008. We estimated tremor locations for the waveforms shown in red in (b). Note that both waveforms were decimated without anti-aliasing filtering to reduce the file size of the figure.

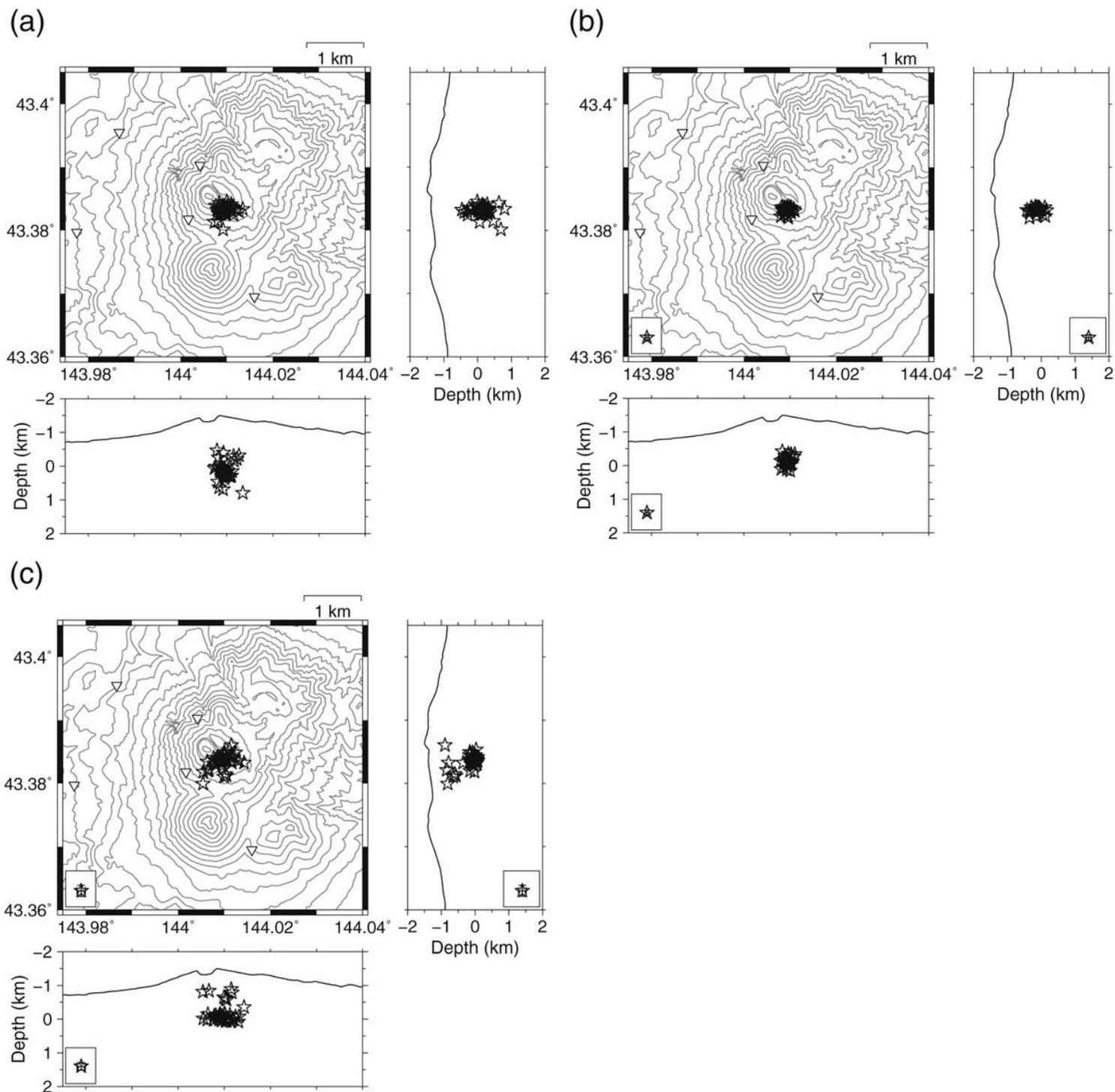


Figure 4

Plan and vertical cross-sectional views of the hypocenter distributions of VT earthquakes from 1 to 10 November 2008 derived from (a) phase arrival times and the HYPOMH algorithm, (b) the master event method using differences of P-wave arrival times, and (c) our relative source location method. In panels (b) and (c), estimated location errors are shown in the lower corners. In the plan views, inverted triangles denotes seismic stations, and elevation contours are at 50 m intervals.

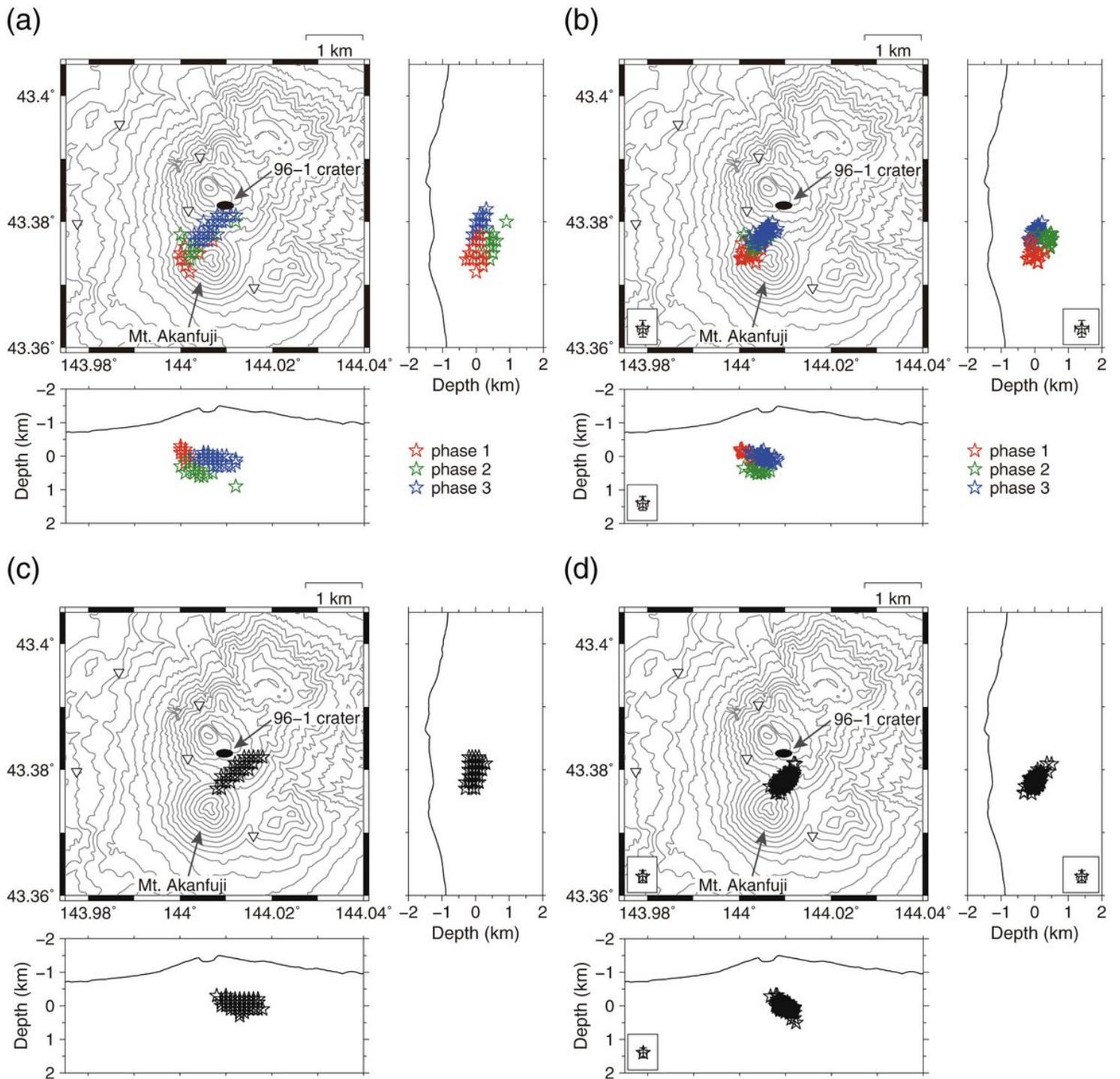


Figure 5

Locations of the tremors of (a, b) 16 and (c, d) 17 November as estimated by (a, c) the ASL method and (b, d) our new location method. In (a) and (b), the red, green, and blue stars indicated source locations for the three phases indicated by the same colors in Fig. 3a.

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