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Article

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A Low-Power Biomimetic Crypto Engine for *All-In-One* IoT based on Programmable and Multifunctional MoS₂ FETs

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Abstract: In the emerging era of internet of things (IoT), ubiquitous sensors continuously collect, consume, store, and communicate an astonishing volume of information, which are becoming increasingly vulnerable to theft and misuse. Modern software crypto systems are powerful but require extensive computational infrastructure for implementing ciphering algorithms making it difficult to be adopted by IoT edge sensors that operate with limited hardware resources and at miniscule energy budgets. Here we propose, and experimentally demonstrate a low-power, biomimetic, crypto system integrated with IoT edge sensor based on an array of atomically thin, multifunctional, and programmable MoS₂ field effect transistors (FETs). We show that the information received by a MoS₂ photodetector and encrypted by a population of MoS₂ based reconfigurable artificial neural encoders is secure from an eavesdropper with finite resources. We also show that our *all-in-one* IoT platform consumes miniscule energy in the range of tens to hundreds of pico Joules, has a small hardware footprint, and combines sensing, non-volatile storage, and security, for the first time.

Introduction

Information security is key for sustainable growth and development of any modern society that thrives on global connectivity in this new era of Internet of Things (IoT). Today, information is collected, stored, and communicated continuously by IoT sensors and edge devices that are found ubiquitously in our homes, workplaces, industrial manufacturing plants, transportation, health sectors, agricultural fields, and so on and so forth. However, there is an escalating threat of information loss, misuse, and manipulation owing to the involvement of untrustworthy parties [1]. While the state-of-the-art crypto systems offer powerful security solutions based on complex ciphering algorithms [2-4] that can be implemented using hardware accelerators [5], IoT edge devices have many restrictions in terms of computational capabilities due to limited hardware and energy resources. Furthermore, low-cost design needs, large-scale deployments, and heterogeneous nature of the IoT sensors limit direct adoption of traditional security solutions, including the widely used public key scheme. Due to inadequate security, IoT devices used in smart-cars, and smart-homes have shown tremendous vulnerability in the recent times [6]. Therefore, wider adoption of IoT technology can be greatly hindered if cryptosystems and security protocols which require less computational resources are not developed and integrated with the IoT edge sensor in a timely manner.

Here, we exploit a new paradigm, namely, in-memory biomimetic computing to offer an integrated sensing, storage, and security solution for IoT edge devices with minimal hardware investments and at frugal energy expenditure. Our demonstration is based on atomically thin and multifunctional MoS₂ field effect transistors (FETs) with a programmable gate stack that can be used as sensor, i.e. photodetector (PD), as well as various components of the proposed cryptographic engine or artificial neural encoder. The encryption is done by a finite population (P)

of encoders with reconfigurable encoding threshold (V_{TH}) using a zero mean white Gaussian noise (WGN) of finite standard deviation (σ). The decryption requires an optimum number of voting mandate (V_M) that is determined by P , V_{TH} , and σ without the knowledge of which an eavesdropper requires an astronomical number of brute force trials (BFTs) for deciphering the information. In fact, the information remains concealed even if the eavesdropper has access to a trained artificial neural network (ANN). Note that our inspiration is derived from the organization of peripheral and central nervous system which employ similar cell type i.e. neurons with different functionalities that transduce external sensory information into electrical impulses and then communicate with each other as a group through successive encoding and decoding processes in the presence of a wide range of synaptic noise. To the best of our knowledge, this is the first demonstration of an *all-in-one* biomimetic IoT hardware platform based on multifunctional MoS₂ FETs that integrates sensing, non-volatile storage, and security. See **Extended Data 1** for a benchmarking table summarizing earlier works based on 2D materials and memristors that combine either sensing and storage or security and storage.

Fig. 1a shows the schematic of our proposed *all-in-one* IoT platform. The IoT sensor collects the information, which is encrypted using an array of encoders. Each encoder comprises of a white Gaussian noise adder (WGNA) and an artificial neuron (AN). Fig. 1b shows the associated hardware based on programmable and multifunctional MoS₂ field effect transistor (FET) arrays, which are used as photodetectors (PDs) for sensing, and WGNAs and ANs for encryption. Fig. 1c shows an example experimental demonstration of sensing and ciphering. Information, for example, an 8×8 pixelated image of the letter ‘N’ obtained by illuminating a blue light emitting diode (LED) is presented to the IoT sensor, i.e. MoS₂ PD. The photocurrent (I_{PH}) in response is superimposed

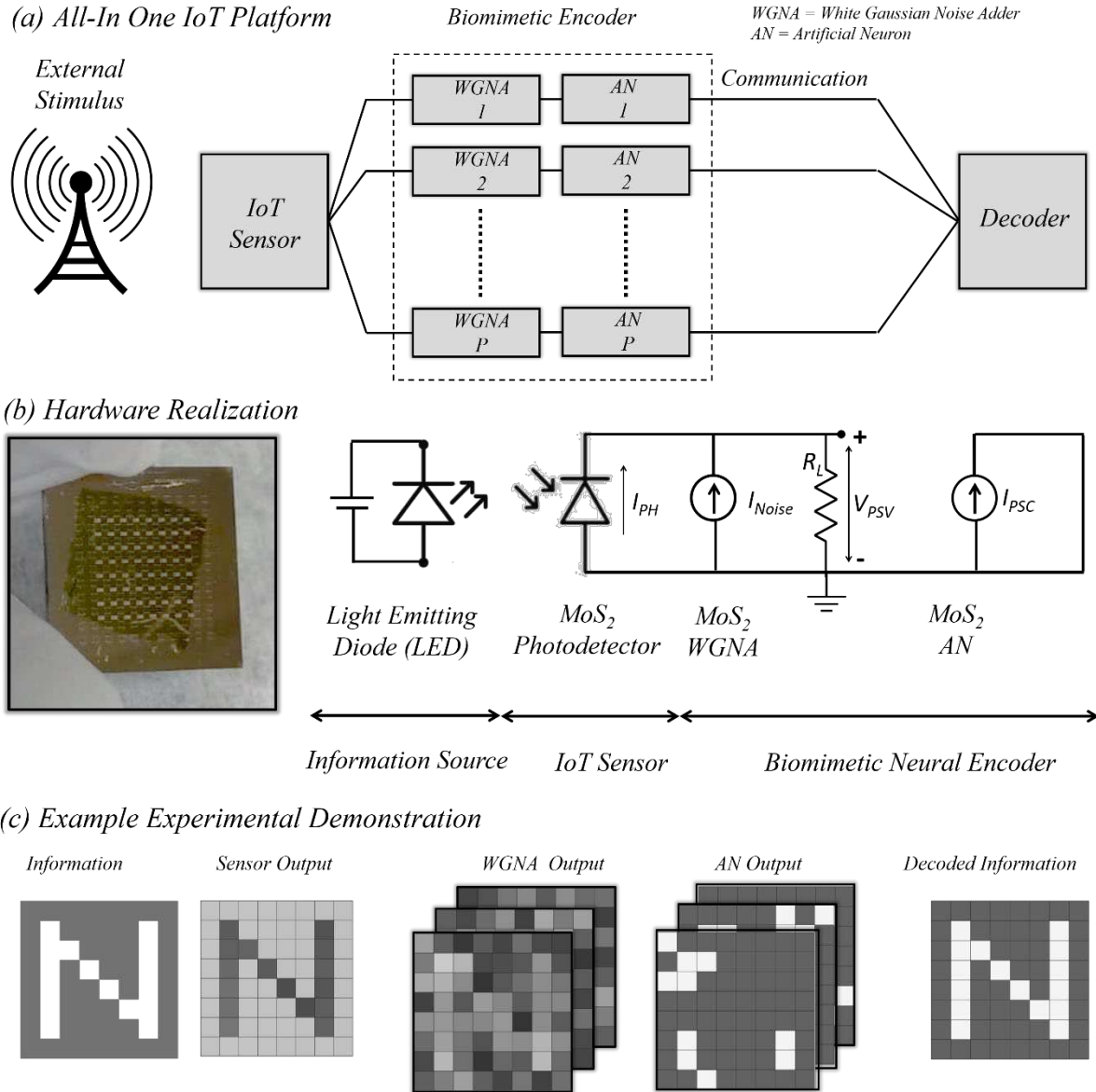


Figure 1. Hardware realization of all-in-one IoT platform based on programmable and multifunctional MoS₂ field effect transistor (FET) arrays. a) Schematic representation of our proposed all-in-one IoT platform that involves sensing, storage, and security. The IoT sensor collects the information, which is encrypted using an array of encoders. Each encoder comprises of a white Gaussian noise adder (WGNA) and an artificial neuron (AN). b) Associated hardware based on programmable and multifunctional MoS₂ FET arrays, which are used as photodetector (PD) for sensing, and WGNA and AN for encryption. c) An example experimental demonstration of sensing and ciphering. Information, for example, an 8×8 pixelated image of the letter ‘N’ obtained by illuminating a blue light emitting diode (LED) is presented to the IoT sensor, i.e. MoS₂ PD. The photocurrent (I_{PH}) in response is superimposed with zero mean white Gaussian noise (WGN) of desirable standard deviation and transduced to subthreshold presynaptic voltage (I_{PSV}) using MoS₂ WGNAs and presented to MoS₂ ANs with pre-programmed threshold voltages. The information is revealed by a decoder through a voting process if the encoding knowledge is accessible.

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The use of MoS₂ for our *all-in-one* IoT platform is motivated by recent studies demonstrating various low-power sensors based on MoS₂ that can benefit the IoT technology [7-13]. In addition, MoS₂ offers compatibility with flexible [14] and printable technologies [15] and shows promise for neuromorphic and biomimetic applications [16-18]. MoS₂ used in this study was grown epitaxially on a sapphire substrate using metal organic chemical vapor deposition (MOCVD) technique at 1000 °C and subsequently, transferred from the growth substrate to the device fabrication substrate using the PMMA-assisted wet transfer process [19]. The large area MOCVD growth allows for the fabrication of low-power and programmable monolayer MoS₂ FET arrays that can be used for sensing, storage, and ciphering information. See **Methods** section for further details on the synthesis, film transfer, and fabrication of MoS₂ FETs. Fig. 2a-b show the schematic and optical image of arrays of such MoS₂ FETs used for our *all-in-one* IoT platform. Fig. 2c shows the transfer characteristics, i.e. source to drain current (I_{DS}) as a function of the back-gate voltage (V_{BG}) at different drain biases (V_{DS}) for a representative MoS₂ FET with 1 μm channel length, 5 μm channel width, and a stack of 40 nm Ni/30 nm Au as the source and drain contacts. The back-gate stack for the FET comprised of atomic layer deposition (ALD) grown 50 nm Al₂O₃ on Pt/TiN/p⁺⁺-Si. As we will discuss next, this gate stack allows realization of analog, non-volatile, and programmable memory states in MoS₂ FETs, which is the key towards the realization of crypto

engine for IoT security. In addition, the use of thin and high-k gate oxide such as Al₂O₃ compared to conventional 300 nm of SiO₂ facilitates better electrostatic control of the MoS₂ channel and allows operation below 5 V, which is critical for achieving low-power IoT platform. As seen in Fig. 2c MoS₂ FET is a unipolar, and n-type thresholding device with $V_{TH} = 0.8$ V, extracted for $I_{DS} = 10$ pA/ μ m, which is 10 times higher than the average noise floor, i.e. 1 pA/ μ m. In other words the device is considered to be ON if $I_{DS} \geq 10$ pA/ μ m. The device also exhibits excellent ON/OFF current ratio of $\sim 10^7$ and subthreshold slope (SS) of less than 225 mV/decade. The electron field effect mobility (μ_{FE}) value extracted from the peak transconductance was found to be ~ 10 cm²/V-s. Fig. 2d shows the output characteristics of the MoS₂ FET, i.e. I_{DS} versus V_{DS} for different V_{BG} . Relatively high ON current of ~ 37 μ A/ μ m at $V_{DS} = 5$ V for an inversion charge carrier density of $\sim 6.2 \times 10^{12}$ /cm² confirms high quality of our MOCVD grown monolayer MoS₂. Note that while our mobility and ON current values are on par with the state-of-the-art literature on large area grown MoS₂, these do not play a significant role in our proposed IoT platform as we will exploit subthreshold device operation to achieve energy efficiency.

Next, we demonstrate the capability of programming our monolayer MoS₂ FETs in any desirable conductance state with non-volatile retention characteristics. The results are shown in Fig. 2e-h. When “Write” programming pulses of different amplitudes, V_p , are applied to the back-gate electrode, each for a total duration of $t_p = 1$ s, the transfer characteristics of the device shifts towards the right as illustrated in Fig. 2e. During programming, the source and drain terminals were grounded. Fig. 2f shows the extracted iso-current (~ 10 pA) threshold voltages, V_{TH} , corresponding to each state measured multiple times, post-programming, to ensure non-volatile retention. Similar observations are made when “Write” programming pulses of same amplitude,

$V_p = 10$ V, but different t_p , are applied to the back-gate electrode as shown in Fig. 2g. Fig. 2h shows the corresponding non-volatile shift in V_{TH} . The shift in V_{TH} can be attributed to our back-gate stack that closely resembles floating gate (FG) configuration used in non-volatile flash memory [20]. See *Extended Data 3* explaining the memory operation using energy band diagrams. In short, the p^{++} -Si/TiN/Pt interface in the stack is characterized by a Schottky barrier (SB), whereas, the gate dielectric, i.e. 50 nm Al_2O_3 , acts as an oxide barrier (OB). The OB is much wider and taller compared to the SB. When a large positive back-gate voltage, $V_{BG} = V_p$, i.e. “Write” pulse is applied to the control gate (CG), i.e. p^{++} -Si, carriers tunnel from the p^{++} -Si into the Pt/TiN floating gate (FG) and remains trapped even when the V_p is released. These negative fixed charges on the FG screen the electric field from CG and thereby makes the V_{TH} more positive. The total amount of charge injected into the FG, and hence shift in V_{TH} of the MoS_2 FET can be controlled by the amplitude, and duration, of the “Write” programming pulse as shown in Fig. 2e and 2g, respectively. Note that once programmed, the devices continue to remain in the programmed state as evident from the retention measurements displayed in Fig. 2f and 2h. This is critical for non-volatile memory operation. Furthermore, the device can be programmed in any desired state indicative of analog memory operation, which we will exploit later for the realization of look-up-table based Gaussian random number generator for the ciphering operation. It is also possible to restore the device from any programmed state to its initial state by applying negative voltage pulses of certain magnitude and duration (see *Extended Data 4* for preset, set, and reset of a representative MoS_2 FET). It is also important to mention here that although our back-gate stack is global, programming and erase operations can be performed on individual MoS_2 FETs without impacting the adjacent devices (see *Extended Data 5*). Finally, the “Write” energy (E_W) was found to be in the range of 500 -1000 fJ calculated based on $E_W = 1/2 C_G V_p^2$.

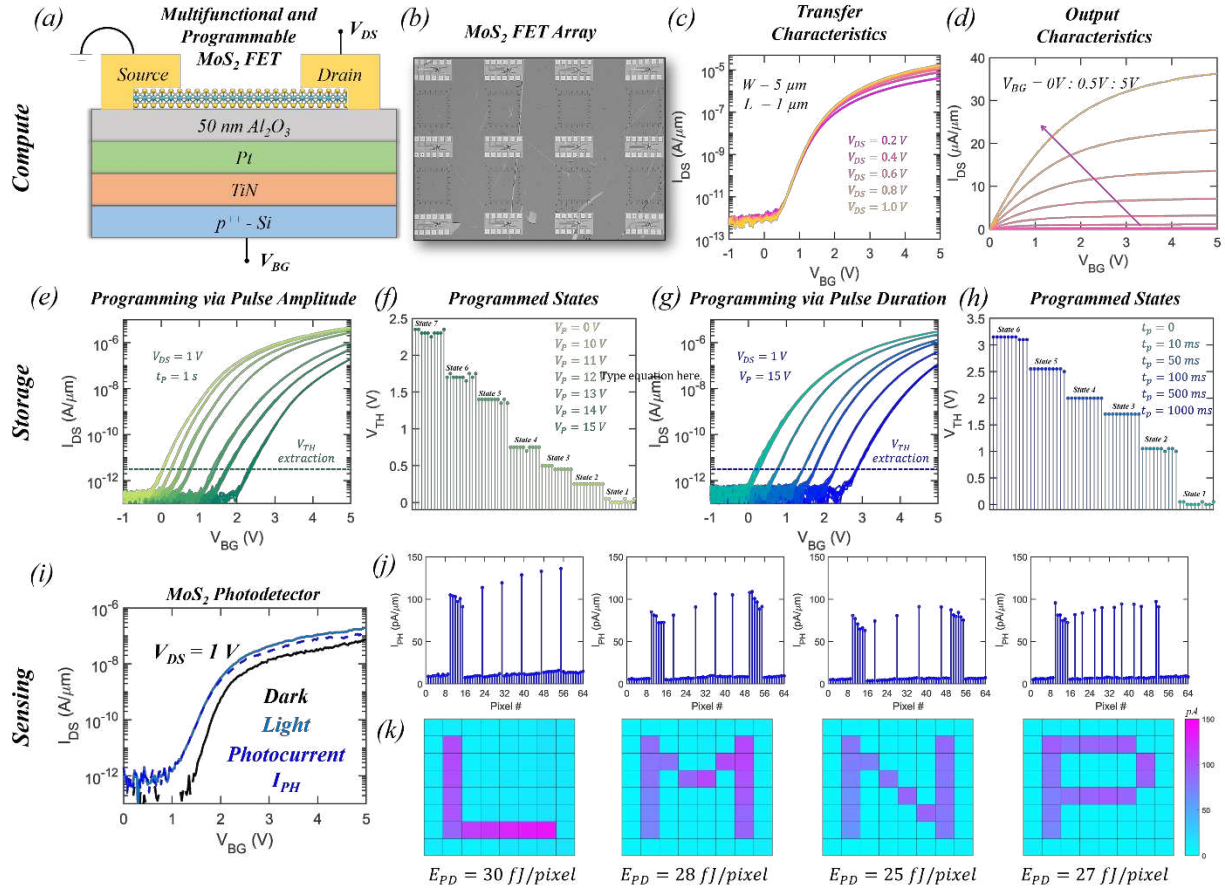


Figure 2. MoS₂ FET for compute, storage, and sensing. a) Schematic of MoS₂ FET with programmable back-gate stack comprised of atomic layer deposition (ALD) grown 50 nm Al₂O₃ on Pt/TiN/p⁺⁺-Si. b) Optical image of arrays of MoS₂ FETs used for our all-in-one IoT platform. c) Transfer characteristics, i.e. source to drain current (I_{DS}) versus back-gate voltage (V_{BG}) at different drain biases (V_{DS}) for a representative MoS₂ FET with 1 μm channel length (L), 5 μm channel width (W), and a stack of 40 nm Ni/30 nm Au as the source and drain contacts. d) Output characteristics of the MoS₂ FET, i.e. I_{DS} versus V_{DS} for different V_{BG} . e) Shift in transfer characteristics of MoS₂ FET when “Write” programming pulses of different amplitudes, V_p , are applied to the back-gate electrode, each for a total duration of $t_p = 1$ s. f) Extracted iso-current (~ 10 pA) threshold voltages, V_{TH} , corresponding to each state in (e) measured multiple times, post-programming to demonstrate non-volatile retention. g) Corresponding non-volatile shift in V_{TH} . The device can be programmed to any desired conductance state indicative of analog memory operation. i) Transfer characteristics of MoS₂ FET in dark and under the illumination of a blue LED, placed at ~ 1 cm distance. The device shows reasonable photoresponse and hence can be used as a photodetector (PD). j) Photoresponse (I_{PH}) of the device, measured at $V_{BG} = 1.5$ V to different input stimulus, i.e. 8×8 pixelated images of the letters, ‘L’, ‘M’, ‘N’, and ‘P’, obtained through the LED illumination. Each pixel corresponds to 1 ms LED illumination. k) Corresponding photocurrent maps demonstrate that the MoS₂ PD can accurately translate optical information into electrical response. Note that the MoS₂ PD was biased in the subthreshold regime to enable exponential reduction in the dark current (~ 1 pA) and thereby making $I_{PH} = I_{DS}$ under illumination. This also allows ultra-low-power photodetection with energy expenditure in the range $E_{PD} \sim 25\text{-}30$ pJ/pixel, averaged over all pixels.

Next, we demonstrate the photosensing capability of monolayer MoS₂ FET. Fig. 2i shows the transfer characteristics of a representative MoS₂ FET in dark and under the illumination of a blue LED, which is placed at ~ 1 cm distance operating at its maximum rated brightness (5 V). Clearly, the device shows reasonable photoresponse and hence can be used as a photodetector (PD). Note that unlike most studies that use LASER excitation to evaluate the photoresponse of MoS₂ FETs, we have used LED as the optical source to resemble more realistic lighting ambience where most IoT sensors will be deployed. The phototransduction mechanism in MoS₂ PD is extensively studied in the literature including our previous reports and can be ascribed to a combination of photocarrier generation in the MoS₂ channel as well as photogating effect arising due to charge trapping/detrapping at the MoS₂/gate-dielectric interface [21]. Fig. 2j shows the photoresponse (I_{PH}) of the device, measured at $V_{BG} = 1.5$ V to different input stimulus, i.e. 8×8 pixelated images of the letters, ‘L’, ‘M’, ‘N’, and ‘P’, obtained through the LED illumination. Each pixel corresponds to $t_L = 1$ ms LED illumination. The corresponding photocurrent maps in Fig. 2k demonstrate that the MoS₂ PD is able to accurately transcribe the optical information into electrical response. Note that the MoS₂ PD was biased in the subthreshold regime to enable exponential reduction in the dark current (~ 1 pA) and thereby making $I_{PH} = I_{DS}$ under illumination. This also allows ultra-low-power photodetection with energy expenditure in the range $E_{PD} \sim 25\text{-}30$ fJ/pixel, averaged over all pixels.

Fig. 3 shows the implementation of the biomimetic crypto engine or artificial neural encoder based on programmable MoS₂ FETs. Fig. 3a show the circuit diagram for the MoS₂ WGNA, which comprises of a current adder (CA) and a look-up-table based white Gaussian Noise (WGN) generator. The CA adds white Gaussian noise (I_{NOISE}) obtained from the WGN generator to the

photocurrent (I_{PH}) obtained from the MoS₂ PD using a simple resistor network and convert it to presynaptic voltage (V_{PSV}) to be applied to the MoS₂ AN. The WGN generator is an array of $M = 64$ MoS₂ FETs with preprogrammed threshold voltages such that their conductance values (G_M) follow random Gaussian distribution. Fig. 3b shows the transfer characteristics of MoS₂ FETs corresponding to a representative WGN generator. Fig. 3c shows the histogram of output current values ($I_M = G_M V_{DS}$) read at $V_{BG} = 0$ V with $V_{DS} = \pm 1$ V that constitute the $I_{NOISE} = [I_1 I_2 I_3 \dots I_M]$. Clearly, I_{NOISE} follow a zero mean Gaussian distribution with a standard deviation of $\sigma_I = 50$ pA/ μ m. Note that different arrays can be preprogrammed to obtain I_{NOISE} with different σ_I . While it can be argued that on-chip WGN generators are more desirable solutions, these are often power hungry, pose integration challenges, and mostly lack reconfiguration capabilities based on application needs. Instead, our in-memory look-up-table based WGN is reconfigurable and inherently energy efficient since during the field operation the noise current is simply read from the memory. Although our approach adds area overhead and utilizes storage resources, it integrates well with our *all-in-one* IoT platform. Fig. 3d shows the transduction of the photocurrent map for the letter ‘N’ to V_{PSV} for different noise standard deviation (σ_V). Note that the resistive network used by the CA allows linear transformation of the noise current into noise voltage with $\sigma_V = R_L \sigma_I$. Fig. 3e shows the corresponding V_{PSV} maps. The average energy expenditure for the transduction of I_{PH} to V_{PSV} was found to be in the range of $E_T = 160$ fJ/pixel, which includes the read energy consumed by the in-memory WGN generator, calculated using Eq. 1.

$$E_T = \sum_1^M [(I_{PH} + I_{NOISE})V_{PSV} + I_{NOISE}V_{DS}]t_L \quad [1]$$

Extended Data 6 shows the schematic and transfer characteristics of the MoS₂ FET used as AN mimicking biological neurons with pre-synaptic voltage (V_{PSV}) applied to the back-gate terminal

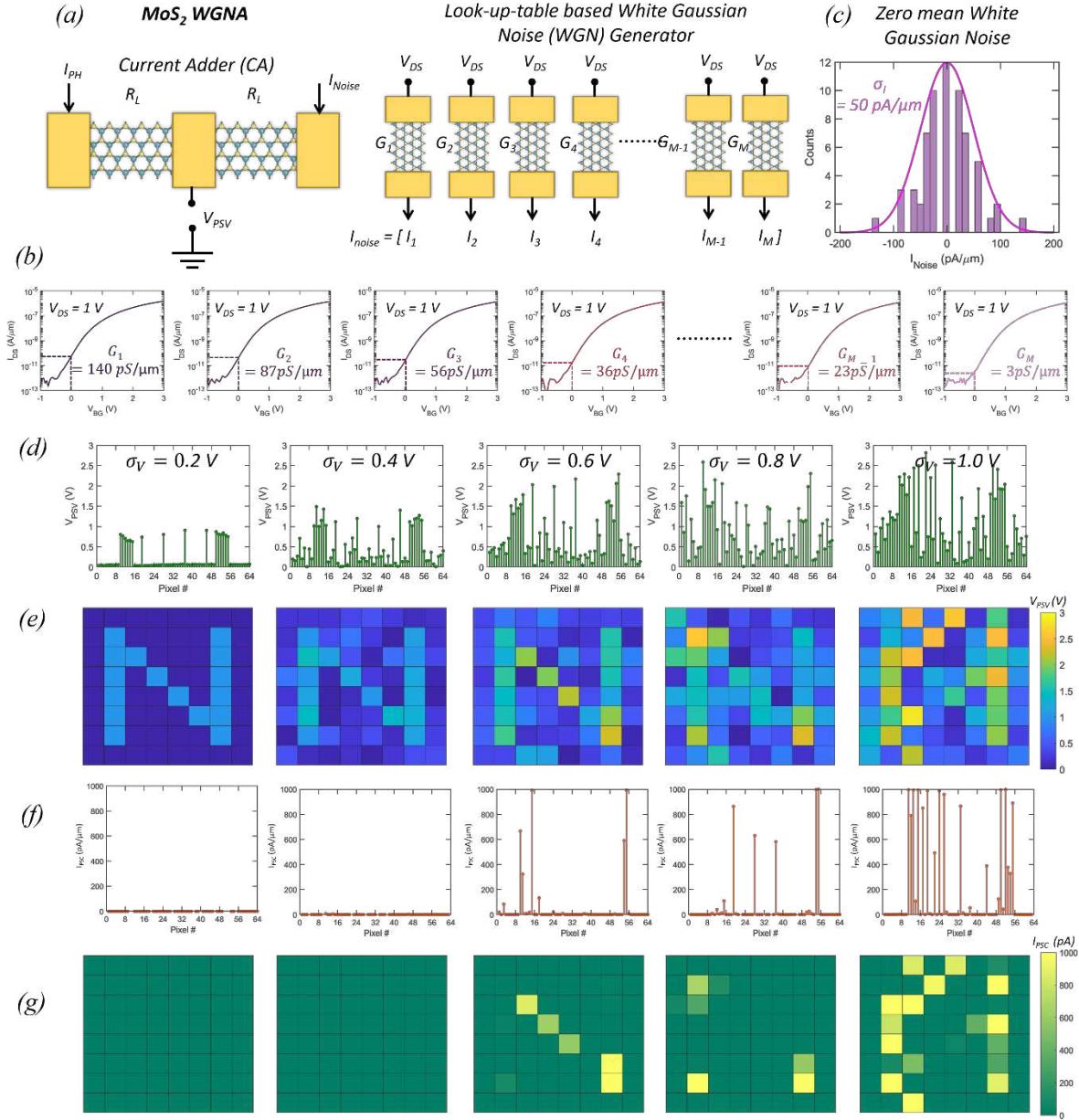


Figure 3. Programmable MoS₂ FET based biomimetic cryptography engine for IoT security. a) Circuit diagram for the MoS₂ FET based white Gaussian noise adder (WGNA) comprising of a current adder (CA) and a look-up-table based white Gaussian Noise (WGN) generator. The WGN generator is an array of $M = 64$ MoS₂ FETs with preprogrammed threshold voltages such that their conductance values (G_N) follow random Gaussian distribution. b) Transfer characteristics of array elements of a representative WGN generator and c) corresponding histogram of output current values ($I_M = G_M V_{DS}$) read at $V_{BG} = 0$ V with $V_{DS} = \pm 1$ V constituting the $I_{NOISE} = [I_1 I_2 I_3 \dots I_M]$. I_{NOISE} follows a zero mean Gaussian distribution with standard deviation of $\sigma_I = 50$ pA/μm. Note that different arrays can be preprogrammed to obtain I_{NOISE} with different σ_I . The CA adds WGN to the photocurrent and converts it into presynaptic voltage (V_{PSV}) to be applied to the MoS₂ based artificial neuron (AN). Since we use resistive network, the noise current transforms into noise voltage with standard deviation, $\sigma_V = R_L \sigma_I$. d) V_{PSV} and e) corresponding color map for the letter 'N' after the transduction process using MoS₂ WGNA for different σ_V . f) Corresponding post-synaptic current (I_{PSC}) and g) I_{PSC} map obtained from MoS₂ AN with a preprogrammed threshold voltage of $V_{TH} = 1.5$ V. Note that, for $V_{PSV} < V_{TH}$ the MoS₂ AN does not invoke any observable current response as in the case of low σ_V . For higher σ_V , there are more threshold crossing events resulting in more brighter pixels in the 8×8 encrypted image of the letter 'N'.

and post-synaptic current (I_{PSC}) measured at the drain terminal with a drain bias, $V_{DS} = 1$ V. The encoding threshold was programmed to be $V_{TH} = 1.5$ V, such that the presynaptic voltage pulses (V_{PSV}) obtained from the MoS₂ WGNA (Fig. 3d) are primarily subthreshold with occasional threshold crossing events due to the addition of the WGN. Note that, for $V_{PSV} < V_{TH}$ the MoS₂ AN does not invoke any observable current response greater than the noise floor of the measurement (~ 1 pA/ μ m). Fig. 3f and Fig. 3g, respectively, show the I_{PSC} and the corresponding map for different σ_V for the letter ‘N’. As evident, for lower σ_V , there are none to limited threshold crossing events resulting in sporadic bright pixels in the 8 \times 8 encrypted image of the letter ‘N’, whereas, for higher σ values, there are more frequent threshold crossing events resulting in greater number of bright pixels in the 8 \times 8 encrypted image of the letter ‘N’. Nevertheless, the I_{PSC} map constitute the encoded information for the letter ‘N’.

Next, to analyze the strength of the encryption process, we define true positive (TP) as an event when a bright pixel in the encoded image corresponds to a bright pixel in the original image, and false positive (FP) as an event when a bright pixel in the encoded image corresponds to a dark pixel in the original image. The likelihood of identifying the letter ‘N’ by an eavesdropper from the encrypted image will, therefore, be determined by the detectivity (D), which is defined as $D = p_{TP} - p_{FP}$, where, p_{TP} is the probability of TP, and p_{FP} is the probability of FP. Colormaps in Fig. 4a-c, respectively, show p_{TP} , p_{FP} , and D as a function of σ_V obtained by repeating the experiments with a population of $P = 50$ encoders and Fig. 4d shows the corresponding population means. Note that the population mean for D exhibits a non-monotonic behavior. At low noise level, there is hardly any FP, i.e. low p_{FP} , but the likelihood of detecting the letter ‘N’ remains low due to limited threshold crossing events for the original bright pixels, i.e. low p_{TP} . At high noise level, both bright

and dark pixels corresponding to the original image cross the spiking threshold resulting in high p_{TP} , and p_{FP} , and, therefore, low D . However, at an intermediate noise, the detectivity reaches its maximum value. Fig. 4e shows the number of brute force trials (BFTs) by the eavesdropper, necessary to identify the letter ‘N’ as a function of σ_V . Note that we computed $BFT = 1/D^S$, where $S = 8 \times 8 = 64$ is the size of the image. The number of BFTs are found to be astronomical irrespective of σ_V . Furthermore, the number of BFTs increases exponentially with S (see *Extended Data 7*). Therefore, the encryption can be considered to be secure from an eavesdropper with finite resources. Fig. 4f shows the average energy expenditure by a MoS₂ AN for the encryption of the letter ‘N’ as a function of σ_V . Note that the energy expenditure is less than 10 pJ/pixel even for the highest σ_V .

The encryption strength is also tested assuming that the eavesdropper has access to a trained artificial neural network (ANN) and the information being communicated are encrypted MNIST data set for digit classification. Fig. 4g shows a fully connected two-layered ANN with 100 neurons in the hidden layer and 10 neurons in the output layer. The 10 output neurons correspond to digits from 0 to 9. MNIST images (28×28 pixels) are flattened to obtain corresponding 784×1 vectors, which are fed to the input layer. Gradient decent algorithm is used to train the ANN using 60,000 images with a learning rate of 0.001 and rectified linear unit (ReLU) as the activation function to ensure high convergence accuracy of 90.6% beyond 300 epochs. Following this, a testing accuracy of 92.2% was achieved using the remaining 10,000 images. Note that higher training and testing accuracies can be achieved by optimizing the network, which is not the primary focus of this work. Next, we added white Gaussian noise to 10,000 MNIST images and binarized them at a threshold of 1.5 mimicking our MoS₂ based artificial neural encoder. Fig. 4h shows some example of

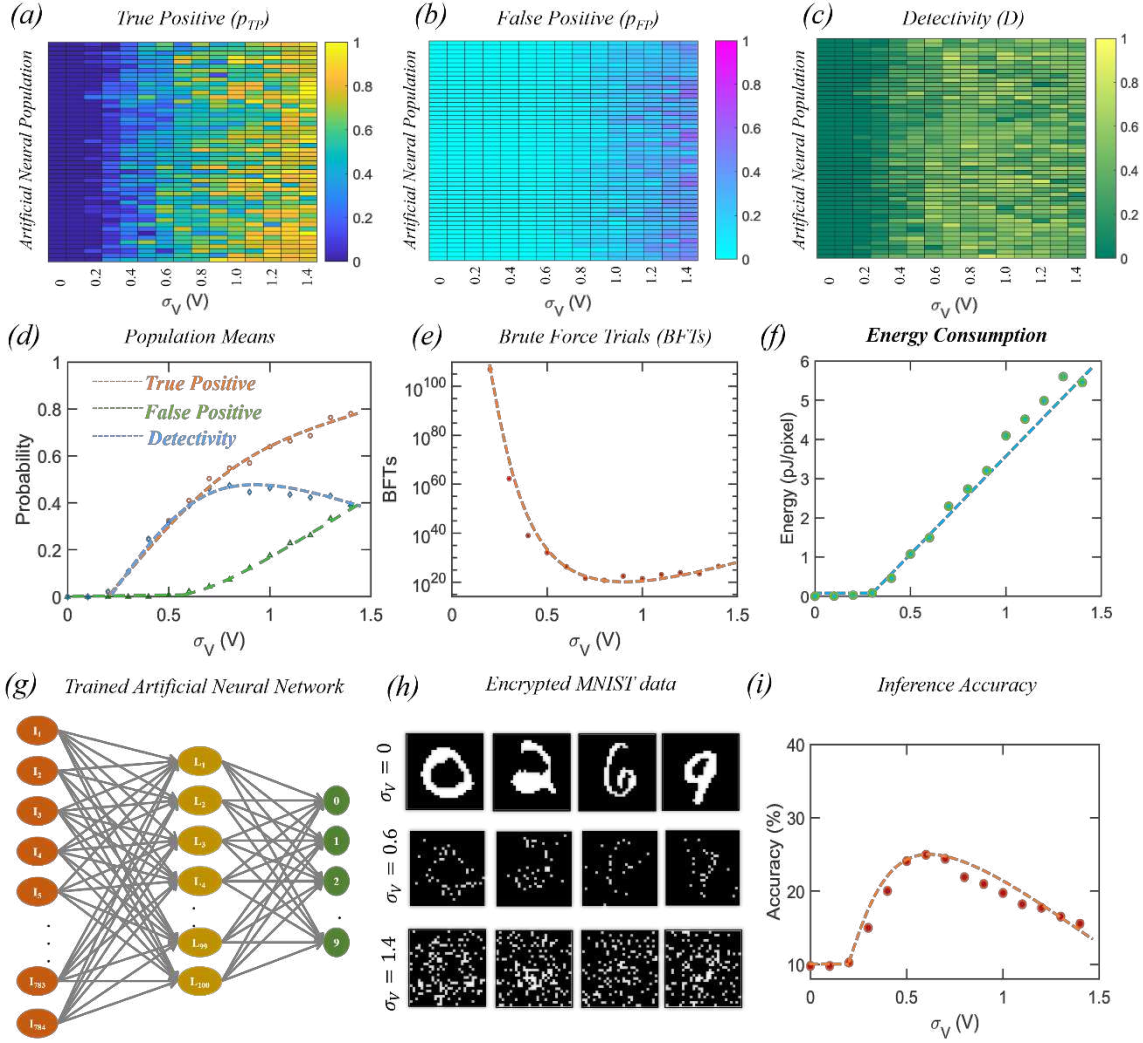


Figure 4. Strength of biomimetic encryption. Colormaps of likelihood or probability of (a) true positive (p_{TP}), (b) false positive (p_{FP}), and (c) detectivity ($D = p_{TP} - p_{FP}$) as a function of σ_V for $P = 50$ encoders. (d) Corresponding population means. True positive (TP) is an event when a bright pixel in the encoded image corresponds to a bright pixel in the original image, and false positive (FP) is an event when a bright pixel in the encoded image corresponds to a dark pixel in the original image. At low noise level, there is hardly any FP, i.e. low p_{FP} , but the likelihood of detecting the letter 'N' remains low due to limited threshold crossing events for the original bright pixels, i.e. low p_{TP} . At high noise level, both bright and dark pixels corresponding to the original image cross the encoder threshold resulting in high p_{TP} , and p_{FP} , and, therefore, low D . However, at an intermediate noise, the detectivity reaches its maximum value. Note that the population mean for D exhibits a non-monotonic trend. e) The number of brute force trials (BFTs) by the eavesdropper, necessary to identify the letter 'N' as a function of σ_V . Note that $BFT = 1/D^S$, where, $S = 8 \times 8 = 64$, is the size of the image. The number of BFTs are found to be astronomical irrespective of the amount of noise. f) The average energy expenditure for the encryption process as a function of σ_V . g) A fully connected artificial neural network (ANN) with 100 neurons in the hidden layer and 10 neurons in the output layer, trained using gradient decent algorithm with learning rate of 0.001 to recognize MNIST data set for digit classification. Rectified linear unit is used as the activation function. The training and testing sets consisted of 60,000 and 10,000 images, respectively. High convergence accuracy of 90.6% and inference accuracy of 92.2% is achieved. h) Representative MNIST images with white Gaussian noise (WGN) of different standard deviation (σ) binarized at a threshold of 1.5 mimicking our MoS₂ based artificial neural encoder. i) Average inference accuracy for 10,000 encrypted images as a function of σ . A non-monotonic trend is seen. However, irrespective of σ , the inference accuracy remains low indicating the robustness of our biomimetic encryption to trained ANNs.

encoded MNIST images for different standard deviation (σ) of the WGN. Fig.4i shows the inference accuracy for the encrypted images as a function of σ , which follows a non-monotonic behavior. Interestingly, the accuracy values are found to be significantly low irrespective of σ , indicating the robustness of our proposed encryption scheme to trained ANNs.

In order to retrieve the information, we adopt population voting-based algorithm. We assume that the encoded images of the letter ‘N’ are transmitted over different communication channels by P encoders. The receiver at the other end receives P encoded images and counts the number votes corresponding to each pixel. Fig. 5a shows the vote counts for each pixel when $P = 50$ for different σ_V . A vote is registered when the encoded pixel is bright, i.e. $I_{PSC} > 10$ pA. The vote is considered to be a true positive vote (TPV) if the corresponding pixel in the original image is also bright, whereas the vote is considered to be a false positive vote (FPV) if the corresponding pixel in the original image is dark. Fig. 5b and 5c, respectively, show the probability distribution for TPVs (p_{TPV}) and FPVs (p_{FPV}) for $P = 50$ for different σ_V . At low noise levels, the probability of crossing the encoding threshold (V_{TH}) is low and hence only a few encoders fire simultaneously resulting in lower expected number of encoders for TPV, i.e. $\langle N_{TPV} \rangle = \sum_{n=1}^P np_{TPV}(n)$. The expected number of encoders for FPV, i.e. , $\langle N_{FPV} \rangle = \sum_{n=1}^P np_{FPV}(n)$, is even lower. Similarly, at high noise level, the probability of crossing the threshold of the encoder is high and hence more encoders fire synchronously resulting in larger $\langle N_{TPV} \rangle$ and $\langle N_{FPV} \rangle$. However, as seen in Fig. 5b-c for any σ_V , $\langle N_{TPV} \rangle$ is higher than $\langle N_{FPV} \rangle$. **Extended Data 8** shows the decoding of the images of the letter ‘N’ for different σ_V for different number of mandated votes (M_V) to mark a pixel as bright for $P = 50$. Fig. 5d shows the corresponding colormap of correlation coefficient (CC) between the original and the decrypted image as a function of σ_V and M_V . Note that for a given σ_V , there is an

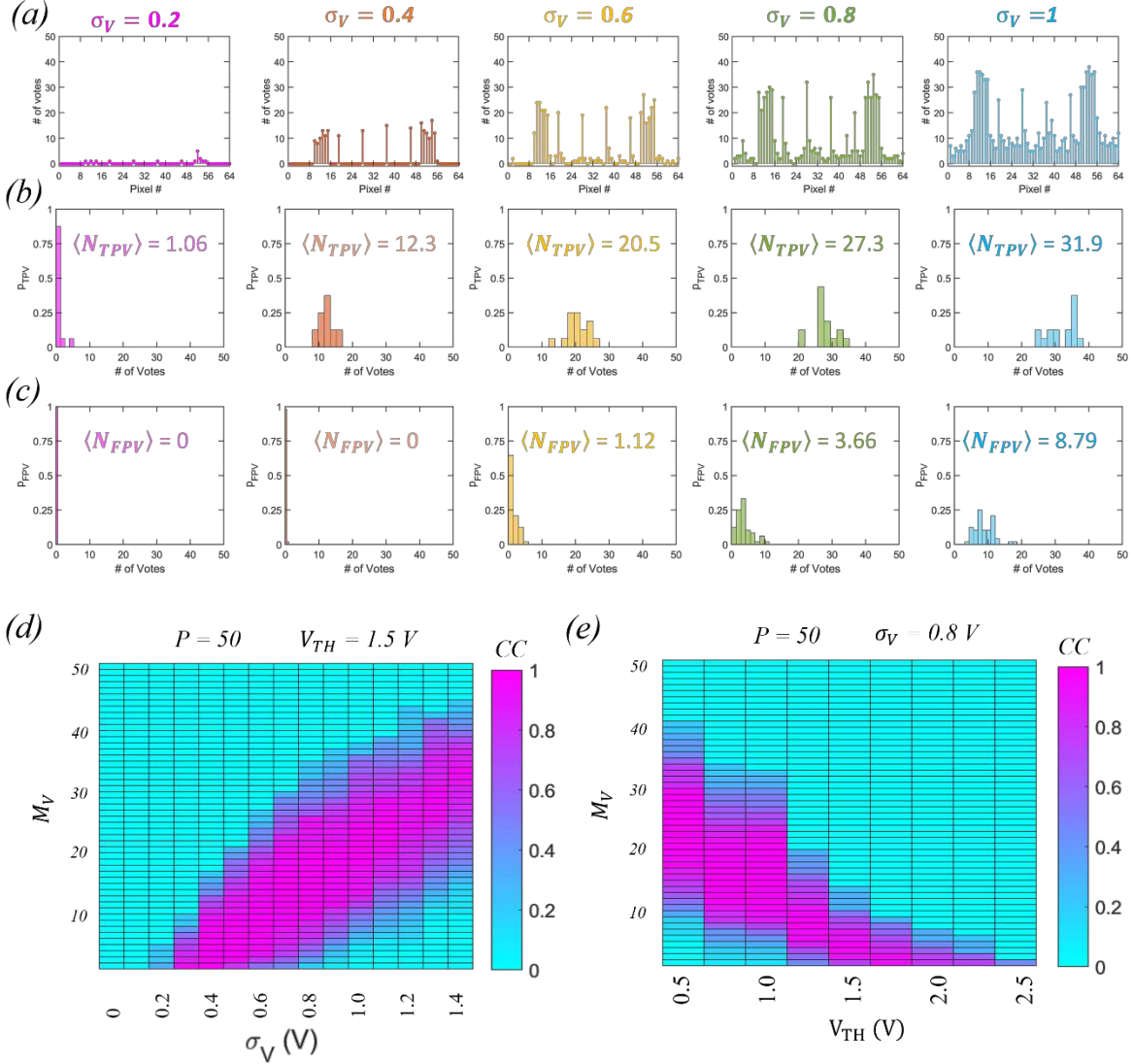


Figure 5. Voting-based decryption of encrypted information. a) Number of votes corresponding to each pixel of the encoded images of the letter ‘N’ received from $P = 50$ encoders for different σ_V . A vote is registered when the encoded pixel is bright, i.e. $I_{PSC} > 10$ pA. The vote is a true positive vote (TPV) if the corresponding pixel in the original image is also bright, whereas the vote is a false positive vote (FPV) if the corresponding pixel in the original image is dark. Probability distribution for b) TPVs (p_{TPV}) and c) FPVs (p_{FPV}) corresponding to (a). Insets show the expected number of TPV, i.e. $\langle N_{TPV} \rangle = \sum_{n=1}^P np_{TPV}(n)$, and FPV, i.e., $\langle N_{FPV} \rangle = \sum_{n=1}^P np_{FPV}(n)$. d) The colormap of correlation coefficient (CC) between the original and the decrypted images of the letter ‘N’ as a function of σ_V and M_V , when encryption is done by $P = 50$ encoder with encoding threshold of $V_{TH} = 1.5$ V. Here, M_V is the minimum number of votes required to mark a pixel as bright. Note that for a given σ_V , there is an optimum M_V , that allows accurate decryption of the encoded image, i.e. $CC = 1$. e) The colormap of CC between the original and the decrypted image of the letter ‘N’ as a function of V_{TH} and M_V for $\sigma_V = 0.8$ V and $P = 50$. Note that without prior knowledge of σ_V , P , and V_{TH} it is difficult to determine M_V and hence decode the information.

optimum M_V , that allows accurate decryption of the encoded image, i.e. $CC = 1$. **Extended Data 9** shows similar results for CC when different encoding population sizes (P) are used. As expected, the optimum number of M_V for accurate decryption is found to be different for similar σ_V . Therefore, without the prior knowledge of the σ_V and P , used by the biomimetic encoder it is difficult to decode the information. The strength of encoding can be further enhanced by exploiting the programming capability of our MoS₂ based ANs. Here we reconfigure the encoding threshold (V_{TH}) similar to neuroplasticity in biological neurons allowing adaptation to changing environment and stimuli. **Extended Data 10** shows the encryption of the letter ‘N’, by encoders with different V_{TH} , for different σ_V . As obvious if $V_{PSV} > V_{TH}$, the encryption process is pointless or in other word the communication is insecure. For V_{TH} values slightly greater than V_{PSV} , there are more threshold crossing events even for low σ_V , whereas, for V_{TH} values further from V_{PSV} , there are limited threshold crossing events even for high σ_V . Fig. 5e shows the colormap of CC between the original and the decrypted image of the letter ‘N’ as a function of V_{TH} and M_V for $\sigma_V = 0.8$ V and $P = 50$ (see **Extended Data 11** for similar results with different σ_V). Clearly, the optimum M_V for accurate decryption is found to be different for different V_{TH} . Therefore, not only σ_V and P , but also prior knowledge of V_{TH} is required for decoding the information, which makes the system more robust from the eavesdropper.

Conclusion

In conclusion, we have experimentally demonstrated an *all-in-one* hardware IoT platform based on programmable and multifunctional MoS₂ FETs, which is capable of sensing, storing, and securing information. Since a single material and similar device structures are used the hardware footprint is minimal, $\sim 5 \mu\text{m} \times 2 \mu\text{m}$ for each photodetector, $\sim 5 \mu\text{m} \times 3 \mu\text{m}$ for each CA, $5 \mu\text{m} \times$

64 μm for each WGN generator, and $\sim 5 \mu\text{m} \times 2 \mu\text{m}$ for each AN. The energy expenditure is also miniscule, in the range of few tens to hundreds of pico Joules, as we have primarily exploited subthreshold FET operation. Furthermore, analog, and non-volatile memory capability allows reconfiguration of the IoT platform based on application needs. Finally, the biomimetic IoT platform is shown to be secure.

Methods

Film Growth: Monolayer MoS₂ was deposited on epi-ready 2” c-sapphire substrate by metalorganic chemical vapor deposition (MOCVD). An inductively heated graphite susceptor equipped with wafer rotation in a cold-wall horizontal reactor was used to achieve uniform monolayer deposition as previously described [22]. Molybdenum hexacarbonyl (Mo(CO)₆) and hydrogen sulfide (H₂S) were used as precursors. Mo(CO)₆ maintained at 10°C and 950 Torr in a stainless-steel bubbler was used to deliver 0.036 sccm of the metal precursor for the growth, while 400 sccm of H₂S was used for the process. MoS₂ deposition was carried out at 1000°C and 50 Torr in H₂ ambient, where monolayer growth was achieved in 18 min. The substrate was first heated to 1000°C in H₂ and maintained for 10 min before the growth was initiated. After growth, the substrate was cooled in H₂S to 300°C to inhibit decomposition of the MoS₂ films.

Film Transfer: After the growth of monolayer MoS₂ on sapphire substrate, the film is then transferred onto the FET gate dielectric substrate by wet transfer technique. Polymethylmethacrylate (A3 PMMA) resist is spin coated onto the growth substrates encapsulating the MoS₂ and then immersed into the 1M NaOH solution kept at 90°C. Capillary action draws the NaOH solution to the PMMA/substrate interface, separating the hydrophobic PMMA/MoS₂ from the sapphire substrate. The detached film floats on the surface, which is then rinsed for multiple times in deionized water and is finally transferred on to the Alumina/ Pt/TiN/p⁺⁺ Si gate dielectric stack[23].

Fabrication of monolayer MoS₂ FET: We have fabricated the back-gated field effect transistors on a 50nm alumina (Al₂O₃) acting as a gate oxide and a stack of Pt/TiN/p⁺⁺ Si as a back-gate

electrode. First, MOCVD grown MoS₂ are transferred onto the alumina sample, then the sample is spin coated with A6 PMMA and followed by electron-beam (e-beam) lithography to specify the channels and then separating them out by sulfur hexafluoride (SF₆) etch under 5 degree centigrade for 30s. After etch step, sample is rinsed in Acetone for 30 min followed by 2-propanol (IPA). To define the source and drain contacts, sample is then spin coated with methyl methacrylate (MMA) followed by A3 PMMA. Then using electron-beam lithography source and drain contacts are patterned and further developed by using 1:1 mixture of 4-methyl -2-pentanone (MIBK) and 2 propanol for 60s. 40nm of Nickel (Ni) and 30 nm of Gold (Au) are deposited/ evaporated on to the patterns using E-beam evaporation. Lift- off the evaporated materials is done by immersing the sample in Acetone for 30 min followed by 2-propanol (IPA).

Electrical Characterization: Electrical characterization of the fabricated devices are performed using Lake Shore CRX-VF probe station under atmospheric condition using a Keysight B1500A parameter analyzer.

Data Availability: The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request.

Code Availability: The codes used for plotting the data are available from the corresponding authors on reasonable request.

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Author Contributions

S.D conceived the idea and designed the experiments. S.D, and A.D performed the experiments, analyzed the data, discussed the results, agreed on their implications. All authors contributed to the preparation of the manuscript.

Competing Interest

The authors declare no competing interests

Acknowledgement

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Figure Captions

Figure 1. Hardware realization of all-in-one IoT platform based on programmable and

multifunctional MoS₂ field effect transistor (FET) arrays. a) Schematic representation of our proposed *all-in-one* IoT platform that involves sensing, storage, and security. The IoT sensor collects the information, which is encrypted using an array of encoders. Each encoder comprises of a white Gaussian noise adder (WGNA) and an artificial neuron (AN). b) Associated hardware based on programmable and multifunctional MoS₂ FET arrays, which are used as photodetector (PD) for sensing, and WGNA and AN for encryption. c) An example experimental demonstration of sensing and ciphering. Information, for example, an 8×8 pixelated image of the letter ‘N’ obtained by illuminating a blue light emitting diode (LED) is presented to the IoT sensor, i.e. MoS₂ PD. The photocurrent (I_{PH}) in response is superimposed with zero mean white Gaussian noise (WGN) of desirable standard deviation and transduced to subthreshold presynaptic voltage (I_{PSV}) using MoS₂ WGNAs and presented to MoS₂ ANs with pre-programmed threshold voltages. The information is revealed by a decoder through a voting process if the encoding knowledge is accessible.

Figure 2. MoS₂ FET for compute, storage, and sensing.

a) Schematic of MoS₂ FET with programmable back-gate stack comprised of atomic layer deposition (ALD) grown 50 nm Al₂O₃ on Pt/TiN/p⁺⁺-Si. b) Optical image of arrays of MoS₂ FETs used for our *all-in-one* IoT platform. c) Transfer characteristics, i.e. source to drain current (I_{DS}) *versus* back-gate voltage (V_{BG}) at different drain biases (V_{DS}) for a representative MoS₂ FET with 1 μm channel length (L), 5 μm channel width (W), and a stack of 40 nm Ni/30 nm Au as the source and drain contacts. d) Output characteristics of the MoS₂ FET, i.e. I_{DS} *versus* V_{DS} for different V_{BG} . e) Shift in transfer

characteristics of MoS₂ FET when “Write” programming pulses of different amplitudes, V_p , are applied to the back-gate electrode, each for a total duration of $t_p = 1$ s, f) Extracted iso-current (~ 10 pA) threshold voltages, V_{TH} , corresponding to each state in (e) measured multiple times, post-programming to demonstrate non-volatile retention. e) Shift in transfer characteristics of MoS₂ FET when “Write” programming pulses of same amplitude, $V_p = 10$ V, but different t_p , are applied to the back-gate electrode. g) Corresponding non-volatile shift in V_{TH} . The device can be programmed to any desired conductance state indicative of analog memory operation. i) Transfer characteristics of MoS₂ FET in dark and under the illumination of a blue LED, placed at ~ 1 cm distance. The device shows reasonable photoresponse and hence can be used as a photodetector (PD). j) Photoresponse (I_{PH}) of the device, measured at $V_{BG} = 1.5$ V to different input stimulus, i.e. 8×8 pixelated images of the letters, ‘L’, ‘M’, ‘N’, and ‘P’, obtained through the LED illumination. Each pixel corresponds to 1 ms LED illumination. k) Corresponding photocurrent maps demonstrate that the MoS₂ PD can accurately translate optical information into electrical response. Note that the MoS₂ PD was biased in the subthreshold regime to enable exponential reduction in the dark current (~ 1 pA) and thereby making $I_{PH} = I_{DS}$ under illumination. This also allows ultra-low-power photodetection with energy expenditure in the range $E_{PD} \sim 25\text{-}30$ pJ/pixel, averaged over all pixels.

Figure 3. Programmable MoS₂ FET based biomimetic cryptography engine for IoT security.

a) Circuit diagram for the MoS₂ FET based white Gaussian noise adder (WGNA) comprising of a current adder (CA) and a look-up-table based white Gaussian Noise (WGN) generator. The WGN generator is an array of $M = 64$ MoS₂ FETs with preprogrammed threshold voltages such that their conductance values (G_N) follow random Gaussian distribution. b) Transfer characteristics of array

elements of a representative WGN generator and c) corresponding histogram of output current values ($I_M = G_M V_{DS}$) read at $V_{BG} = 0$ V with $V_{DS} = \pm 1$ V constituting the $I_{NOISE} = [I_1 I_2 I_3 \dots I_M]$. I_{NOISE} follows a zero mean Gaussian distribution with standard deviation of $\sigma_I = 50$ pA/ μm . Note that different arrays can be preprogrammed to obtain I_{NOISE} with different σ_I . The CA adds WGN to the photocurrent and converts it into presynaptic voltage (V_{PSV}) to be applied to the MoS₂ based artificial neuron (AN). Since we use resistive network, the noise current transforms into noise voltage with standard deviation, $\sigma_V = R_L \sigma_I$. d) V_{PSV} and e) corresponding color map for the letter ‘N’ after the transduction process using MoS₂ WGNA for different σ_V . f) Corresponding post-synaptic current (I_{PSC}) and g) I_{PSC} map obtained from MoS₂ AN with a preprogrammed threshold voltage of $V_{TH} = 1.5$ V. Note that, for $V_{PSV} < V_{TH}$ the MoS₂ AN does not invoke any observable current response as in the case of low σ_V . For higher σ_V , there are more threshold crossing events resulting in more brighter pixels in the 8×8 encrypted image of the letter ‘N’.

Figure 4. Strength of biomimetic encryption. Colormaps of likelihood or probability of (a) true positive (p_{TP}), (b) false positive (p_{FP}), and (c) detectivity ($D = p_{TP} - p_{FP}$) as a function of σ_V for $P = 50$ encoders. (d) Corresponding population means. True positive (TP) is an event when a bright pixel in the encoded image corresponds to a bright pixel in the original image, and false positive (FP) is an event when a bright pixel in the encoded image corresponds to a dark pixel in the original image. At low noise level, there is hardly any FP, i.e. low p_{FP} , but the likelihood of detecting the letter ‘N’ remains low due to limited threshold crossing events for the original bright pixels, i.e. low p_{TP} . At high noise level, both bright and dark pixels corresponding to the original image cross the encoder threshold resulting in high p_{TP} , and p_{FP} , and, therefore, low D . However, at an intermediate noise, the detectivity reaches its maximum value. Note that the population mean

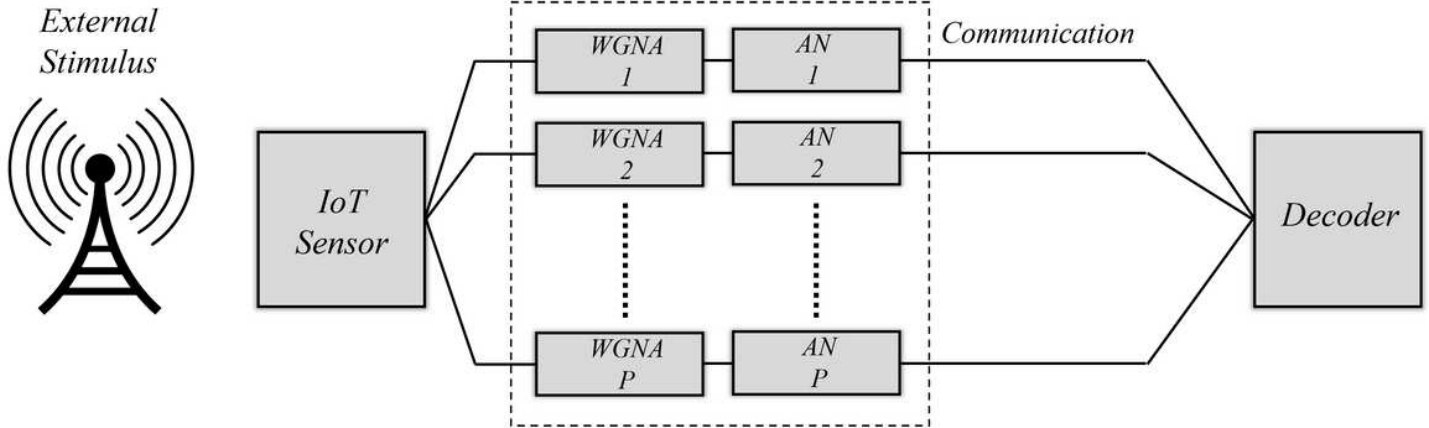
for D exhibits a non-monotonic trend. e) The number of brute force trials (BFTs) by the eavesdropper, necessary to identify the letter ‘N’ as a function of σ_V . Note that $BFT = 1/D^S$, where, $S = 8 \times 8 = 64$, is the size of the image. The number of BFTs are found to be astronomical irrespective of the amount of noise. f) The average energy expenditure for the encryption process as a function of σ_V . g) A fully connected artificial neural network (ANN) with 100 neurons in the hidden layer and 10 neurons in the output layer, trained using gradient decent algorithm with learning rate of 0.001 to recognize MNIST data set for digit classification. Rectified linear unit is used as the activation function. The training and testing sets consisted of 60,000 and 10,000 images, respectively. High convergence accuracy of 90.6% and inference accuracy of 92.2% is achieved. h) Representative MNIST images with white Gaussian noise (WGN) of different standard deviation (σ) binarized at a threshold of 1.5 mimicking our MoS₂ based artificial neural encoder. i) Average inference accuracy for 10,000 encrypted images as a function of σ . A non-monotonic trend is seen. However, irrespective of σ , the inference accuracy remains low indicating the robustness of our biomimetic encryption to trained ANNs.

Figure 5. Voting-based decryption of encrypted information. a) Number of votes corresponding to each pixel of the encoded images of the letter ‘N’ received from $P = 50$ encoders for different σ_V . A vote is registered when the encoded pixel is bright, i.e. $I_{PSC} > 10$ pA. The vote is a true positive vote (TPV) if the corresponding pixel in the original image is also bright, whereas the vote is a false positive vote (FPV) if the corresponding pixel in the original image is dark. Probability distribution for b) TPVs (p_{TPV}) and c) FPVs (p_{FPV}) corresponding to (a). Insets show the expected number of TPV, i.e. $\langle N_{TPV} \rangle = \sum_{n=1}^P np_{TPV}(n)$, and FPV, i.e., $\langle N_{FPV} \rangle = \sum_{n=1}^P np_{FPV}(n)$. d) The colormap of correlation coefficient (CC) between the original and the

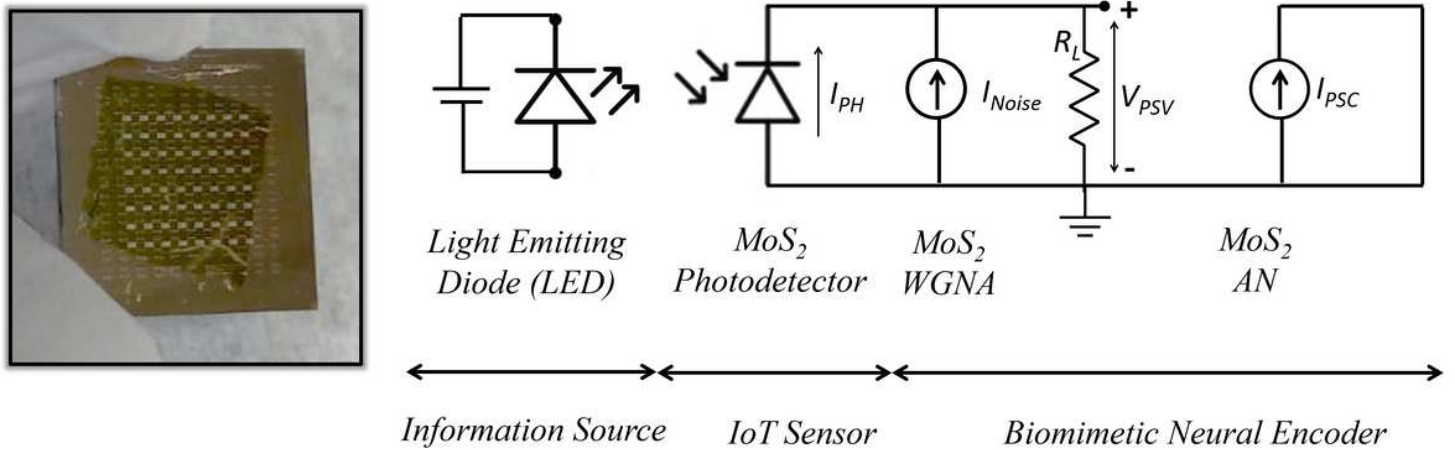
decrypted images of the letter 'N' as a function of σ_V and M_V , when encryption is done by $P = 50$ encoder with encoding threshold of $V_{TH} = 1.5$ V. Here, M_V is the minimum number of votes required to mark a pixel as bright. Note that for a given σ_V , there is an optimum M_V , that allows accurate decryption of the encoded image, i.e. $CC = 1$. e) The colormap of CC between the original and the decrypted image of the letter 'N' as a function of V_{TH} and M_V for $\sigma_V = 0.8$ V and $P = 50$. Note that without prior knowledge of σ_V , P , and V_{TH} it is difficult to determine M_V and hence decode the information.

Figures

(a) All-In One IoT Platform



(b) Hardware Realization



(c) Example Experimental Demonstration

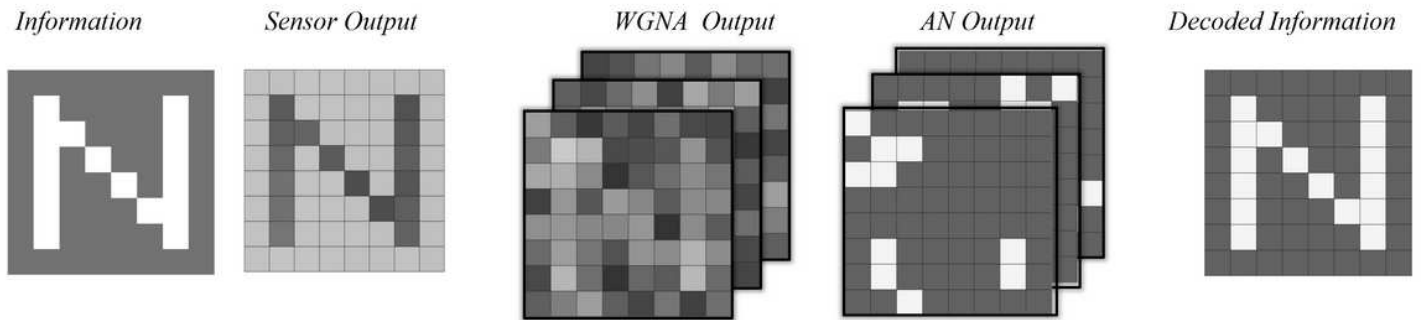


Figure 1

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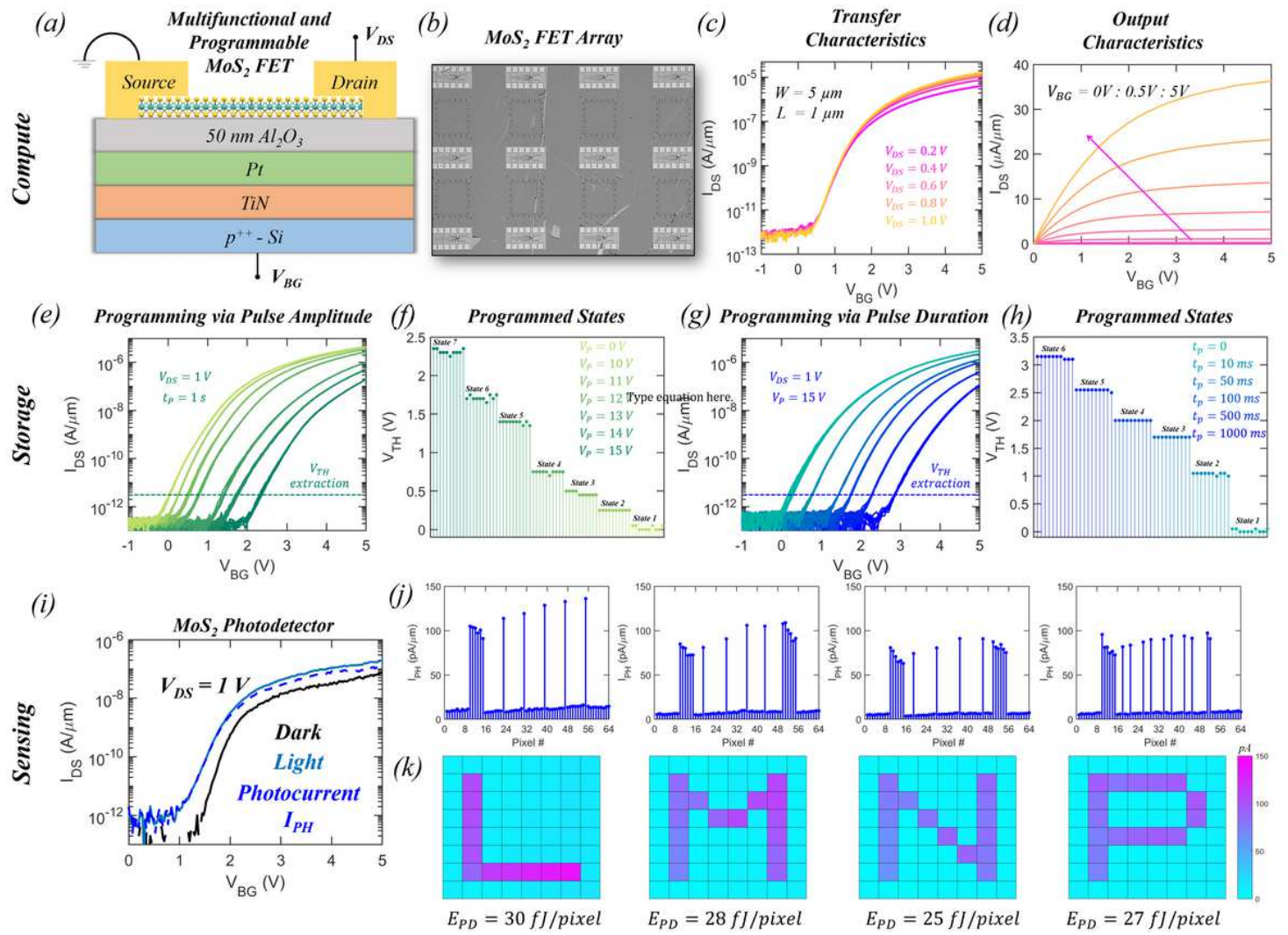


Figure 2

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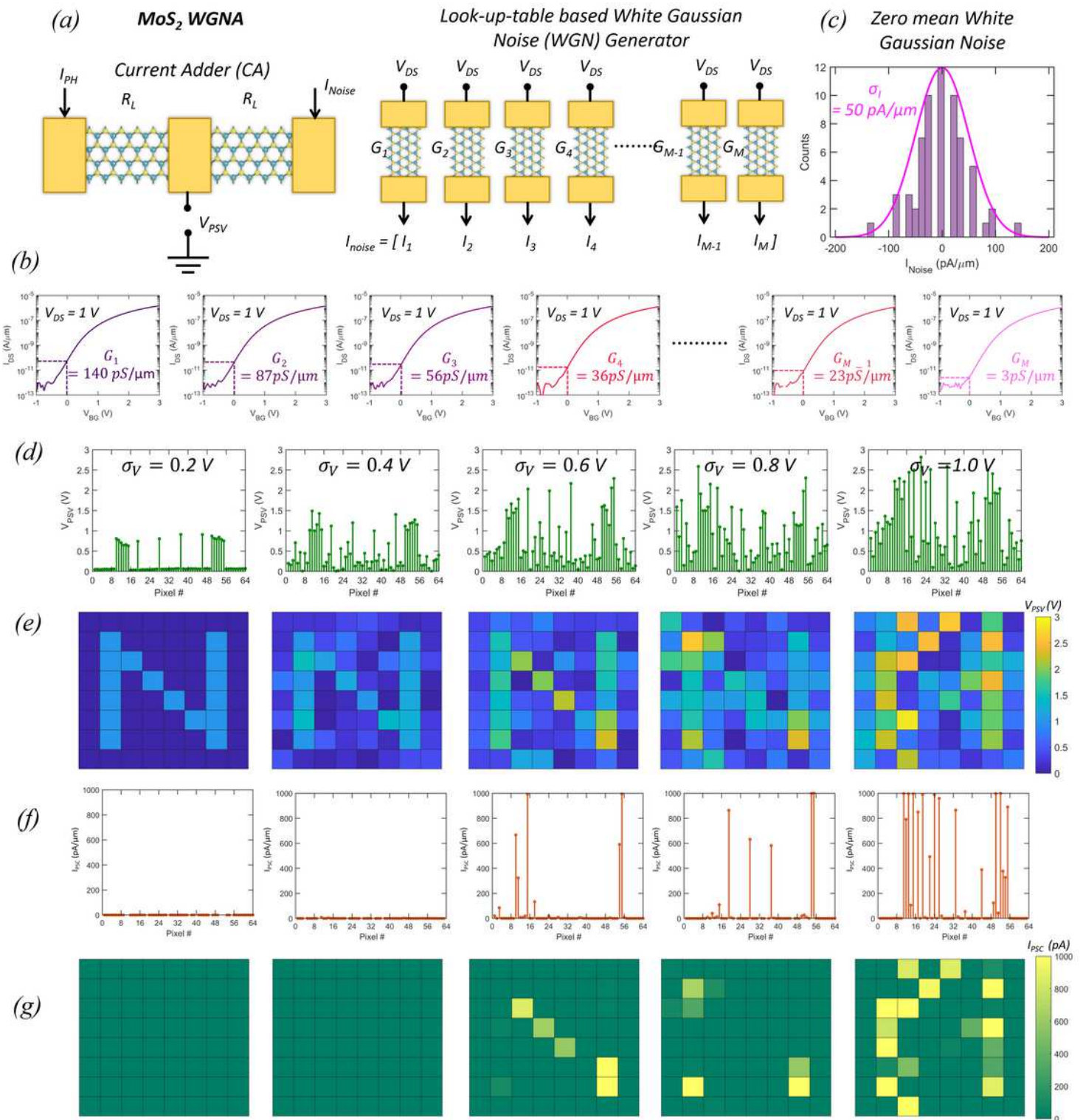


Figure 3

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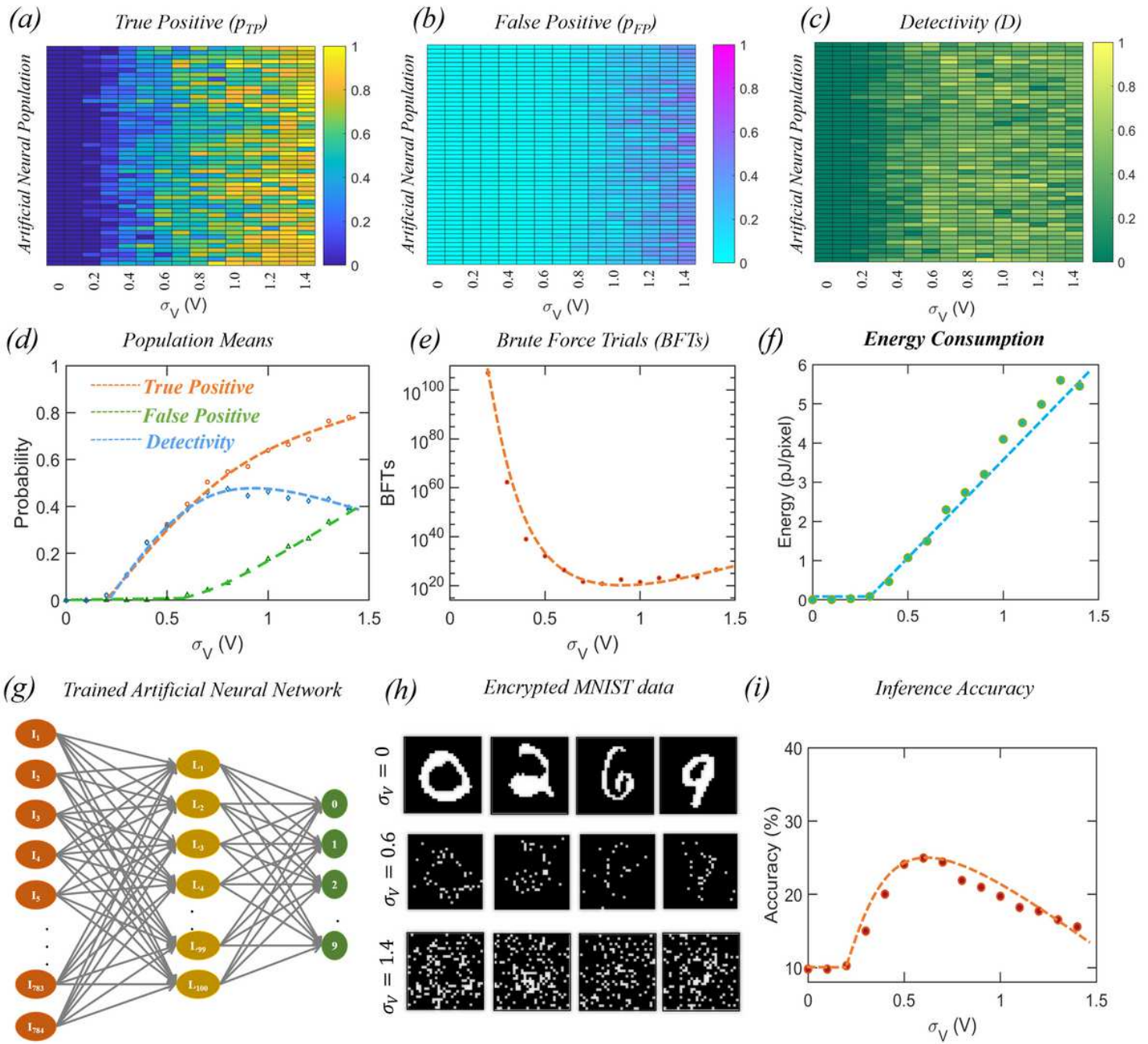


Figure 4

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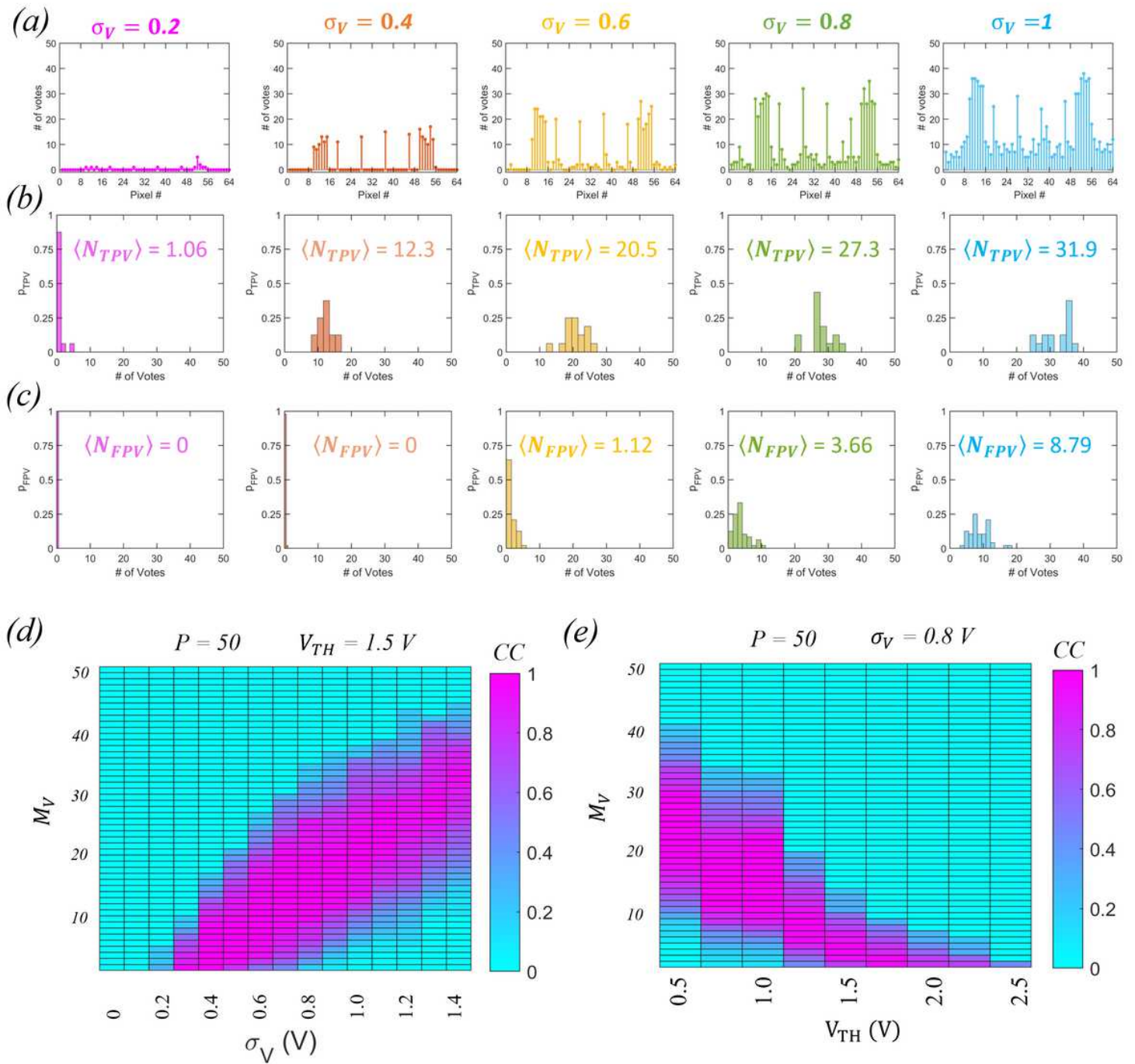


Figure 5

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